

Summary STK 4150/9150

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You are expected to know and be able to use basic concepts introduced in the book.

Your knowledge is expected to be larger than the content of the book, i.e.

You are supposed to be able to derive equations not directly written in the Book, but with similar complexity.

Course @ a slide

Prelim/Jan

- Statistics preliminaries (Chapter 2)
- Temporal processes (Chapter 3)
 - Deterministic models
 - Stochastic models
 - Spectral representation

January-March

- Spatial processes
 - Geostatistical processes, sec 4.1
 - Lattice processes, sec 4.2
 - Point processes, sec 4.3

March-May

- Spatio-temporal processes
 - Exploratory methods (Chapter 5)
 - Models (Chapter 6)
 - Hierarchical models (Chapters 7 and 8)
- Focus on
 - Modeling
 - Analysis in practice (using R)
 - Theoretical aspects

Data collected over time

- Past, present, future, change
- Temporal aspect important?

Two (separate) approaches to modelling

- Statistical
 - Variability through randomness
 - Learning dynamic structure from data
- Dynamic system theory
 - Typically deterministic

Denoted $\mathbf{Y}(\cdot)$ or $\{\mathbf{Y}(r) : r \in D_t\}$

- r time index
- $\mathbf{Y}(r)$ possibly multivariate, deterministic or stochastic
- $D_t \in \mathcal{R}^1$

D_t specify type of process

- Continuous time process: $D_t \in (-\infty, \infty)$ or $[0, \infty)$: $\mathbf{Y}(t)$
- Discrete time process: $D_t \in \mathcal{N}$ or \mathcal{N}^+ : \mathbf{Y}_t
- Point process: Random times
Example: Time of tornado. Mark: Severity of tornado

Continuous time:

- Measured discrete
- Modelled discrete?
- Dynamic system theory: Often modelled continuous (PDE's)

- Spatial correlation
 - Stationary
 - Isotropic/Anisotropic
 - Permutation test for independence (Morans I)
- Variogram
 - Link to covariance
 - Nugget effect
 - Sill
- Spatial prediction
 - Interpolation
 - Minimum Mean Squared Prediction Error (Kriging)
 - Prediction in a Gaussian model
- Kriging
 - Simple Kriging (known mean)
 - Bayesian Kriging (prior on mean)
 - Universal Kriging (unknown mean)
 - Ordinary Kriging (Special case of UK)

- General set up for "Kriging type problems"
 - Kriging case
 - General case
 - Change of support
- Spatial moving average models
 - Construction
 - Correlation function
- Computations in multigaussian settings
 - Conditional distribution
 - Deriving Mean and co-variance
 - Conditional simulation using Kriging equations

Hierarchical (statistical) models

Hierarchical model

| | Variable | Densities | Notation in book |
|----------------|--------------|------------------------------------|-----------------------------------|
| Data model: | \mathbf{Z} | $p(\mathbf{Z} \mathbf{Y}, \theta)$ | $[\mathbf{Z} \mathbf{Y}, \theta]$ |
| Process model: | \mathbf{Y} | $p(\mathbf{Y} \theta)$ | $[\mathbf{Y} \theta]$ |
| Parameter: | θ | | |

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Simultaneous model: $p(\mathbf{y}, \mathbf{z}|\theta) = p(\mathbf{z}|\mathbf{y}, \theta)p(\mathbf{y}|\theta)$

Marginal model: $L(\theta) = p(\mathbf{z}|\theta) = \int_{\mathbf{y}} p(\mathbf{z}, \mathbf{y}|\theta) d\mathbf{y}$

Inference: $\hat{\theta} = \operatorname{argmax}_{\theta} L(\theta)$

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Bayesian approach: Include model on θ

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| Data model: | \mathbf{Z} | $p(\mathbf{Z} \mathbf{Y}, \theta)$ | $[\mathbf{Z} \mathbf{Y}, \theta]$ | Simultaneous |
| Process model: | \mathbf{Y} | $p(\mathbf{Y} \theta)$ | $[\mathbf{Y} \theta]$ | |
| Parameter model: | θ | $p(\theta)$ | $[\theta]$ | |

model: $p(\mathbf{y}, \mathbf{z}, \theta)$

Marginal model: $p(\mathbf{z}) = \int_{\theta} \int_{\mathbf{y}} p(\mathbf{z}, \mathbf{y}|\theta) d\mathbf{y} d\theta$

Inference: $\hat{\theta} = \int_{\theta} \theta p(\theta|\mathbf{z}) d\theta$

- Linear parameters approach (for mean parameters)
 - Ordinary kriging
 - Universal Kriging
 - Bayesian Kriging
- Hyper parameters: Plug-in estimate/Empirical Bayes
- Hyper parameters: Bayesian approach
 - MCMC
 - Laplace approximation
 - INLA
- Non Gaussian observations
 - Monte Carlo
 - Laplace approximation
 - INLA

- AR(1) as lattice process
- MRF – Markov random field
 - Undirected graph (MRF)
 - Neighborhood
 - Clique
- Negpotential function
- Gibbs distribution
- Besag's lemma (conditional vs joint distribution)
- Hammersley- Clifford theorem (clique vs Neg potential function)
- Lattice models
 - Gaussian CAR
 - Precision matrices
 - Latent Gaussian process
 - Auto logistic model (Ising model)
 - Auto Poisson model
- Gaussian CAR
 - Relation to precision matrix
 - When is it well defined?

- Point process (random locations, random count, random marks)
- Density of a point process (given the count)
- Poisson process
 - Intensity
 - Homogeneous/ In homogeneous
- Other processes
 - Random intensity (Log Gaussian Cox Process)
 - Clustering (Parent-child, e.g. Neyman-Scott)
 - Repulsion (Markov point process, Strauss - Hard core process)
- Inference
 - Kernel estimate of intensity
 - L-function (K-function)
 - Edge effects

- Visualization
- Presentation of results
- Empirical Orthogonal functions
 $\mathbf{C}_Z = \mathbf{\Psi}\mathbf{\Lambda}^2\mathbf{\Psi}^T$, $\mathbf{\Lambda}^2 = \text{diag}\{\lambda_i^2\}$ $\mathbf{\Psi} = [\psi_1, \dots, \psi_m]$
 - Efficient computation
 - Estimation of space functions (time coefficients)
 - Estimation of time functions (space coefficients)
- Space-Time Index (STI) used for permutation test in time space dependency.

Spatio-temporal covariance functions

- Stationarity: spatio-temporal, Spatial, temporal
- Spatio-temporal - Kriging
- Seperable, additive , multiplicative correlation functions

Stochastic differential/difference equations

- Integro-difference equation models
- Using (partial) differential equations (e.g. Matern correlation)
- Diffusion-injection models (interpretation of terms)
- Blurring space: Hard in space-time Simple in Fourier domain
- Discretization

Time series of spatial processes

- AR(q) process in time
- Stationary transitions
- Stationary distributions
- Discretization in space as well gives Vector-AR

- Data in Process models
- Observation types
 - number of observations
 - Incidence matrix
 - Change of support
 - Multiple data sources
- Linear observations
- Kalman filter
- Kalman smoother
- nonlinear/non Gaussian
- Conditioning to nonlinear functions of a random field

Bayesian approach: Also include model for parameters

Methodology for inference in Hierarchical Dynamical Spatio-Temporal Models

- General Problem
- Sequential vs non sequential
- Kalman filter
- EM-algorithm
- MCMC
- Sequential Monte Carlo, particle filter
- INLA

- Exercises
- Boreal - data
- Potts model
- Scottish lip cancer
- Pacific SST
- Eurasian Dove