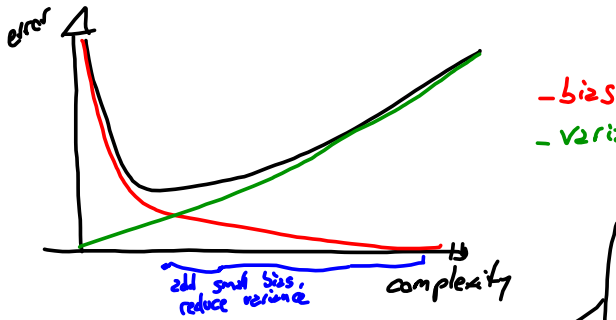


# Methods of regularization



ordinary  
 • least squares estimator  
 BLUE (Best Linear Unbiased Estimator)  
 minimize the variance

- model selection: reduce the variance by removing those variables that are not contributing much to the bias-reduction
- same idea for PCR

accepting a small increase in the bias in order to reduce the variance to get the smallest possible prediction error

Penalized (regularized) regression → we add to our usual loss (deviance) a term (penalty) which force the estimator to be a little bit biased, but obtain smaller variance

Notes: - we now assume to have centred response  $y_i - \bar{y}$ , because we do not want to penalize the intercept  
 - for reasons which will be clear soon, we will work with standardized  $x$

$$x_i^* = \frac{x_i - \bar{x}}{s(x)}$$

## Ridge regression

Consider a linear model  $y = X\beta + \epsilon$

Ridge regression finds the regression coefficient estimates by minimizing

$$J_{\text{ridge}}(\beta, \lambda) = \sum_{i=1}^n (y_i - x_i^T \beta)^2 + \lambda \sum_{j=1}^p \beta_j^2 = \|y - X\beta\|_2^2 + \lambda \beta^T \beta$$

↑ tuning parameter (penalty parameter)      ↪ L<sub>2</sub> penalty

The minimizer of this loss function is

$$\hat{\beta}_{\text{ridge}}(\lambda) = (X^T X + \lambda I)^{-1} X^T y$$

$\lambda > 0$

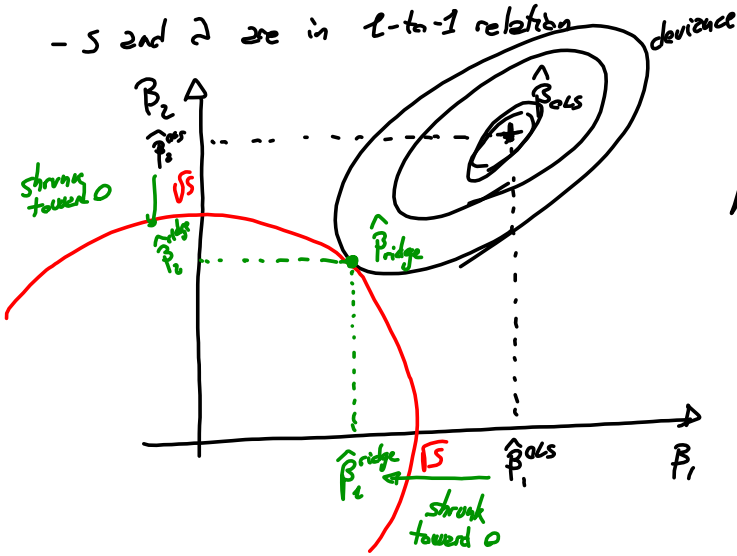
Note that  $\lambda$  is a very important parameter that controls the amount of penalization

- $\lambda = 0$  → no penalty, so  $\hat{\beta}_{\text{ridge}} = \hat{\beta}_{\text{OLS}}$
- $\lambda = +\infty$  → each small deviation of  $\hat{\beta}$  from 0 are strongly penalized, so  $y - \bar{y} = 0$   
 $\hat{\beta}_{\text{ridge}} = 0 \quad \forall_j$
- normally, it is computed by cross-validation
- even for small  $\lambda$ , we reduce problems of collinearity
- allow regression of the case  $p > n$

Alternative formulation.

Minimize  $\sum_{i=1}^n (y_i - x_i^T \beta)^2$  subject to  $\sum_{j=1}^p \beta_j^2 \leq s$

-  $s$  and  $\lambda$  are in 1-to-1 relation



simple case, two variables  $\rightarrow$  two regression coefficients

Note: due to correlation, it is not necessarily true that  $\lambda_u > \lambda_s \nRightarrow |\hat{\beta}_j(\lambda_u)| < |\hat{\beta}_j(\lambda_s)|$   
 $s_u < s_s$

Bias

$E[\hat{\beta}_{OLS}] = \beta$  ordinary least squares estimator is unbiased **BLUE**

