

First improvement: weight depending on the distance

- our assumption is that the response we want to predict is similar to the responses  $y_i$  of the points close to  $x_0$ .
- in  $K-NN$  we average on the  $k$  closest points
- we expect closer points to be more similar to further points
- ⇒ we can give different weights based on the distance to  $x_i$ .

$$w_i = \frac{1}{h} K\left(\frac{x_i - x_0}{h}\right) \rightarrow \text{kernel}$$

$h$  is a tuning parameter (bandwidth or smoothing parameter)

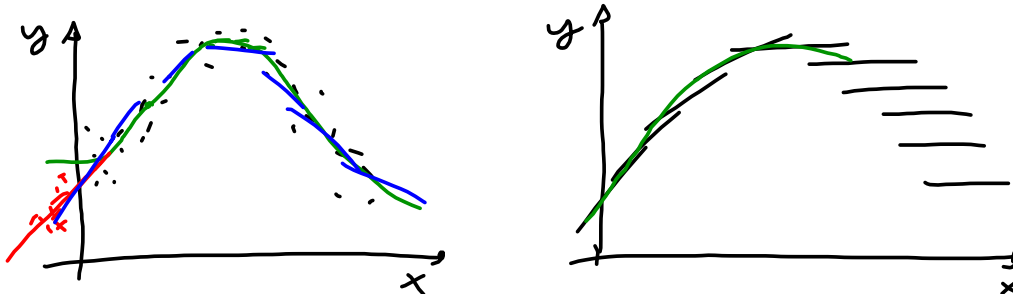
$$\hat{y}_0 = \sum_{i \in N_h(x_0)} w_i y_i$$

Typical kernels are:

normal	$\frac{1}{\sqrt{2\pi}} \exp\left\{-\frac{1}{2} \left(\frac{x_i - x_0}{h}\right)^2\right\}$	defined in $\mathbb{R}$
Epanechnikov	$\frac{3}{4} \left[1 - \left(\frac{x_i - x_0}{h}\right)^2\right]$	$\cdot \cdot (-1; 1)$
biquadratic	$\frac{15}{16} \left(1 - \left(\frac{x_i - x_0}{h}\right)^2\right)^2$	$\cdot \cdot (-1; 1)$
tricubic	$\frac{7}{81} \left(1 - \left \frac{x_i - x_0}{h}\right ^3\right)^3$	$\cdot \cdot (-1; 1)$
rectangular	$\frac{1}{2}$	$\cdot \cdot (-1; 1)$

used (empirical evidence showed that it is not really important which kernel is implemented) → much more important the choice of  $h$

Second improvement: from constant to linear approximation



Instead of approximating the function at each point with a constant, we use a line

$$y = f(x) + \epsilon \quad \hat{y} = \hat{\beta}_0$$

↓ Taylor expansion around  $x_0$

$$f(x) = \underbrace{f(x_0)}_{\beta_0} + \underbrace{f'(x_0)}_{\beta_1} (x - x_0) + \cancel{o((x-x_0)^2)}$$

To estimate  $\beta_0$  and  $\beta_1$ , we can extend the concept of least squares estimator

$$\hat{\beta}_0, \hat{\beta}_1 = \underset{\beta_0, \beta_1}{\operatorname{argmin}} \sum_{i=1}^n (y_i - \beta_0 - \beta_1 (x_i - x_0))^2 w_i$$

where  $w_i$  are weights that penalizes the contribution of observations far from  $x_0$

The solution is

$$(\hat{\beta}_0, \hat{\beta}_1) = \hat{\beta} = (X^T W X)^{-1} X^T W y$$

↑  
Weighted least squares

where  $X = \begin{pmatrix} 1 & x_1 - x_0 \\ \vdots & \vdots \\ 1 & x_n - x_0 \end{pmatrix}_{n \times 2}$

$$W = \begin{pmatrix} \frac{1}{h} k\left(\frac{x_1 - x_0}{h}\right) & 0 \\ \vdots & \vdots \\ 0 & \frac{1}{h} k\left(\frac{x_n - x_0}{h}\right) \end{pmatrix}_{n \times n}$$

## Choice of the bandwidth

- $h$  is the tuning parameter, and control the model complexity
- smaller  $h$  means a smaller window (in the picture, the light blue area), so we estimate  $f(x)$  based on the local behaviour of the data
    - less bias, more variance → when  $h$  is too small, we have a bumpy curve that follow the randomness in the data → OVERFITTING
  - larger  $h$  means larger window, more data are used to estimate  $f(x)$ 
    - lower variance, higher bias → when  $h$  is too large, our curve does not capture the systematic part of the data → UNDERFITTING

The optimal choice of  $h$  is related to the bias-variance trade-off.

