

Chapter 4 - Spatial processes R packages and software

Lecture notes

Odd Kolbjørnsen and Geir Storvik

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- General set up for "Kriging type problems"
 - Introductory example
 - Kriging case
 - General case
- Change of support
- Spatial moving average models
 - Construction
 - Correlation function
- Non gaussian observations
 - Monte Carlo
 - Laplace approximation
 - INLA

Today

- To day computations
 - Software
 - Computer
 - R
 - INLA
- Next timel lattice models

- There is always an existing software that "does your job"
- The challenge is to figure out how this works
- Even if the software does not do exactly what you want maybe it is good enough
- Reasons **not** to make your own computer code
 - existing code is tested (less bugs)
 - existing code is optimized (speed)
 - often related to publications
 - easier to get others to "accept it"
- Reasons to make your own computer code
 - understand the methodology better
 - improve/develop existing methodology
 - combining with other techniques
 - compete with existing computer code
 - because you have too much spare time

Software options

- Wiki List of spatial analysis software
 - .../wiki/List_of_spatial_analysis_software/
 - LuciadLightspeed, Open GeoDa, CrimeStatc, SaTScan, SAGA, IDRISI, Biodiverse, ERDAS IMAGINE, TerraLens ++
- ArcGIS: Geoprocessing, visualization (GIS = Geographic information system)
- GeoBUGS: Bayesian analysis (WinBugs)
- GeoDa: Explanatory Spatial Analysis +
- STARS: Space-time
- SAS/STAT: spatial analysis (limited)
- SPLUS: SpatialStats
- Matlab: Spatial-statistics toolbox (fast but limited)
- GEOEAS, SGeMS, GSLIB ,COHIBA, CRAVA ++
- **R**

Spatial analysis in R

- CRAN (The Comprehensive R Archive Network)

URL: <https://CRAN.R-project.org/view=Spatial>

- Classes for spatial data: sp, spacetime
 - Handling spatial data: geosphere
 - Reading and writing spatial data: rgdal
 - Visualisation
 - Point pattern analysis
 - Geostatistics: geoR, gstat, spatial
 - Disease mapping and areal data analysis: INLA
 - Spatial regression: nlme
 - Ecological analysis
- `install.packages(...)`
 - `update.packages(...)`
 - `library(...)`

Hierarchical and hierarchical Bayesian approach

Hierarchical model

	Variable	Densities	Notation in book
Data model:	\mathbf{Z}	$p(\mathbf{Z} \mathbf{Y}, \theta)$	$[\mathbf{Z} \mathbf{Y}, \theta]$
Process model:	\mathbf{Y}	$p(\mathbf{Y} \theta)$	$[\mathbf{Y} \theta]$
Parameter:	θ		

Simultaneous model: $p(\mathbf{y}, \mathbf{z}|\theta) = p(\mathbf{z}|\mathbf{y}, \theta)p(\mathbf{y}|\theta)$

Marginal model: $L(\theta) = p(\mathbf{z}|\theta) = \int_{\mathbf{y}} p(\mathbf{z}, \mathbf{y}|\theta) d\mathbf{y}$

Inference: $\hat{\theta} = \operatorname{argmax}_{\theta} L(\theta)$

Bayesian approach: Include model on θ

	Variable	Densities	Notation in book
Data model:	\mathbf{Z}	$p(\mathbf{Z} \mathbf{Y}, \theta)$	$[\mathbf{Z} \mathbf{Y}, \theta]$
Process model:	\mathbf{Y}	$p(\mathbf{Y} \theta)$	$[\mathbf{Y} \theta]$
Parameter model:	θ	$p(\theta)$	$[\theta]$

Simultaneous model: $p(\mathbf{y}, \mathbf{z}, \theta)$

Marginal model: $p(\mathbf{z}) = \int_{\theta} \int_{\mathbf{y}} p(\mathbf{z}, \mathbf{y}|\theta) d\mathbf{y} d\theta$

Inference: $\hat{\theta} = \int_{\theta} \theta p(\theta|\mathbf{z}) d\theta$

INLA = Integrated nested Laplace approximation (software)

