Introduction to STK 4150/9150 Environmental and spatial-temporal statistics

> 16 .January 2017 Odd Kolbjørnsen

Today

- Who are we?
- Book
- Form
- Introduction
- Scope
- Begin @ the end
- Statistical preliminaries

Odd Kolbjørnsen

- Ph.D from NTNU in 2002
 - Nonlinear topics in the Bayesian approach to inverse problems
- 2002-2014: Norsk Regnesentral
- 2010-2015: Associate Editor in Mathematical Geosciences
- 2014 : Senior Exploration Analyst
 Lundin-Norway







Desired background

- General knowledge of quantitative methods/modelling
- General knowledge of mathematics (matrix/vector calculations)
- Probability theory
 - Expectations/Covariance matrices
 - Conditional densities/probabilities
 - Bayes theorem
- (Linear) Regression
- Maximum likelihood
- Knowledge of common distributions (normal, binomial, Poisson, Gamma, t)

STK 4150/9150

- Course made by:
 Geir Storvik
- Lectured by
 Odd Kolbjørnsen
- Book by:
 - Noel Cressie









Wiley Series in Probability and Statistics

Statistics for SPATIO-TEMPORAL DATA



Noel Cressie · Christopher K. Wikle





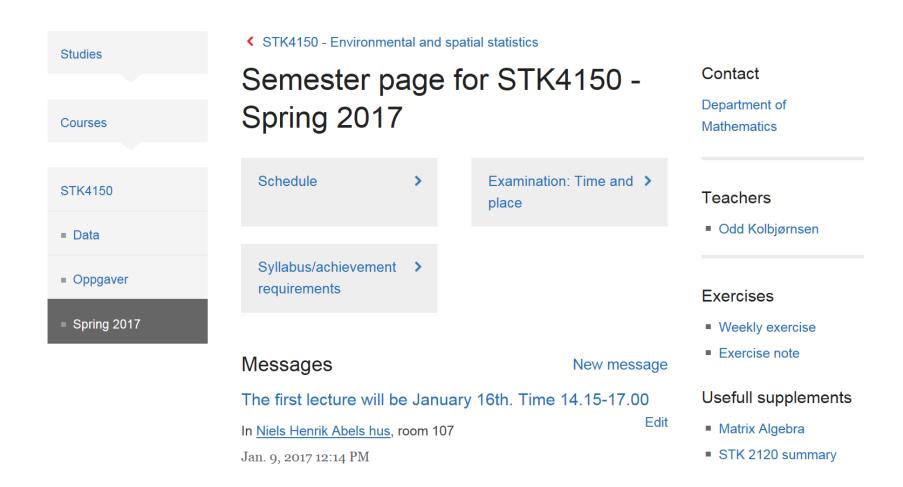
Course form

Grading

- Lectures
- Weekly exercises
- Compulsory project (Given in May)
 Written exam (30.May 9:00-13:00)
- Monday:
 - 14:15 16:00 Lectures

16.15 – 17:00 Last week Exercise Q&A

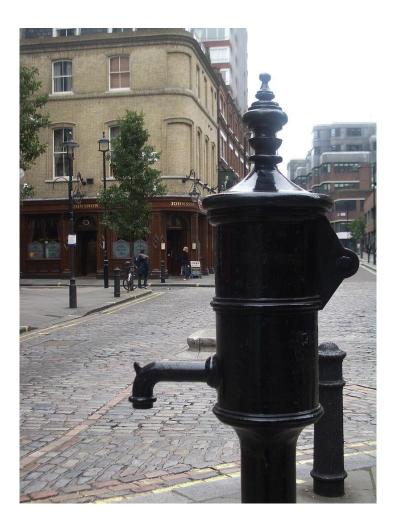
http://www.uio.no/studier/emner/matnat/math/STK4150/v17/



Environmental statistics (Wide definition)

- Meteorology (temperature, wind, humidity)
- Climate (CO2, Temperature)
- Pollution (ozone, sulfur,)
- Biological data (species, plants, Sustainable population management)
- Human data (Mortality, Disease surveillance)

