

UNIVERSITETET I OSLO

Det matematisk-naturvitenskapelige fakultet

Examination in: STK4150 — Environmental and spatial statistics

Day of examination: Monday 10. june 2013.

Examination hours: 09.00 – 13.00.

This examination set consists of 3 pages.

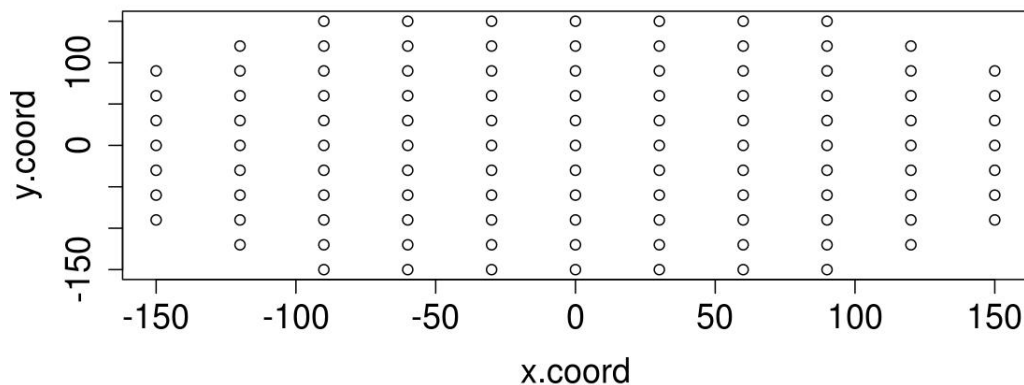
Appendices: None

Permitted aids: Approved calculator, Cressie and Wikle: Statistics for Spatio-temporal data

Make sure that your copy of the examination set is complete before you start solving the problems.

Problem 1.

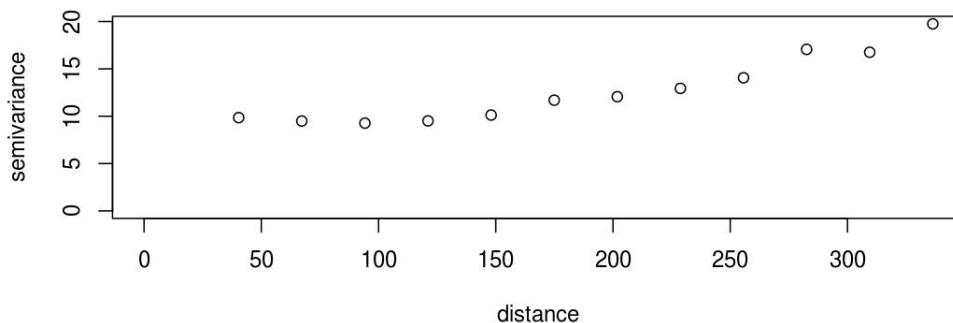
In this exercise we will consider a pure spatial data set on soil physical and chemical data collected on a field in the Weissenstaedter Becken, Germany. We will concentrate on the **moisture** content which is measured in $\text{Kg}/\text{Kg} \cdot 100\%$. The plot below displays the spatial sites, showing that the data are collected on a regular grid



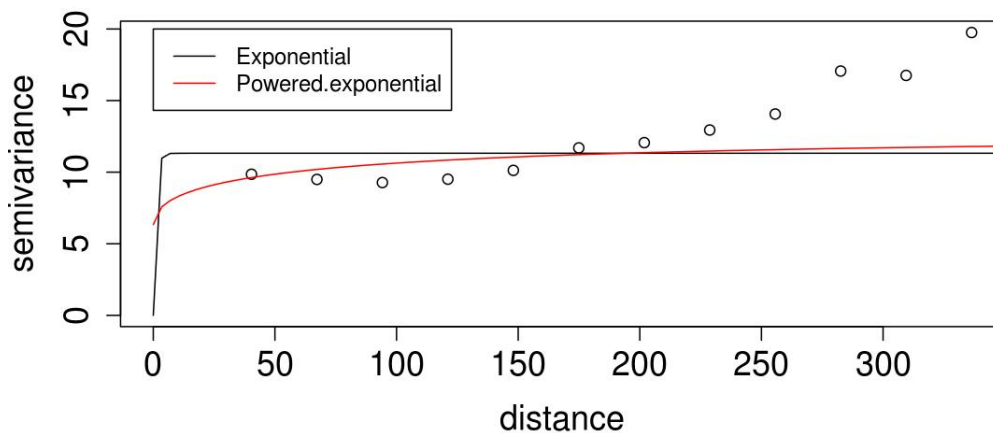
(Continued on page 2.)

We will consider the use of spatial statistics for this dataset.

- (a) Below is a (semi-)variogram of the data shown (assuming an isotropic and stationary structure). Discuss the use of variograms in general and comment on the particular shape of the variogram in this case.



- (b) In the plot below, an exponential and a powered exponential covariance function were fitted to the data. The log-likelihood values for these covariance functions were -287.2 and -286.9, respectively. In comparison, a non-spatial model gave a likelihood value equal to -286.9. Based on these results, do you find that any of these fits are satisfactory?



- (c) An alternative to geostatistical models are CAR models. Discuss the benefits in using CAR models in general.
- (d) A possible CAR based model is

$$Z_i = \mu + \delta_i + \varepsilon_i$$

(Continued on page 3.)

where $\{\delta_i\}$ follows a CAR structure (with a sum-constraint):

$$[\delta_i | \delta_j, j \neq i] = N\left(\frac{1}{N_i} \sum_{j \sim i} \delta_j, \sigma_\delta^2 / N_i\right)$$

where N_i is the number of neighbors of site i and $\sum_{j \sim i}$ means the sum over all sites j that are neighbors to site i . Further, $\{\varepsilon_i\}$ are iid and $N(0, \sigma_\varepsilon^2)$.

A fit to this model using the four nearest grid points as neighbors gave $\hat{\sigma}_\delta^2 = 2.751$ and $\hat{\sigma}_\varepsilon^2 = 6.712$. Further, the loglikelihood value was -258.36 in this case.

Discuss these results and compare with previous results.

- (e) In the model for $\{\delta_i\}$ a sum-constraint was imposed when doing the analysis. Why is this a reasonable restriction to impose?

Problem 2.

Consider a discretized version of a spatiotemporal process $\{y_t(s)\}$ where s is a spatial point (in one dimension) and t is a temporal point:

$$y_t(s) = \beta_1 y_{t-\Delta_t}(s) + \beta_2 [y_{t-\Delta_t}(s - \Delta_s) + y_{t-\Delta_t}(s + \Delta_s)] + \delta_t(s)$$

where $\{\delta_t(s)\}$ is a process that is independent in time but possibly correlated in space. We will also assume that β_1, β_2 are chosen such that the process is stationary in time.

- (a) What do we mean by stationarity in time? Discuss reasons for assuming/not assuming such a property.
- (b) Write $y_t(s)$ as a function of $\{y_{t-2\Delta_t}(v)\}$. Based on this, discuss why discretization with a small Δ_t is preferable. What are the disadvantages with having a small Δ_t ?
- (c) Is this model separable? Justify your answer.
- (d) Assume now that we have observations $Z_t(s)$ that, conditional on the Y -process are independent and Poisson distributed with expectations $\exp(Y_t(s))$.

What do we call these types of models. What are the benefits in this kind of modelling compared to a direct multivariate model on the observed Z 's?

- (e) Discuss the computational problems related to models of the type suggested in (d) and discuss briefly possible computational tools for performing inference.

END