

UNIVERSITY OF OSLO

Faculty of Mathematics and Natural Sciences

Examination in: STK4150 — Environmental and spatial statistics

Day of examination: Friday, June 4, 2010.

Examination hours: 09.00–12.00.

This problem set consists of 3 pages.

Appendices: None.

Permitted aids: Accepted calculator.

Please make sure that your copy of the problem set is complete before you attempt to answer anything.

FASIT

Problem 1 Gaussian processes

- (a) Second order stationarity means that $E[Z(\mathbf{x})]$ is constant, μ say, for all \mathbf{x} while $\text{Cov}[Z(\mathbf{x}), Z(\mathbf{x} + \mathbf{v})]$ only depend on \mathbf{v} , given through $C(\mathbf{v})$. Strictly stationarity means that $(Z(\mathbf{x}_1), \dots, Z(\mathbf{x}_n))$ has the same distribution as $(Z(\mathbf{x}_1 + \mathbf{v}), \dots, Z(\mathbf{x}_n + \mathbf{v}))$ for all $n, \mathbf{x}_1, \dots, \mathbf{x}_n, \mathbf{v}$. This is equivalent to second order stationarity in the Gaussian case.
- (b) Define Σ_z to be the covariance matrix for $\mathbf{Z} = (Z(\mathbf{x}_1), \dots, Z(\mathbf{x}_n))$. Then the covariance matrix for the observations is $\Sigma_y = \Sigma_z + \sigma^2 \mathbf{I}$. Further, by defining

$$\mathbf{c} = (C(|\mathbf{x}_1 - \mathbf{x}_0|), \dots, C(|\mathbf{x}_n - \mathbf{x}_0|))^T,$$

we have

$$\begin{pmatrix} \mathbf{Y} \\ Z(\mathbf{x}_0) \end{pmatrix} \sim \text{MVN} \left(\mu \mathbf{1}_{n+1}, \begin{pmatrix} \Sigma_y & \mathbf{c} \\ \mathbf{c}^T & C(0) \end{pmatrix} \right)$$

which leads to

$$\begin{aligned} E[Z(\mathbf{x}_0)|\mathbf{Y}] &= \mu + \mathbf{c}^T [\Sigma_z + \sigma^2 \mathbf{I}]^{-1} (\mathbf{Y} - \mu \mathbf{1}_n) \\ \text{Var}[Z(\mathbf{x}_0)|\mathbf{Y}] &= C(0) - \mathbf{c}^T [\Sigma_z + \sigma^2 \mathbf{I}]^{-1} \mathbf{c} \end{aligned}$$

Since the expectation is the centrepoint in the distribution for $Z(\mathbf{x}_0)$ given all we know, it is a reasonable predictor.

The conditional variance can be used as an uncertainty measure.

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(c) We have that Y_i is a binomial variable where

$$\Pr(Y_i = 1) = \Pr(Z(\mathbf{x}_i) > 0) = 1 - \Phi((0 - \mu)/\sqrt{C(0)}) = \Phi(\mu/\sqrt{C(0)})$$

Further

$$\begin{aligned} \text{Cov}[\tilde{Y}_i, \tilde{Y}_j] &= E[\tilde{Y}_i \tilde{Y}_j] - \Phi(\mu/\sqrt{C(0)})^2 \\ &= E[\tilde{Y}_i \tilde{Y}_j] - \Phi(\mu/\sqrt{C(0)})^2 \\ &= \int_{z_i > 0} \int_{z_j > 0} f(z_i, z_j) dz_i dz_j - \Phi(\mu/\sqrt{C(0)})^2 \end{aligned}$$

where $f(z_i, z_j)$ is the bivariate Gaussian distribution for $Z(\mathbf{x}_i), Z(\mathbf{x}_j)$

Problem 2 Extreme values

(a) We have $\Pr(M_n \leq x) \rightarrow 0$ for $x < x_{\max}$ while $\Pr(M_n \leq x_{\max}) = 1$, i.e. a degenerate distribution.