In practice  $h$  is chosen by cross-validation or  $AIC_c$

## Theoretical aspects

Under specific conditions ( $\text{Var}(\epsilon_i) = \sigma^2 \forall i$ ,  $\text{Cov}(\epsilon_i, \epsilon_j) = 0 \forall i \neq j$  and regularity condition)

$$E[\hat{f}(x)] \approx f(x) + \underbrace{\frac{h^2}{2} \sigma_w^2 f''(x)}_{\text{bias} = b(x)} \quad \begin{array}{l} h \text{ sufficiently small} \\ n \text{ " large} \end{array}$$

$$\text{Var}[\hat{f}(x)] \approx \frac{\sigma^2}{nh} \frac{\alpha(w)}{g(x)} \quad \text{bias} = b(x)$$

with  $\sigma_w^2 = \int z^2 w(z) dz$ ,  $\alpha(w) = \int w(z)^2 dz$ ,  $g(x)$  is the density from which  $x$ : have been sampled

$$h \rightarrow 0 \quad \underbrace{E[\hat{f}(x)] - f(x)}_{\text{bias}} \rightarrow 0 \quad \text{Var}(\hat{f}(x)) \rightarrow \infty$$

$$h \rightarrow \infty \quad \text{Var}(\hat{f}(x)) \rightarrow 0 \quad E[\hat{f}(x)] - f(x) \rightarrow \infty$$

Having expected value and variance, we can, in theory, use the asymptotic distribution

$$\frac{\hat{f}(x) - f(x) - b(x)}{\sqrt{\text{Var}(\hat{f}(x))}} \sim N(0, 1)$$

to construct confidence bands around  $\hat{f}(x)$

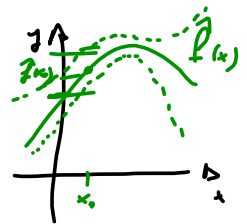
↳ same concept of confidence intervals, provide an <sup>indication</sup> ~~measure~~ of the uncertainty around our estimate

Problem: the bias contains a term,  $f''(x)$ , that is unknown and we cannot estimate, not even approximately

Solution: use variability bands on the form

$$\hat{f}(x) - z_{1-\frac{\alpha}{2}} \sqrt{\widehat{\text{Var}}(\hat{f}(x))}, \quad \hat{f}(x) + z_{1-\frac{\alpha}{2}} \sqrt{\widehat{\text{Var}}(\hat{f}(x))}$$

where  $z_{1-\frac{\alpha}{2}}$  is the  $1-\frac{\alpha}{2}$  quantile of the standard normal distribution

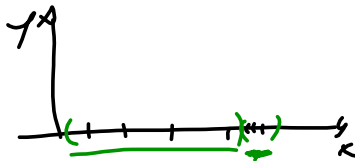


Note:

- the variability bands are computed pointwise
- for each points, they are not confidence intervals
- the confidence level for a fixed x is anyway  $1-\alpha$ , but it does not work for the entire curve

### loess

- combine the local linear regression we saw today with the idea of a fixed amount of points used for the local estimation (like KNN)
  - instead of computing the smoothing window based on the distance from  $x_0$ , the window is constructed in order to include a specific amount (or proportion) of data
  - smoothing parameter  $m$
  - idea behind: it more reasonable to use larger smoothing windows where the data are more sparse



Extension to several dimensions

In theory, our non-parametric estimation of  $f(x)$  can be extended to more dimensions

E.g.  $p=2$   $y = f(x_1, x_2) + \epsilon$   $\mathbb{R}^2 \rightarrow \mathbb{R}$

Let  $y_i \in \mathbb{R}$ ,  $x_i = (x_{i1}, x_{i2}) \in \mathbb{R}^2$   $i=1, \dots, n$

$$\min_{\beta_0, \beta_1, \beta_2} \sum_{i=1}^n (y_i - \beta_0 - \beta_1(x_{i1} - x_{01}) - \beta_2(x_{i2} - x_{02}))^2 w_i \quad (1)$$

where now  $w_i$  has form

$$w_i = \frac{1}{h_1 h_2} K\left(\frac{x_{i1} - x_{01}}{h_1}\right) K\left(\frac{x_{i2} - x_{02}}{h_2}\right)$$

Now we have 2 tuning (smoothing) parameters, one for each dimension (we need to take into account the different variability of  $x_1$  and  $x_2$ )