$E[\hat{\beta}_{Ridge}] = E[(X^T X + \lambda I)^{-1} X^T y]$

$= E[(X^T X + \lambda I)^{-1} (X^T X) (X^T X)^{-1} X^T y]$

$= E[(I_p + \lambda (X^T X)^{-1})^{-1} (X^T X)^{-1} X^T y]$

$= W(\lambda) E[\hat{\beta}_{OLS}] = W(\lambda) \beta$  the ridge estimator is unbiased only if  $W(\lambda) = I$ , i.e.,  $\lambda = 0$

$Var(\hat{\beta}_{Ridge}) = Var(W(\lambda) \hat{\beta}_{OLS})$

$= W(\lambda) Var(\hat{\beta}_{OLS}) W(\lambda)^T$

$= \sigma^2 W(\lambda) (X^T X)^{-1} W(\lambda)^T$

$Var(\hat{\beta}_{OLS}) = \sigma^2 (X^T X)^{-1}$

$Var(\hat{\beta}_{OLS}) - Var(\hat{\beta}_{Ridge}) = \sigma^2 [(X^T X)^{-1} - W(\lambda) (X^T X)^{-1} W(\lambda)^T]$

$= \sigma^2 W(\lambda) [W(\lambda)^T (X^T X) W(\lambda)^{-1} - (X^T X)^{-1}] W(\lambda)^T$

$= \sigma^2 W(\lambda) [(I_p + \lambda (X^T X)^{-1}) (X^T X) (I_p + \lambda (X^T X)^{-1}) - (X^T X)] W(\lambda)^T$

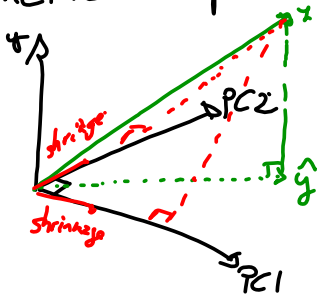
$= \sigma^2 W(\lambda) [(X^T X)^{-1} + \lambda (X^T X)^{-2} + \lambda (X^T X)^{-1} + \lambda^2 (X^T X)^{-3} - (X^T X)^{-1}] W(\lambda)^T$

$= \sigma^2 W(\lambda) [2\lambda (X^T X)^{-2} + \lambda^2 (X^T X)^{-3}] W(\lambda)^T > 0$

all are quadratic form

$Var(\hat{\beta}_{Ridge}^{(\lambda)}) \leq Var(\hat{\beta}_{OLS})$

Geometric interpretation related to PCA



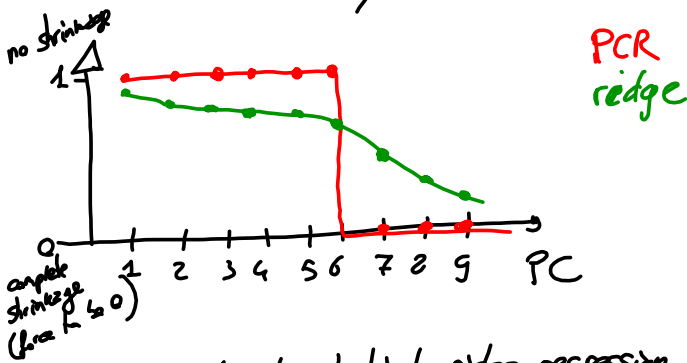
$$\hat{\beta}_1^{ols} = \frac{\|y\|}{\|pc1\|}$$

$$\hat{\beta}_1^{ridge} = \frac{\|y\|}{\|pc1\| + \lambda} \hat{\beta}_1^{ols}$$

$$\hat{\beta}_2^{ols} = \frac{\|y\|}{\|pc2\|}$$

$$\hat{\beta}_2^{ridge} = \frac{\|y\|}{\|pc2\| + \lambda} \hat{\beta}_2^{ols}$$

- ridge regression projects the response on the principal components
- shrink the low-variance components more than the high-variance components  
 likely to be noise likely to be signal



The general idea behind ridge regression, is that we minimize a loss function of the form

$$\sum_{i=1}^n (y_i - x_i^T \beta)^2 + \lambda P(\beta)$$

→ specifically for ridge regression,  $P(\beta) = \beta^T \beta = \sum_{j=1}^p \beta_j^2$

$P(\beta)$  can but must not be the  $L_2$  norm → we can use the  $L_1$  norm  
 from the sum of squares to the sum of absolute values →  $\sum_{j=1}^p |\beta_j|$