C-code, R-interface

Can be installed by

```
source("http://www.math.ntnu.no/inla/givemeINLA.R")
```

Both empirical Bayes and Bayes

R-INLA: An R-package for INLA

Håvard Rue

Department of Mathematical Sciences
NTNU, Norway

February 2, 2011

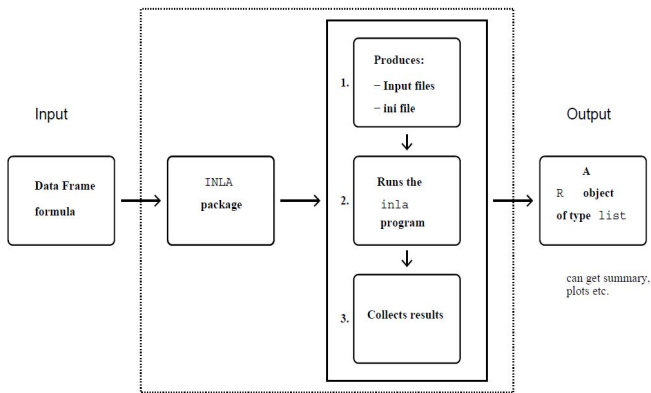
Full presentation on the course web page

Implementing INLA

All procedures required to perform INLA need to be carefully implemented to achieve a good speed; easy to implement a slow version of INLA.

- The GMRFLib-library
- The inla-program
- The INLA package for R
 - R-interface to the inla-program. (That's why its not on CRAN.)
 - Convert "formula"-statements into ".ini"-file definitions
 - Similar interface as other R packages

The INLA package for R



Main functions of the INLA package

- `f()` Define your model as a formula
- `inla()` Run the analysis
- `summary()`
- `plot()`
- `inla.hyperpar()`
- `inla.cpo()`

Documentation is available at www.r-inla.org and has help-pages in R

Model specification the INLA package II

The model is specified in R through a formula, similar to `glm/gam++`:

```
> formula = y ~ x1 + x2 + f(x3, ...)
```

The `f()` function is used to specify various “random”-effects in the model.

Some models

- `iid`, `iid1d`, `ii2d`, `iid3d`: random effects
- `rw1`, `rw2`, `ar1`: smooth effect of covariates or time effect
- `seasonal`: seasonal effect
- `besag`: spatial effect (CAR model)
- `generic`: user defined precision matrix

Example - simulated data

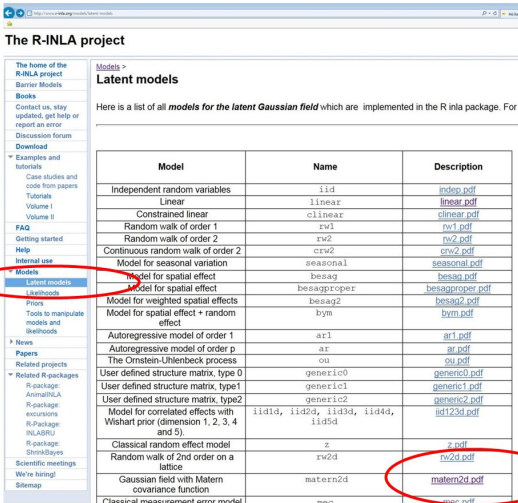
Assume

$$\begin{aligned} Y(\mathbf{s}) &= \beta_0 + \beta_1 x(\mathbf{s}) + \sigma_\delta \delta(\mathbf{s}), & \{\delta(\mathbf{s})\} & \text{matern correlation} \\ Z(\mathbf{s}_i) &= Y(\mathbf{s}_i) + \sigma_\varepsilon \varepsilon(\mathbf{s}_i), & \{\varepsilon(\mathbf{s}_i)\} & \text{independent} \end{aligned}$$

Simulations:

- Simulation on 20×30 grid
- $\{x(\mathbf{s})\}$ sinus curve in horizontal direction
- Parameter values $(\beta_0, \beta_1) = (2, 0.3)$, $\sigma_\delta = 1$, $\sigma_\varepsilon = 0.3$ and $(\theta_1, \theta_2) = (2, 3)$

Latent models in INLA



The R-INLA project

Models >
Latent models

Here is a list of all *models for the latent Gaussian field* which are implemented in the R inla package. For