Again, the solution of the minimization problem (1) is based on weighted least squares

$$\hat{\beta} = (X^T W X)^{-1} X^T W y$$

where:  $y = (y_1, \dots, y_n)^T$

$$W = \text{diag}(w_1, \dots, w_n)$$

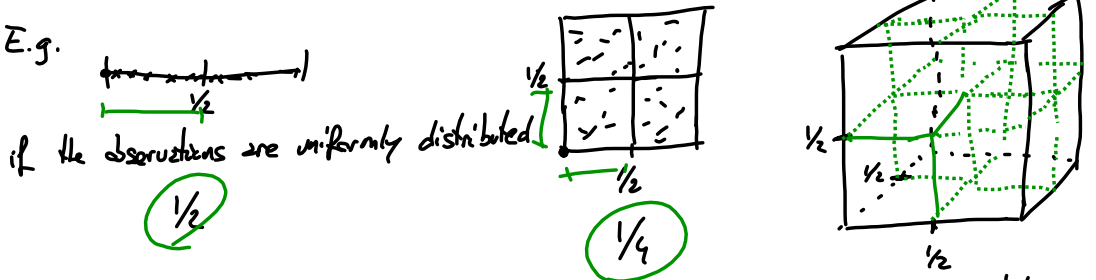
$$X = \begin{pmatrix} 1 & x_{11} - x_{01} & x_{12} - x_{02} \\ \vdots & \vdots & \vdots \\ 1 & x_{n1} - x_{01} & x_{n2} - x_{02} \end{pmatrix}$$

In theory it works for any  $p$  (not only  $p=2$  like here above).

In practice, these techniques are never used for  $p > 2$

- difficulties to plot/visualize the results
- hard to interpret the results
- suffer from the curse of dimensionality: increasing the number of dimensions, the number of observed points close to the point of interest decreases really quickly

E.g.



In order to compensate for the increased dimension of the space, in order to base our estimate on the same amount of data, we need  $n^{1/p}$  observations (e.g., if in 1 dimension, we want  $\hat{f}(x)$  based on 100 observations,  $n=2$   $100^2$ , with 5 variables  $100^5$  (10 billions)

Basically, when the problem is multidimensional (with a large number of dimensions) we cannot use our non-parametric techniques

- issues with the number of observation;
- computational issues

Possible way to proceed: construct principal components, use let us say the first two.   
 ↳ maintain as much variability as possible in as few dimensions as possible

# SPLINES



- piecewise constant
- " linear
- continuous piecewise linear
- discontinuous cubic
- continuous cubic
- cubic continuous in first derivative
- " " " " " " " " " "

piecewise polynomial function  
 - split the support in several pieces  
 (fix  $\xi_1, \xi_2, \dots, \xi_k$ )  
 - fit a polynomial in each piece



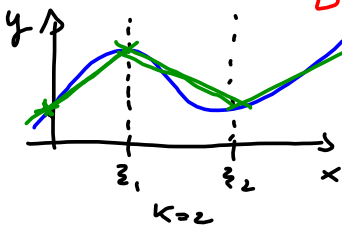
can be any, the preferred is 3  
 $f(\xi_i^-) = f(\xi_i^+)$   
 $f'(\xi_i^-) = f'(\xi_i^+)$   
 $f''(\xi_i^-) = f''(\xi_i^+)$

cubic splines

How can we use splines to evaluate the relationship between  $y$  and  $x$  (regression splines)?

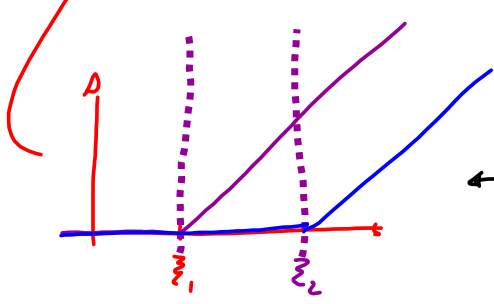
Simplest case,  $k=2$ ,  $d=1$  (2 knots, straight lines)  
 → parametric case  $f(x; \beta)$

$$f(x; \beta) = \beta_0 + \beta_1 x + \beta_2 (x - \xi_1)_+ + \beta_3 (x - \xi_2)_+ \quad \text{basis}$$



$$h_1 = 1 \quad h_3 = (x - \xi_1)_+ \\ h_2 = x \quad h_4 = (x - \xi_2)_+$$

$$\hat{f}(x; \beta) = \sum_{j=1}^k \hat{\beta}_j h_j(x)$$



← form of  $(x - \xi_i)_+$

In the case of cubic splines with a generic number of knots  $K$ ,

$$f(x; \beta) = \sum_{j=1}^{k+4} \beta_j h_j(x)$$

where

$$h_j(x) = x^{j-1} \quad \text{for } j=1, \dots, 4$$

$$h_{j+4}(x) = (x - \xi_i)_+^3 \quad \text{for } j=1, \dots, k$$

$$\begin{cases} h_1(x) = x^0 = 1 \\ h_2(x) = x^1 = x \\ h_3(x) = x^2 \\ h_4(x) = x^3 \end{cases}$$

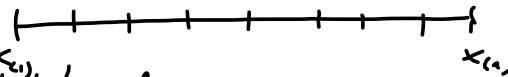
We need to decide  $K$ , the number of knots, and their positions

$K$  is the complexity parameter: higher values, more complex functions

→ find by cross-validation

Once  $K$  has been selected, we need to place  $\xi_1, \dots, \xi_K$  in the support of  $X$

• uniformly among the range of  $X$



• use the quantiles of the empirical distribution of  $X$