Minimize  $\sum_{i=1}^n (y_i - x_i^T \beta)^2 + \lambda \sum_{j=1}^p |\beta_j|$

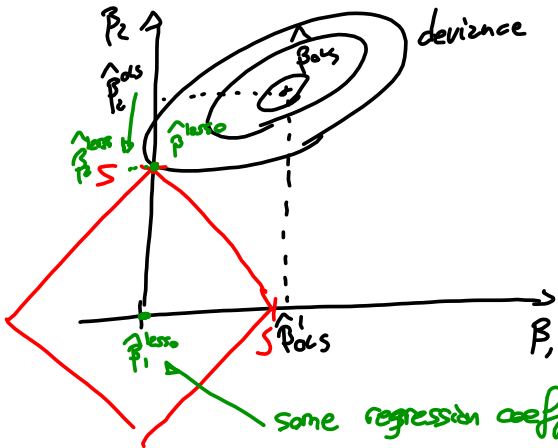
LASSO (Least Angle Shrinkage and Selection Operator)

The most interesting feature of LASSO is that it forces some estimates to be exactly equal to 0 → intrinsic variable selection → for a suitable  $\lambda$

The same considerations done for  $\lambda$  of ridge regression are valid for LASSO

Using the alternative form for LASSO as well

$$\hat{\beta}_{LASSO} = \underset{\beta}{\operatorname{argmin}} \sum_{i=1}^n (y_i - x_i^T \beta)^2 \quad \text{subject to} \quad \sum_{j=1}^p |\beta_j| \leq s$$



some regression coefficients estimates are forced to be 0

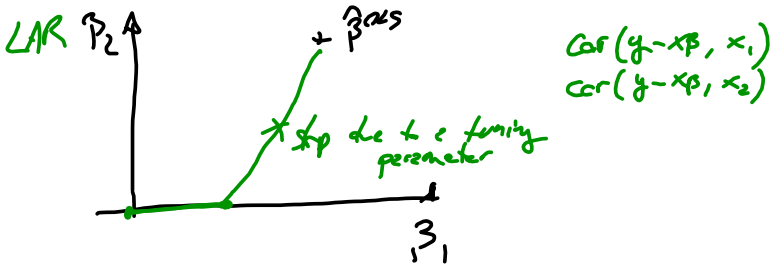
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Advantages

- shrinkage
- automatic variable selection

Disadvantages

- no close form for  $\hat{\beta}_{LASSO}$  due to the non-differentiability of the  $L_1$  loss
  - we need to rely on numerical computations
- ↳ in practice, very good algorithms based on LAR, of which lasso is a special case



$$\sum_{i=1}^n (y_i - \beta_0 + \sum_{j=1}^p x_{ij} \beta_j)^2 + \sum_{j=1}^p |\beta_j|$$



# Prediction of quantitative variables

Back to the initial problem, predict  $y$  using  $x$

$$y = f(x)$$

→ until now: parametric approach

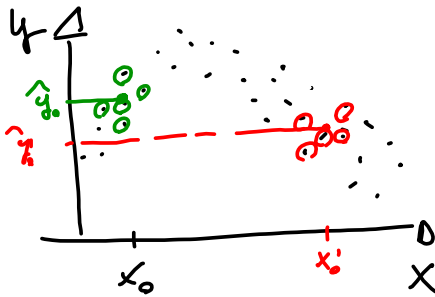
$$y = f(x; \beta)$$

family of functions, indexed by  $\beta$

$$\hat{y} = f(x; \beta) \Big|_{\beta = \hat{\beta}}$$

- in the class of parametric functions, find the best by selecting the best  $\hat{\beta}$
- simple, easy to compute

Alternative: do not restrict to a parametric form, base our estimation on the data only (plus some regularity conditions) → NON-PARAMETRIC APPROACH



$$\hat{y}_0 = f(x_0)$$

$$k=S = \frac{1}{S} \sum_{x_i \in N_k(x_0)} y_i$$

$$\hat{y}_0 = \frac{1}{K} \sum_{x_i \in N_k(x_0)} y_i$$

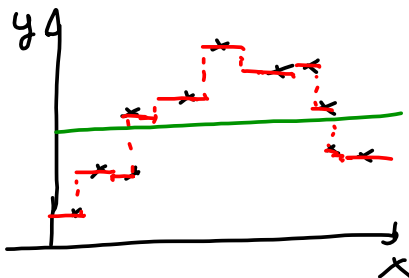
where  $N_k(x_0)$  denotes the set of the  $k$  closest points to  $x_0$

We assume that the values of the closest points are similar to the one of interest, and we base our estimates on those response → simple mean

Basically, we are assuming that  $f(x)$  is constant close to  $x_0$   $f(x) = \beta_0$

$k$  is the tuning parameter, that tells how many neighbours to include in the estimate

- smaller value, more complex model, until the extreme  $k=d$ , in which each  $x_0$  is estimated through its closest neighbour
- larger values, simpler model, until the extreme  $k=n$ , in which  $x_0$  is estimated with all the observations:  $f(x) = \bar{y}$



$k=1$

$k=n$

- complexity is inverse of  $k$
- how to choose  $k$
- CROSS-VALIDATION