Model	Name	Description
Independent random variables	iid	indep.pdf
Linear	linear	linear.pdf
Constrained linear	clinear	clinear.pdf
Random walk of order 1	rw1	rw1.pdf
Random walk of order 2	rw2	rw2.pdf
Continuous random walk of order 2	crw2	crw2.pdf
Model for seasonal variation	seasonal	seasonal.pdf
Model for spatial effect	besag	besag.pdf
Model for spatial effect	besagproper	besagproper.pdf
Model for weighted spatial effects	besag2	besag2.pdf
Model for spatial effect + random effect	bym	bym.pdf
Autoregressive model of order 1	ar1	ar1.pdf
Autoregressive model of order p	ar	ar.pdf
The Ornstein-Uhlenbeck process	ou	ou.pdf
User defined structure matrix, type 0	generic0	generic0.pdf
User defined structure matrix, type1	generic1	generic1.pdf
User defined structure matrix, type2	generic2	generic2.pdf
Model for correlated effects with Wishart prior (dimension 1, 2, 3, 4 and 5).	iid1d, iid2d, iid3d, iid4d, iid5d	iid123d.pdf
Classical random effect model	z	z.pdf
Random walk of 2nd order on a lattice	rw2d	rw2d.pdf
Gaussian field with Matern covariance function	matern2d	matern2d.pdf
Classical measurement error model	me	me.pdf

Latent model =
INLA language for:
"a Gaussian thing we
use in the model"

The question is not
whether you use a
Gaussian model or not
but how you do it!

Matern model - setup

```
C:\Forelesning\STK4150\R\inla_matern_inmodel.R - R Editor
#Necessary libraries
library(INLA)
library(geoR)
set.seed(231171)

#Size of grid (note you might want to reduce this if the computation is slow)
nrow=20
ncol=30
n = nrow*ncol

#Indices in both directions
i.m = matrix(rep(1:ncol,each=nrow),nrow=nrow)
j.m = matrix(rep(1:nrow,ncol),ncol=ncol)
#Covariate
x.m = sin(j.m+0*i.m)
image(x.m,zlim=c(-2,2),col=rainbow(256))

#Converting matrices to vectors, inla requires input to be vectors
x = inla.matrix2vector(x.m)
i = inla.matrix2vector(i.m)
j = inla.matrix2vector(j.m)

#Parameter values
beta = c(2,0.3);sigma.y=1
#Making covariance matrix through distance matrix
d = as.matrix(dist(cbind(i,j),diag=TRUE,upper=TRUE))
C = sigma.y^2*matern(d,2,3)
par(mfrow=c(1,1))
image(beta[1]+beta[2]*x.m,zlim=c(-1,5),col=rainbow(256))
image(C,zlim=c(-2,2),col=rainbow(256),ylim=rev(c(0,1)))
```

[Code on webpage](#)

Matern model - setup

```
C:\Forelesning\STK4150\R\inla_matern_inmodel.R - R Editor
#Necessary libraries
library(INLA)
library(geoR)
set.seed(231171)

#Size of grid (note you might want to reduce this if the computation is slow)
nrow=20
ncol=30
n = nrow*ncol

#Indices in both directions
i.m = matrix(rep(1:ncol,each=nrow),nrow=nrow)
j.m = matrix(rep(1:nrow,ncol),ncol=ncol)
#Covariate
x.m = sin(j.m+0*i.m)
image(x.m, zlim=c(-2,2), col=rainbow(256))

#Converting matrices to vectors, inla requires input to be vectors
x = inla.matrix2vector(x.m)
i = inla.matrix2vector(i.m)
j = inla.matrix2vector(j.m)

#Parameter values
beta = c(2,0.3);sigma.y=1
#Making covariance matrix through distance matrix
d = as.matrix(dist(cbind(i,j),diag=TRUE,upper=TRUE))
C = sigma.y^2*matern(d,2,3)
par(mfrow=c(1,1))
image(beta[1]+beta[2]*x.m, zlim=c(-1,5), col=rainbow(256))
image(C, zlim=c(-2,2), col=rainbow(256),ylim=rev(c(0,1)))
```