John Snow on Cholera



1854 London outbreak of Cholera



First use of spatial statistics in medicine. Disease surveillance

Environmental statistics

- Variability in space and time
- Correlation in data
- Aim to infer cause- effect relationship
- Need where and when!
 - Recording of where and when is a powerful tool for obtaining covariates

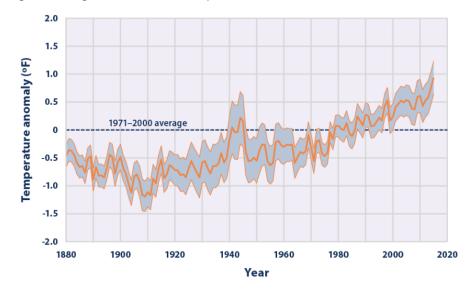


Figure 1. Average Global Sea Surface Temperature, 1880-2015

This graph shows how the average surface temperature of the world's oceans has changed since 1880. This graph uses the 1971 to 2000 average as a baseline for depicting change. Choosing a different baseline period would not change the shape of the data over time. The shaded band shows the range of uncertainty in the data, based on the number of measurements collected and the precision of the methods used.

Data source: NOAA, 2016[®] Web update: August 2016

https://www.youtube.com/watch?v=e0vj-0imOLw

Change of support:

- Measure at locations
 (~0.01m²)
- Average over globe~
 (361 132 000 km²)

Spatial statistics

- "Predict region of boreal forest (taiga) from satellite data.
- Explanatory variables:
 - Wetness index
 - Vegetation index
 - Temperature
 - Greenness index
- Boreality index



- Number of boreal spices / total number of spices

Spatial data - Example

Typical question

- Do an explanatory variable influence a response?
- Example:
 - Response: Number of species that belong to a set of boreal species divided by the total number of species *at a site*.

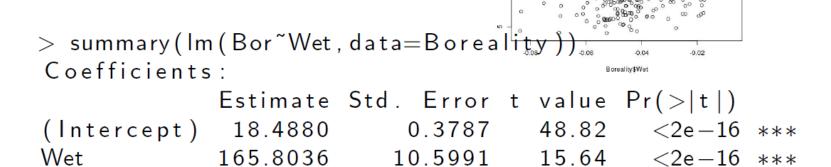
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Boreality\$Bor 5 20

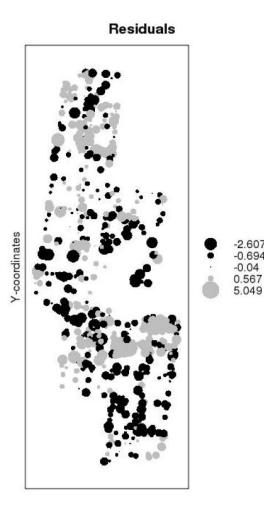
• Explanatory variable: Index of wetness

Possible approach

- Linear regression
- Assumes independence in residuals. Realistic here?



Spatial correlation

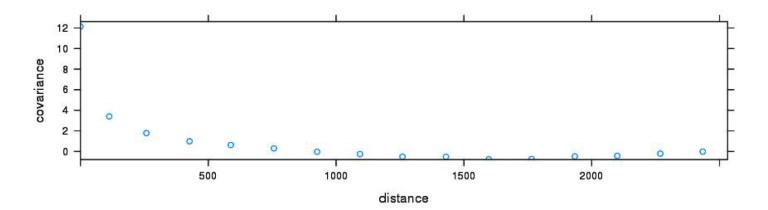


- Bubble plot of residuals
- Clustering of high and low values
 - Spatial correlation in the residual process
 - Missing explanatory variable with spatial characteristics

Covariance function for process $\{Y(\mathbf{s}), \mathbf{s} \in \mathbb{R}^2\}$:

 $Cov[Y(\mathbf{s} + \mathbf{h}), Y(\mathbf{s})] = C_Y(\mathbf{h})$

Plot of estimate (Boreal data)