Define $a_n = x_{\max}$ and $b_n = n^{-1}$. We have

$$\begin{aligned} \Pr(Z_n \leq x) &= \Pr(x_{\max} - M_n \leq x/n) \\ &= \Pr(M_n \geq x_{\max} - x/n) \\ &= 1 - \Pr(M_n < x_{\max} - x/n) \\ &= 1 - F[x_{\max} - x/n]^n \\ &= 1 - \exp\{n \log F[x_{\max} - x/n]\} \\ &= 1 - \exp\left\{\frac{\log F[x_{\max} - x/n]}{n^{-1}}\right\} \end{aligned}$$

This gives

$$\begin{aligned} \lim_{n \rightarrow \infty} \Pr(Z_n \leq x) &= 1 - \lim_{n \rightarrow \infty} \exp\left\{\frac{\log F[x_{\max} - x/n]}{n^{-1}}\right\} \\ &= 1 - \lim_{n \rightarrow \infty} \exp\left\{\frac{f(x_{\max} - x/n) x n^{-2}}{F[x_{\max} - x/n]^{-n^{-2}}}\right\} \\ &= 1 - \lim_{n \rightarrow \infty} \exp\left\{-\frac{f(x_{\max} - x/n) x}{F[x_{\max} - x/n]}\right\} \\ &= 1 - \exp\{-x f(x_{\max})\} \end{aligned}$$

(b) We have

$$\Pr(M_n \geq x) = \Pr(Z_n \leq n(x_{\max} - x)) \approx 1 - \exp\{-n(x_{\max} - x)f(x_{\max})\}$$

This gives

$$1 - \exp\{-n(x_{\max} - x)f(x_{\max})\} \approx N^{-1}$$

which implies

$$x \approx x_{\max} - \log(N/(N-1))/[n f(x_{\max})]$$

This gives the value for which the maximum will exceed every N th year.

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Problem 3 Markov random fields

(a) The Markov property is that

$$\Pr(X_k | X_j, j \neq i) = \Pr(X_k | X_j, j \in N_k)$$

where N_k denotes the set of neighbors of k .

We have that

$$\begin{aligned} \Pr(x_k | x_j, j \neq i) & \\ & \propto \exp\left\{-\beta \sum_{i < j; |i-j|=1} x_i x_j\right\} \\ & \propto \exp\left\{-\beta \sum_{|k-j|=1} x_k x_j\right\} \end{aligned}$$

showing the Markov property with $N_k = \{j; |k-j|=1\}$.

(b) We have

$$\begin{aligned} \Pr(\mathbf{X} = \mathbf{x} | \mathbf{Y} = \mathbf{y}) & \propto \Pr(\mathbf{X} = \mathbf{x}) p(\mathbf{y} | \mathbf{X} = \mathbf{x}) \\ & \propto \exp\left\{-\beta \sum_{i < j; |i-j|=1} x_i x_j\right\} \prod_{i=1}^n f\left(y_i - ax_i - \frac{b}{M_i} \sum_{j; |j-i|=1} x_j\right) \\ & \propto \exp\left\{-\beta \sum_{i < j; |i-j|=1} x_i x_j + \sum_{i=1}^n \log f\left(y_i - ax_i - \frac{b}{M_i} \sum_{j; |j-i|=1} x_j\right)\right\} \end{aligned}$$

Then

$$\begin{aligned} \Pr(X_k = x_k | X_j = x_j, j \neq k, \mathbf{Y} = \mathbf{y}) & \\ & \propto \exp\left\{-\beta \sum_{i < j; |i-j|=1} x_i x_j + \sum_{i=1}^n \log f\left(y_i - ax_i - \frac{b}{M_i} \sum_{j; |j-i|=1} x_j\right)\right\} \\ & \propto \exp\left\{-\beta \sum_{|k-j|=1} x_k x_j + \log f\left(y_k - ax_k - \frac{b}{M_k} \sum_{j; |j-k|=1} x_j\right)\right\} \\ & \quad \exp\left\{\sum_{j; |k-j|=1} \log f\left(y_j - ax_j - \frac{b}{M_j} \sum_{l; |l-j|=1} x_l\right)\right\} \end{aligned}$$

showing that we still have a Markov random field, but now with $N_k = \{j; |k-j|=1 \text{ or } |k-j| = \sqrt{2} \text{ or } |k-j|=2\}$, i.e the first nearest neighbors, the 4 neighbors on the diagonal and the four grid points two units apart either in the horizontal or the vertical direction.

(c) Define $\{X_{t,i}\}$ to be the space-time process. Direct extension:

$$\Pr(\mathbf{X} = \mathbf{x}) \propto \exp\left\{-\beta \sum_{t=1}^T \sum_{i < j; |i-j|=1} x_{t,i} x_{t,j} - \gamma \sum_i \sum_{t=2}^T x_{t,i} x_{t-1,i}\right\} \quad (*)$$