Packages

Set seed to have reproducible calculations

dimensions

Spatial parameters

Covariate

Format to fit INLA

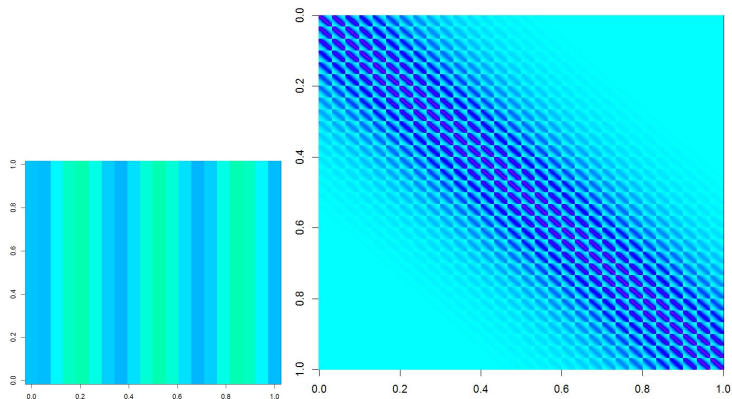
parameters

Distance matrix: 600 x 600

geoR

Plot mean and covariance

Process model mean and covariance



Mean: $20 \times 30 = 600$, Covariance: $600 \times 600 = 360000$

Matern model - parametrization

```
C:\Forelesning\STK4150\R\inla_matern_linmodel.R - R Editor
#Simulating data using Cholesky decomposition
C.chol = t(chol(C))
y = beta[1]+x*beta[2] + C.chol%*%matrix(rnorm(n),ncol=1)
#Additive Gaussian observation noise
z = y+0.3*rnorm(n)

y.m = inla.vector2matrix(y,nrow,ncol)
z.m = inla.vector2matrix(z,nrow,ncol)

#Plotting covariate and latent process and observations
par(mfrow=c(2,3))
image(x.m,zlim=c(-1,5),col=rainbow(256))
image(y.m,zlim=c(-1,5),col=rainbow(256))
image(z.m,zlim=c(-1,5),col=rainbow(256))

#Making dataframe for inla call, using delta for spatially correlated
#random effect
GridIndex = 1:n
data=data.frame(z=z,x=x,GridIndex=GridIndex)

#Defining model through a formula statement
#Note that the matern2d model assumes GridIndex is defined on a grid with
#dimensions nrow and ncol

formula= z ~ 1 + x + f(GridIndex, model="matern2d", nu=3, nrow=nrow, ncol=ncol)

#inla call using empirical Bayes approach
result.eb=inla(formula, family="gaussian", data=data,
  control.predictor = list(compute = TRUE),
  control.inla=list(int.strategy="eb"))
summary(result.eb)

#inla call using Bayes approach
result.b=inla(formula, family="gaussian", data=data, control.predictor = list(compute = TRUE))
summary(result.b)
```

Matern model - parametrization

```
C:\Forelesning\STK4150\R\inla_matern_inmodel.R - R Editor
#Simulating data using Cholesky decomposition
C.chol = t(chol(C))
y = beta[1]+x*beta[2] + C.chol%*%matrix(rnorm(n),ncol=1)
#Additive Gaussian observation noise
z = y+0.3*rnorm(n)

y.m = inla.vector2matrix(y,nrow,ncol)
z.m = inla.vector2matrix(z,nrow,ncol)

#Plotting covariate and latent process and observations
par(mfrow=c(2,3))
image(x.m,zlim=c(-1,5),col=rainbow(256))
image(y.m,zlim=c(-1,5),col=rainbow(256))
image(z.m,zlim=c(-1,5),col=rainbow(256))

#Making dataframe for inla call, using delta for spatially correlated
#random effect
GridIndex = 1:n
data=data.frame(z=z,x=x,GridIndex=GridIndex)

#Defining model through a formula statement
#Note that the matern2d model assumes GridIndex is defined on a grid with
#dimensions nrow and ncol

formula= z ~ 1 + x + f(GridIndex, model="matern2d", nu=3, nrow=nrow, ncol=ncol)

#inla call using empirical Bayes approach
result.eb=inla(formula, family="gaussian", data=data,
  control.predictor = list(compute = TRUE),
  control.inla=list(int.strategy="eb"))
summary(result.eb)

#inla call using Bayes approach
result.b=inla(formula, family="gaussian", data=data, control.predictor = list(compute = TRUE))
summary(result.b)
```