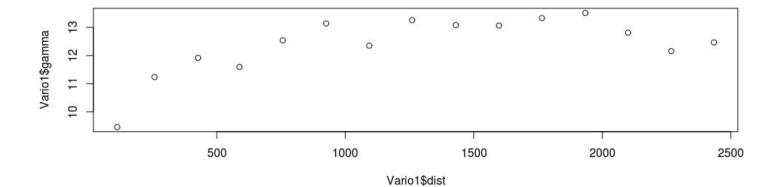


Spatial correlation - Variogram function

Alternative: Variogram function for process $\{Y(\mathbf{s}), \mathbf{s} \in \mathcal{R}^2\}$:

$$\begin{split} \gamma(\mathbf{h}) = &0.5 \text{Var}[Y(\mathbf{s} + \mathbf{h}) - Y(\mathbf{s})] \\ = &0.5 \{\text{Var}[Y(\mathbf{s} + \mathbf{h})] + \text{Var}[Y(\mathbf{s})] - 2 \text{Cov}[Y(\mathbf{s} + \mathbf{h}), Y(\mathbf{s})]\} \\ \stackrel{\mathbf{h} \text{ large}}{\approx} &0.5 \{\text{Var}[Y(\mathbf{s} + \mathbf{h})] + \text{Var}[Y(\mathbf{s})] \\ = &\text{Var}[Y(\mathbf{s})] \quad \text{if stationarity} \end{split}$$

Note: $Cov[Y(\mathbf{s} + \mathbf{h}), Y(\mathbf{s})] = C_Y(\mathbf{h}) = \gamma(\mathbf{0}) - \gamma(\mathbf{h})$ Plot of estimate (Boreal data)



What should we do with the boreal data?

- What goes wrong if we assumes independence?
 - Too certain on a large scale
 - Data redundancy (information content repeated)
 - Too uncertain on a short scale
 - Local refinement due to correlation (interpolation)

Simulation example: X_i and Y_i are independent, i = 1, ..., n: Model

$$Y_i|X_i = x_1 \sim N(\beta_0 + \beta_1 x_i, \sigma^2)$$

Assume $\beta_1 = 0$.

Wald test on H_0 : $\beta_1 = 0$ should reject hypothesis a fraction of $100\alpha\%$. Repeated experiment 1000

- All x's and y's independent: Rejection 48 times
- Dependence:

$$X_i = ax_{i-1} + \eta_i \qquad a = 0.9$$
$$Y_i = by_{i-1} + \varepsilon_i \qquad b = 0.9$$

Rejection 530 times!

• Dependence: Effective number of observations much lower

Assume $Y_1, ..., Y_n$ time series Simple model

$$\begin{split} Y_1 &\sim \mathcal{N}(\mu, \sigma^2 / (1 - a^2)) \\ Y_t &= \mu + a(y_{t-1} - \mu) + \delta_t, \quad \delta_t \sim \mathcal{N}(0, \sigma^2), \quad t = 2, ..., \end{split}$$

Autoregressive model of order 1, AR(1).

- $Y_t \sim N(\mu, \sigma^2/(1-a^2)$ for all t!
- Independence if a = 0

Simulation example, 1000 simulations, $\alpha = 0.05$:

- Ignoring dependence: Rejected 530 times
- Correction for dependence using AR(1) model: Rejected 56 times.

