

UNIVERSITY OF OSLO

Faculty of Mathematics and Natural Sciences

Examination in: STK4060 — Time series

Day of examination: Monday June 6th 2016

Examination hours: 14.30–18.30

This problem set consists of 2 pages.

Appendices: Note on state space model and Kalman filter

Permitted aids: Approved calculator

Please make sure that your copy of the problem set is complete before you attempt to answer anything.

Problem 1

Let x_t be a stationary time series with $E[x_t] = 0$ and $\text{var}(x_t) < \infty$.

- Explain what an ARMA(p,q) time series is and what it means that is causal and invertible.
- Is the time series x_t satisfying

$$x_t = -0.1x_{t-1} + 0.12x_{t-2} + w_t$$

causal?

- Explain what the partial autocorrelation coefficient is and how it is used to determine the order of an autoregressive time series.

Problem 2

The bivariate AR(1) process

$$\begin{pmatrix} \psi_t \\ \psi_t^* \end{pmatrix} = 0.5 \begin{pmatrix} \cos \lambda & \sin \lambda \\ -\sin \lambda & \cos \lambda \end{pmatrix} \begin{pmatrix} \psi_{t-1} \\ \psi_{t-1}^* \end{pmatrix} + \begin{pmatrix} \kappa_t \\ \kappa_t^* \end{pmatrix}$$

where κ_t and κ_t^* are independent $N(0, \sigma_\kappa^2)$ and $N(0, \sigma_{\kappa^*}^2)$ respectively can be used for describing cyclical patterns. Consider first λ as known. Then two ways to formulate the model as a part of a larger model is as

- the *trend and cycle* model where

$$\begin{aligned} y_t &= \mu_t + \psi_t + \epsilon_t \\ \mu_t &= \mu_{t-1} + \beta_{t-1} + \eta_t \\ \beta_t &= \beta_{t-1} + \zeta_t \end{aligned}$$

(Continued on page 2.)

and as

(ii) the *cyclical trend* model where

$$\begin{aligned} y_t &= \mu_t + \epsilon_t \\ \mu_t &= \mu_{t-1} + \beta_{t-1} + \psi_{t-1} + \eta_t \\ \beta_t &= \beta_{t-1} + \zeta_t \end{aligned}$$

where ϵ_t , η_t and ζ_t are independent and mutual independent $N(0, \sigma_\epsilon^2)$, $N(0, \sigma_\eta^2)$ and $N(0, \sigma_\zeta^2)$ variables, which also are independent of the κ_t 's and κ_t^* 's.

- Formulate both models as state-space models.
- Assume that the initial state has expectation zero and covariance matrix equal to the identity matrix so $\mathbf{x}_0^0 = 0$ and $P_0^0 = I$. Describe what the Kalman gain at time 1, K_1 , is for the *trend and cycle* model.
- If now the parameter λ is not assumed to be known, how would you estimate it based on observations y_1, \dots, y_n ?

Problem 3

Consider observations z_1, \dots, z_n from a time series with covariance function $\gamma(h)$ satisfying $\sum_{-\infty}^{\infty} |\gamma(h)| < \infty$ so that the spectral density $f_z(\omega)$ exists. Recall that the discrete Fourier transform is given as $d_z(j/n) = \frac{1}{\sqrt{n}} \sum_{t=1}^n z_t e^{-2\pi i(j/n)t}$, $j = 0, \dots, n-1$.

- Define the periodogram and state its main properties. Explain how the periodogram can be used for estimating the spectral density.
- Let the time series y_t be defined as

$$y_t = \mu + x_t, \quad t = 1, \dots, n$$

where x_t is a stationary time series with discrete Fourier transform d_x . The expectation $E[x_t] = 0$ and μ is a known constant. Express the discrete Fourier transform of y_t in terms of the discrete Fourier transform of x_t , i.e. d_x , and μ .

- Let y_t be as in part b) and let

$$y'_t = \begin{cases} y_t, & t = 1, \dots, n \\ 0, & t = n+1, \dots, n' \end{cases}$$

i.e. y_t padded. Find the discrete Fourier transform of y'_t . Compare the result to what you found in part b).

- Discuss whether it is preferable to subtract μ from the series y_t or from the padded version y'_t when the focus of interest is the periodic behavior of y_t .

END