Synthetic case and data

Format to fit INLA

Plot

Numbering all grid nodes linearly
Format

Empirical Bayes

Bayesian approach

Empirical Bayes vs Bayes

```
> (result.eb)
```

```
Call:
c("inla(formula = formula, family = \"gaussian\", data = data, control.predictor = list(compute = TRUE), ", " control.inla = list(int.strategy = \"
```

```
Time used:
Pre-processing   Running inla Post-processing   Total
0.3276081       3.2136819       0.3432090       3.8844991
```

```
Integration Strategy: Empirical Bayes
```

```
Model contains 3 hyperparameters
The model contains 2 fixed effect (including a possible intercept)
```

```
Likelihood model: gaussian
```

```
The model has 1 random effects:
1.'GridIndex' is a Matern2D model
```

```
> (result.b)
```

```
Call:
"inla(formula = formula, family = \"gaussian\", data = data, control.predictor = list(compute = TRUE))"
```

```
Time used:
Pre-processing   Running inla Post-processing   Total
0.3276088       3.8844841       0.2652051       4.4772980
```

```
Integration Strategy: Model contains 3 hyperparameters
The model contains 2 fixed effect (including a possible intercept)
```

```
Likelihood model: gaussian
```

```
The model has 1 random effects:
1.'GridIndex' is a Matern2D model
```

Empirical Bayes

```
> summary(result.eb)
```

Call:

```
c("inla(formula = formula, family = \"gaussian\"), data = data, control.predictor = list(compute = TRUE), ", "
```

Time used:

Pre-processing	Running inla	Post-processing	Total
0.3432	8.7831	0.3276	9.4539

Fixed effects:

	mean	sd	0.025quant	0.5quant	0.975quant	mode	kld
(Intercept)	1.7991	0.0826	1.6369	1.7990	1.9611	1.7991	0
x	0.3385	0.0645	0.2119	0.3385	0.4650	0.3385	0

Random effects:

Name	Model
GridIndex	Matern2D model

Model hyperparameters:

	mean	sd	0.025quant	0.5quant	0.975quant	mode
Precision for the Gaussian observations	13.213	1.3969	10.6733	13.144	16.160	13.009
Precision for GridIndex	1.398	0.2839	0.8915	1.385	1.999	1.368
Range for GridIndex	4.901	0.3261	4.3208	4.878	5.600	4.822

Expected number of effective parameters(std dev): 259.71(0.00)

Number of equivalent replicates : 2.31

Marginal log-Likelihood: -385.97

Posterior marginals for linear predictor and fitted values computed

Matern model - parametrization

	Model	Range par	Smoothness par
Book	$\propto \{ \ \mathbf{h}\ /\theta_1 \}^{\theta_2} K_{\theta_2}(\ \mathbf{h}\ /\theta_1)$	θ_1	θ_2
geoR	$\propto \{ \ \mathbf{h}\ /\phi \}^{\kappa} K_{\kappa}(\ \mathbf{h}\ /\phi)$	ϕ	κ
INLA	$\propto \{ \ \mathbf{h}\ * \kappa \}^{\nu} K_{\nu}(\ \mathbf{h}\ * \kappa)$	$1/\kappa$	ν

Note: INLA reports an estimate of another “range”, defined as

$$r = \frac{\sqrt{8}}{\kappa}$$

corresponding to a distance where the covariance function is approximately zero. An estimate of the range parameter can then be obtained by

$$\frac{1}{\kappa} = \frac{r}{\sqrt{8}}$$

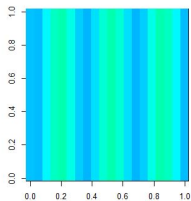
Note: INLA works with *precisions* $\tau_y = \sigma_y^{-2}$, $\tau_z = \sigma_z^{-2}$.