AR(1) - alternative formulation

$$Y_1 \sim \mathcal{N}(\mu, \sigma^2/(1-a^2))$$

$$Y_t = \mu + a(y_{t-1}-\mu) + \delta_t, \quad \delta_t \sim \mathcal{N}(0, \sigma^2)$$

imply $\mathbf{Y} = (Y_1, ..., Y_n)$ is multivariate Gaussian where

$$egin{aligned} & E[Y_t] = \mu \ & ext{var}[Y_t] = \sigma^2/(1-a^2) \ & ext{cor}[Y_t, Y_{t+ au}] = a^ au = C_Y(au) \end{aligned}$$

Can write

$$\begin{split} \mathbf{Y} \sim & \mathcal{N}(\mu \mathbf{1}, \mathbf{\Sigma}) \\ & \boldsymbol{\Sigma}_{tt} = & \mathsf{Var}[Y_t] \\ & \boldsymbol{\Sigma}_{t,t+\tau} = & \mathsf{Cov}[Y_t, Y_{t+\tau}] = \boldsymbol{\Sigma}_{tt} \mathsf{cor}[Y_t, Y_{t+\tau}] \end{split}$$

The alternative formulation

$$\mathbf{Y} \sim \mathcal{N}(\mu \mathbf{1}, \mathbf{\Sigma})$$

 $\Sigma_{tt} = \sigma^2 / (1 - a^2)$
 $\Sigma_{t,t+\tau} = \Sigma_{tt} a^{\tau} = \Sigma_{tt} C_Y(\tau)$

allow for extensions:

Including covariates

 $\mathbf{Y} \sim \! \mathcal{N}(\mathbf{X}\boldsymbol{\beta}, \boldsymbol{\Sigma})$

Other correlation structures structures

$$\Sigma_{t,t+\tau} = \Sigma_{tt} C_Y(\tau)$$

• Higher dimensional processes

Assume now $\{Y(\mathbf{s}), \mathbf{s} \in \mathbb{R}^2\}$ is a spatial process Let $\mathbf{Y} = (Y(\mathbf{s}_1), ..., Y(\mathbf{s}_n))$ Assume $\mathbf{Y} \sim N(\mathbf{X}\beta, \mathbf{\Sigma})$ where

$$\operatorname{cor}[Y(\mathbf{s}_i), Y(\mathbf{s}_j)] = C_Y(|\mathbf{s}_i - \mathbf{s}_j|)$$

Example boreal species:

- Using $C_Y(|\mathbf{s}_i \mathbf{s}_j|) = \exp(-|\mathbf{s}_i \mathbf{s}_j|/\theta)$
- Estimation of β_1

	Estimate	Std.Error	t-value	P-value
Independence	165.804	10.60	15. <mark>6</mark> 4	0
Spatial dependence	75.432	13.54	5.57	4.05e-08

Assume now
$$\{Y(\mathbf{s}), \mathbf{s} \in \mathbb{R}^2\}$$
 is a spatial process
Let $\mathbf{Y} = (Y(\mathbf{s}_1), ..., Y(\mathbf{s}_n))$
Assume $\mathbf{Y} \sim N(\mathbf{X}\beta, \mathbf{\Sigma})$ where

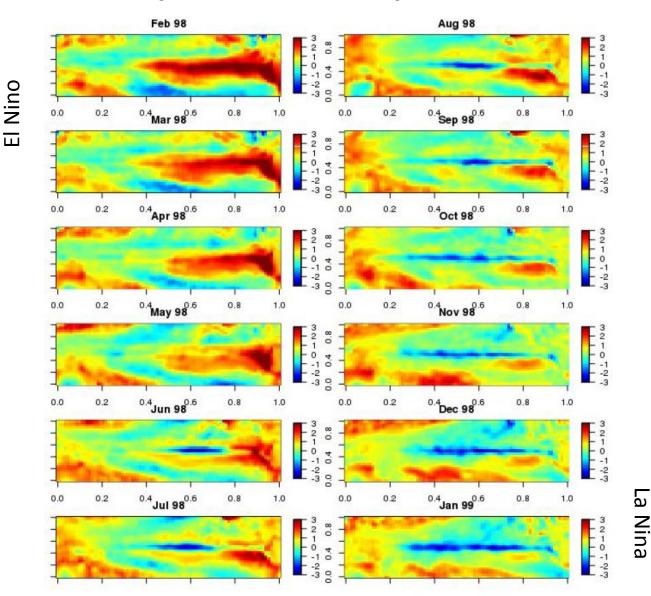
$$\operatorname{cor}[Y(\mathbf{s}_i), Y(\mathbf{s}_j)] = C_Y(|\mathbf{s}_i - \mathbf{s}_j|)$$

Problems:

- Multivariate Gaussian process for a finite number of positions
- Want a simultaneous distribution for a continuous set of variables
- Possible to define distribution for {Y(s), s ∈ R²} through all possible Y?
- What restrictions are needed on $C_Y(\cdot)$?

- Often, $Y(\mathbf{s})$ not available, but rather a summary for a region is given
- Regional data require special models
- Main idea: Neighbor regions have similar features
- Main approach: Markov models (extensions of models from STK2130)

Spatio-temporal Data

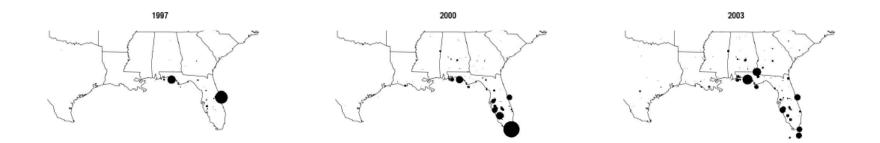


Surface temperature in Pacific region from February 1998 to January 1999

Invasive spread of Eurasian Collared Dove







North American Breeding Bird Survey data on the Eurasian Collared Dove (Streptopelia decaocto) for the years 1986 - 2008.

Can in principle do the same as for spatial processes: Let $\mathbf{Y} = (Y(\mathbf{s}_1, t_1), ..., Y(\mathbf{s}_n, t_n))$ Assume $\mathbf{Y} \sim N(\mathbf{X}\beta, \mathbf{\Sigma})$ where

$$\operatorname{cor}[Y(\mathbf{s}_i, t_i), Y(\mathbf{s}_j, t_j)] = C_Y(|\mathbf{s}_i - \mathbf{s}_j|, |t_i - t_j|)$$

As for time-series, there is an alternative in writing the model as a dynamical process:

$$Y_t(\mathbf{s}) = \mathcal{M}_t(\mathbf{s}, \mathbf{Y}_{t-1}(\cdot)) + \delta_t(\mathbf{s})$$

 \mathcal{M}_t can be based on

- statistical properties in data and/or
- physical knowledge of the process (e.g differential equations)

Typically $\{\mathbf{Y}(\mathbf{s}, t)\}$, the physical/biological process of interest, is not directly observed but

$$\mathbf{Z}_t = \mathbf{Y}_t + \varepsilon_t, \quad \varepsilon_t \sim N(\mathbf{0}, \sigma_{\varepsilon}^2 \mathbf{I})$$

Λ

Further, there are unknown parameters involved Hierarchical structure

$$\theta_M \rightarrow \mathbf{Y} \rightarrow \mathbf{Z}$$

If $\mathbf{Y} = \mathbf{y}$ is directly observed, likelihood

$$L(\boldsymbol{\theta}_M) = f(\mathbf{y}|\boldsymbol{\theta}_M) = \prod_{t=1}^T f(\mathbf{y}_t|\mathbf{y}_{< t}; \boldsymbol{\theta}_M)$$

Typically multivariate Gaussian densities (but more complicated if non-linearities are included) **Z** observed data, **Y** latent structure, likelihood

$$L(\boldsymbol{\theta}_{M},\boldsymbol{\theta}_{D}) = f(\mathbf{z}|\boldsymbol{\theta}_{M},\boldsymbol{\theta}_{D}) = \int_{\mathbf{y}} f(\mathbf{z}|\mathbf{y};\boldsymbol{\theta}_{D}) f(\mathbf{y}|\boldsymbol{\theta}_{M}) d\mathbf{y}$$

High-dimensional integral

Dynamic modelling: Allow for sequential calculation of likelihood.