Result - INLA - empirical Bayes

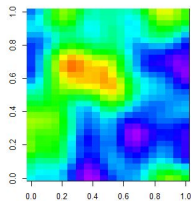
Parameter	True value	Estimate Run 1
β_1	2.0	1.7991
β_2	0.3	0.3385
σ_z	0.3	$\frac{1}{\sqrt{13.213}} = 0.275$
σ_y	1.0	$\frac{1}{\sqrt{1.398}} = 0.846$
ϕ_1	2.0	$\frac{4.901}{\sqrt{8}} = 1.7328$

Spatial prediction Run 1

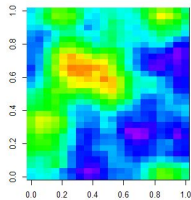
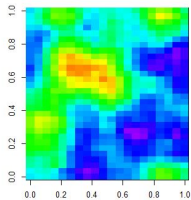
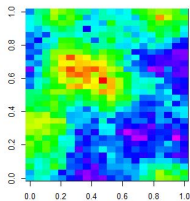
Prior mean



"True" intensity



Gaussian data



Empirical Bayes and Bayesian prediction

Result - INLA - empirical Bayes

Parameter	True value	Estimate Run 1	Estimate Run 2
β_1	2.0	1.799	1.9719
β_2	0.3	0.3385	0.4741
σ_z	0.3	$\frac{1}{\sqrt{13.213}} = 0.275$	$\frac{1}{\sqrt{13.6917}} = 0.2756$
σ_y	1.0	$\frac{1}{\sqrt{1.398}} = 0.846$	$\frac{1}{\sqrt{0.0014}} = 26.72^*$
ϕ_1	2.0	$\frac{4.901}{\sqrt{8}} = 1.7328$	$\frac{17.44}{\sqrt{8}} = 6.16^*$

* Commonly seen variance vs range tradeoff.

Large variance and long range vs

"on scale" variance and "on scale" range

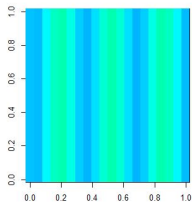
Always compare your estimates with data variance.

Here: $\widehat{\text{Var}}(Z) = 1.03$, theoretically ($\text{Var}(Z) = 1.09 = 1.0 + 0.3^2$)

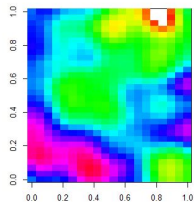
This is an argument for a Bayesian approach with an informative prior

Spatial prediction Run 2

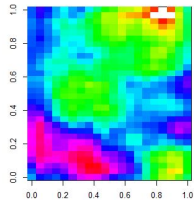
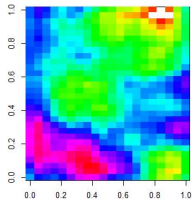
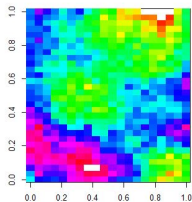
Prior mean



"True" intensity



Gaussian data



Empirical Bayes and Bayesian prediction

Example - simulated data

Assume

$$Y(\mathbf{s}) = \beta_0 + \beta_1 x(\mathbf{s}) + \sigma_\delta \delta(\mathbf{s}), \quad \{\delta(\mathbf{s})\} \text{ matern correlation}$$
$$Z(\mathbf{s}_i) \sim \text{Poisson}(\exp(Y(\mathbf{s}_i)))$$

Simulations:

- Simulation on 20×30 grid
- $\{x(\mathbf{s})\}$ sinus curve in horizontal direction
- Parameter values $(\beta_0, \beta_1) = (1, 0.3)$, $\sigma_\delta = 1$, $\sigma_\varepsilon = 0.3$ and $(\theta_1, \theta_2) = (2, 3)$

Empirical Bayes (note constant term changed from 2 to 1, hence $y-1$)

```
## poisson data|
intensity=y-1; # changed just to reduce the intensity slightly
z = rpois(n,exp(intensity))
z.m = inla.vector2matrix(z,nrow,ncol)

data=data.frame(z=z.m,x=x,GridIndex=GridIndex)
formula= z ~ 1 + x + f(GridIndex, model="matern2d", nu=3, nrow=nrow, ncol=ncol)
result.eb.pois=inla(formula, family="poisson", data=data, control.inla=list(int.strategy="eb"))

pred.y.eb.pois = result.eb.pois$summary.fixed[1,1]+result.eb.pois$summary.fixed[2,1]*x+
  result.eb.pois$summary.random$GridIndex$mean
pred.y.m.eb.pois = inla.vector2matrix(pred.y.eb.pois,nrow,ncol)
par(mfrow=c(2,2))
image(intensity,zlim=c(-2,5),col=rainbow(256),ylim=rev(c(0,1)))
image(z.m,zlim=c(-1,15),col=rainbow(256),ylim=rev(c(0,1)))
image(pred.y.m.eb.pois,zlim=c(-2,5),col=rainbow(256),ylim=rev(c(0,1)))
```