Hierarchical model

	Variable	Densities	Notation in book
Data model:	Z	$p(\mathbf{Z} \mathbf{Y}, oldsymbol{ heta})$	$[Z Y, \boldsymbol{ heta}]$
Process model:	Υ	$ ho(\mathbf{Y} m{ heta})$	$[\mathbf{Y} heta]$
Parameter:	$oldsymbol{ heta}$		

Simultaneous model: $p(\mathbf{y}, \mathbf{z}|\boldsymbol{\theta})$ Marginal model: $p(\mathbf{z}|\boldsymbol{\theta}) = \int_{\mathbf{y}} p(\mathbf{z}, \mathbf{y}|\boldsymbol{\theta}) d\mathbf{y}$

Bayesian approach: Include model on heta

	Variable	Densities	Notation in book
Data model:	Ζ	$p(\mathbf{Z} \mathbf{Y}, \boldsymbol{ heta})$	$[Z Y, \theta]$
Process model:	Υ	$ ho(\mathbf{Y} m{ heta})$	$[\mathbf{Y} heta]$
Parameter model:	heta	ho(heta)	[heta]

Simultaneous model: $p(\mathbf{y}, \mathbf{z}, \theta)$ Marginal model: $p(\mathbf{z}) = \int_{\boldsymbol{\theta}} \int_{\mathbf{y}} p(\mathbf{z}, \mathbf{y}|\boldsymbol{\theta}) d\mathbf{y} d\boldsymbol{\theta}$

Spatio-temporal data and uncertainties

- Space-Time: The next Frontier
- Time-data give possibilities for causation
- Spatio-temporal data contain many sources of uncertainty
- Statistics: Science of Uncertainty!
 - Uncertainty in data
 - Uncertainty in models

Course @ a slide

- Statistics preliminaries (Chapter 2)
- Temporal processes (Chapter 3)
 - Deterministic models
 - Stochastic models
 - Spectral representation
 - Spatial processes
 - Geostatistical processes, sec 4.1
 - Lattice processes, sec 4.2
 - Point processes, sec 4.3

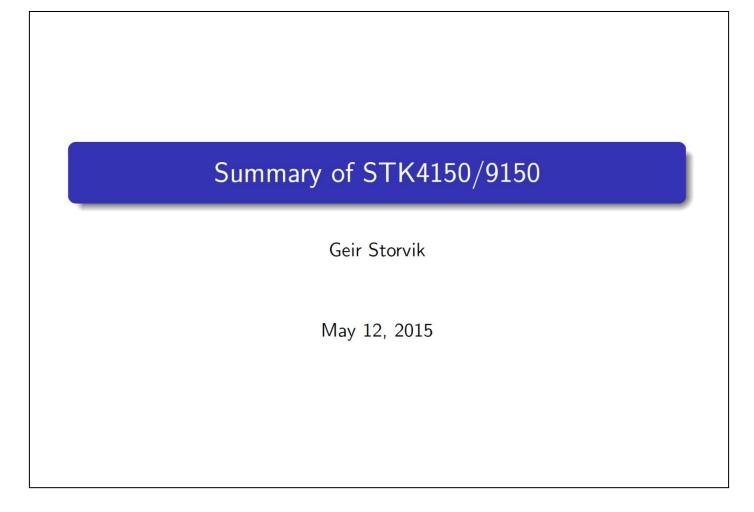
- Spatio-temporal processes
 - Exploratory methods (Chapter 5)
 - Models (Chapter 6)
 - Hierarchical models (Chapters 7 and 8)
- Focus on
 - Modeling
 - Analysis in practice (using R)
 - Theoretical aspects

Prelim/Jan

Computations

- Inference for space time-processes difficult due to
 - Complex models
 - Latent processes (likelihood not directly specified)
 - Huge amounts of data
- Possibilities
 - Use available software
 - Typically for specific models
 - Monte Carlo methods
 - Preferred method in the book, described in sec 2.3
 - Using integrated nested Laplace approximation (INLA)
 - Flexible software for latent Gaussian processes
 - Will be used throughout the course
 - Computation within R