Parameter prediction, Poisson

```
> summary(result.eb.pois)

Call:
inla(formula = formula, family = \"poisson\", data = data, control.inla = list(int.strategy = \"eb\"))

Time used:
  Pre-processing   Running inla Post-processing       Total
      0.3432         5.0857         0.1716         5.6005

Fixed effects:
      mean      sd 0.025quant 0.5quant 0.975quant  mode kld
(Intercept) 1.5271 0.1110   1.3086   1.5272   1.7444 1.5276  0
x            0.3266 0.0884   0.1534   0.3265   0.5002 0.3264  0

Random effects:
Name      Model
GridIndex  Matern2D model

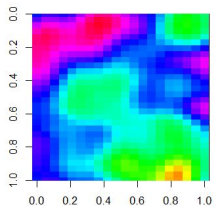
Model hyperparameters:
      mean      sd 0.025quant 0.5quant 0.975quant  mode
Precision for GridIndex 0.7305 0.1903   0.4133   0.7128   1.155 0.681
Range for GridIndex     5.4164 0.4146   4.6727   5.3900   6.300 5.328

Expected number of effective parameters(std dev): 171.86(0.00)
Number of equivalent replicates : 3.491

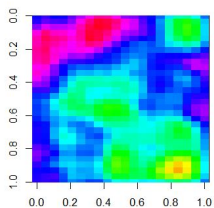
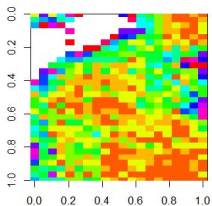
Marginal log-Likelihood: -1325.95
```

Spatial prediction, Poisson

"True" intensity



Poisson data (counts)



Estimated intensity

Principle in GRMF = Gaussian Markov Random field is to invert the relation in "smoothing of independent Gaussian variables"

$$\mathbf{Y} = \mathbf{L}\boldsymbol{\varepsilon}, \boldsymbol{\varepsilon} \sim N(\mathbf{0}, \mathbf{I}) \Rightarrow \mathbf{Y} \sim N(\mathbf{0}, \boldsymbol{\Sigma} = \mathbf{L}\mathbf{L}^T)$$

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- Select the smooting kernel to be the cholesky factor: $\mathbf{Y} = \mathbf{L}\boldsymbol{\varepsilon}$
- Then flip the equation and use the pressision matrix $\mathbf{Q} = \boldsymbol{\Sigma}^{-1}$:

$$\mathbf{L}^{-1}\mathbf{Y} = \boldsymbol{\varepsilon}, \boldsymbol{\varepsilon} \sim N(\mathbf{0}, \mathbf{I}) \Rightarrow \mathbf{Y} \sim N(\mathbf{0}, \mathbf{Q} = \mathbf{L}^{-1}\mathbf{L}^{-T})$$

The formulations are equivalent but \mathbf{L} and \mathbf{L}^{-1} differs greatly. This has major impact on computations.

Choleskey versus inverse choleskey in AR(1)

$$Y_1 = \sigma_1 \varepsilon_1, \quad Y_i = \alpha Y_{i-1} + \sigma \varepsilon_i$$

"Inverse formulation":

$$\varepsilon_1 = \frac{1}{\sigma_1} Y_1, \quad \varepsilon_i = \frac{1}{\sigma} Y_i - \frac{\alpha}{\sigma} Y_{i-1}, \quad i > 1$$

"Direct formulation":

$$Y_i = \alpha^{i-1} \sigma_1 \varepsilon_1 + \sigma \sum_{j=2}^i \alpha^{i-j} \varepsilon_j$$

The "Inverse formulation" can model long range dependency with a sparse matrix (few non-zero elements).

Complexity inverse formulation, – solving $\mathbf{L}^{-1}\mathbf{Y} = \boldsymbol{\varepsilon}$: $\sim n$

Complexity direct formulation, – multiply $\mathbf{Y} = \mathbf{L}\boldsymbol{\varepsilon}$: $\sim n^2$