Begin @ the end



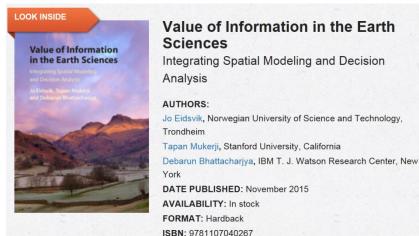
Aims

- Prediction/forecasting
- Learning about the processes

Challenges

- Complex dependence structures
- Huge amounts of data

Not focus on decisions theory. If interested:



The importance of taking dependence into account

- Spatio-temporal data often contain dependence
- Ignoring dependence can give wrong results (too small uncertainty measures)
- Inclusion of dependence complicates
 - Modeling
 - Inference/computation
- Inclusion of covariates can reduce dependence
- Dependence can improve prediction/forecasting

Exploratory data analysis (EDA)

- Always do EDA!
- Various tools:
 - Direct plots of data/animations
 - Autocorrelation function (time series)
 - Variograms (spatial data)
 - Moran's I, STI (tests for dependence, spatial/spatio-temporal)
 - Empirical orthogonal functions (spatio-temporal)

- Differential equations (deterministic/stochastic) $Y_t = \mathcal{M}(Y_{t-1}) + W_t$
- ARMA models: $Y_t = \sum_{k=1}^p \alpha_k Y_{t-k} + \sum_{l=0}^q \beta_l W_{t-l}$
- Most useful: AR(1). NB: Sparse precision matrix
- Non-linear models related to differential equations (?)

- Geostatistical modeling covariance functions
 - Need non-negative definite covariance matrix for any finite collection of spatial points
 - Challenge to construct legal covariance functions
 - Stationarity/isotrophy simplifies modeling and inference
 - Prediction through kriging

•
$$\mathbf{x}_1 | \mathbf{x}_2 \sim \mathcal{N}(\boldsymbol{\mu}_1 + \boldsymbol{\Sigma}_{12} \boldsymbol{\Sigma}_{22}^{-1} (\mathbf{x}_2 - \boldsymbol{\mu}_2), \boldsymbol{\Sigma}_{11} - \boldsymbol{\Sigma}_{12} \boldsymbol{\Sigma}_{22}^{-1} \boldsymbol{\Sigma}_{21})$$

- CAR/MRF-models sparse precision matrices
 - $p(Y(\mathbf{s}_i)|\mathbf{Y}_{-i}) = p(Y(\mathbf{s}_i)|Y(\mathbf{s}_j), j \in \mathcal{N}_i)$
 - Simplifies modeling/inference
- Hierarchical modeling allow for non-Gaussian observations

- Possible to define time as extra "spatial" dimension
 - More difficult to construct valid covariance functions
- Advantages in modeling time dynamically
 - Partial differential equations stochastic versions
 - Time series approaches $\mathbf{Y}_t = \mathcal{M}(\mathbf{Y}_{t-1}) + \mathbf{W}_t$

Spatio-temporal processes - simplifications

- Spatio-temporal data involve a huge number of observations/variables
- Difficult to model, difficult to process
- Need simplifications
 - Additive models $Y_t(\mathbf{s}) = \mathbf{X}_t(\mathbf{s})^T \boldsymbol{\beta} + \alpha_t + \delta(\mathbf{s}) + \varepsilon_t(\mathbf{s})$
 - Separable covariance functions
 - Dimension reductions: $\mathbf{Y}_t = \mathbf{\Phi} \boldsymbol{\alpha}_t$ with dynamics in lower dimensional $\boldsymbol{\alpha}_t$.

Hierarchical modeling

- Distinguish between
 - process model
 - observation model
- Advantages
 - Simpler modeling
 - Allow for non-Gaussian observations
- Can include model for parameters in a Bayesian framework

- Kalman filtering (linear Gaussian models)
- MCMC
- INLA
- (Particle filters)
- (EM algorithm)

- Efficient generic tools for models outside the INLA framework
- Tools for model selection
- More integration of physical and statistical models