

① Rough Path Theory

1. Introduction

Basic literature:

1. Friz, P., Hairer, M.: A Course on Rough Paths. Springer (2014).
2. Lyons, T., Caruana, M., Lévy, T.: Differential Equations Driven by Rough Paths. LNM, Springer (2006).
3. Friz, P., Victoir, N.: Multidimensional Stochastic Processes as Rough Paths. Cambridge Univ. Press (2010).

The motivation of rough path theory initiated by T. Lyons in the mid-nineties comes from controlled differential equations of the form

$$Y_t = f(Y_t)X_t, Y_0 = \emptyset, \quad (1)$$

where X is the derivative of a given function X (driving signal), \emptyset the initial condition, f (smooth) function and Y the unknown.

More generally, if X is of finite 1 -variation (bounded variation), i.e.

if $\sup_{\mathcal{P}} \sum |X_{t_{i+1}} - X_{t_i}|^p < \infty \quad (2)$

for $p=1$, where the supremum is taken over all partitions \mathcal{P} of $[0, T]$, then we can recast (1) in integral form w.r.t. the Lebesgue-Stieltjes integral as

$$Y_t = \emptyset + \int_0^t f(Y_s) dX_s \quad (3)$$

However, in applications to physics, chemistry or finance (e.g. Y_t stock price at time t , X "market noise") the control or driving signal may not be

② smooth, but "rough" in the sense of Hölder continuity with exponent $0 < \alpha < 1$, that is

$$X \in C^\alpha([0, T]; \mathbb{R}^d) := \{g \in C([0, T]; \mathbb{R}^d) : \sup_{s \neq t} \frac{|g(s) - g(t)|}{|s-t|^\alpha} = \|g\|_\alpha\}$$

In this case, one needs to make sense of the integral term in (3) or more generally of the integral

$$\int_0^T z_s dX_s$$

for $X \in C^\alpha([0, T]; \mathbb{R}^d)$.

It turns out that this integral can be defined as a Young integral:

Theorem (Young 1936):

(i) Let $Z \in C^\beta([0, T]; \mathbb{R})$, $X \in C^\alpha([0, T]; \mathbb{R})$ with $0 < \alpha, \beta < 1$ and $\alpha + \beta > 1$. Then

$$\int_0^T z_s dX_s := \lim_{|\mathcal{P}| \rightarrow 0} \sum_{[s_i, t_i] \in \mathcal{P}} z_{s_i} (X_{t_i} - X_{s_i}) \quad (4)$$

converges, where $|\mathcal{P}|$ is the mesh of the partition \mathcal{P} of $[0, T]$.

The resulting bilinear map $(X, Z) \mapsto \int_0^T z_s dX_s$ is continuous, that is

$$|\int_0^T z_s dX_s| \leq C_{\alpha+\beta} (|Z|_1) \cdot \|Z\|_\beta \cdot \|X\|_\alpha$$

(ii) If $\alpha + \beta \leq 1$, then there exist $Z \in C^\beta([0, T]; \mathbb{R})$, $X \in C^\alpha([0, T]; \mathbb{R})$ such that (4) does not converge (i.e. different sequences of partitions yield different limits or none at all).

If $X \in C^\alpha([0, T]; \mathbb{R}^m)$ with $\alpha > \frac{1}{2}$ and $f \in C_b^2(\mathbb{R}^d; \mathbb{R}^{dxm})$ (space of twice cont. diff. $g: \mathbb{R}^d \rightarrow \mathbb{R}^{dxm}$ with bounded part. derivatives), one shows by using the Picard iteration scheme that there is a unique solution Y to (3) or equivalently

$$dY_t = f(Y_t) dX_t, Y_0 = \{ \in \mathbb{R}^d$$

③ Although the concept of the Young integral is useful, it is still too restrictive in many applications : E.g. in math. finance X could be a path of a Brownian motion ($t \mapsto B_t(\omega)$), i.e. a continuous process, starting in zero with independent and stationary increments on some probability space (Ω, \mathcal{A}, P) . Here

$$\int_0^t Z_s(\omega) dB_s(\omega) \quad (5)$$

may represent the value of a portfolio of stocks at time t w.r.t. a (admissible) hedging strategy process $Z_s(\omega)$, $0 \leq s \leq t$, $\omega \in \Omega$.

It is known that

$$(t \mapsto B_t(\omega)) \in C^{1-\epsilon}([0, T]) \quad P\text{-a.e.}$$

for all $\epsilon \in (0, \frac{1}{2})$.

However, paths of Z are in general not in $C^{\beta}([0, T])$

→ definition of (5) in the sense of Young may fail

→ solution : Ito-integral (K. Ito 1944) :

$$\int_0^T Z_s dB_s = \lim_{|\Delta| \rightarrow 0} \sum_{[u, v]} Z_u (B_v - B_u) \quad (6)$$

in probability for processes Z (with right continuous paths having existing left limits), which are adapted (i.e. $Z_s \delta((B_u)_{0 \leq u \leq s})$)-measurable for all s

This concept relies on the martingale property of B and can be even extended to semi-martingales X :

$$X_t = X_0 + A_t + M_t$$

↑ bounded (local)
variation martingale
process

④ → Itô integration quite general integration concept
 → problem: may not be general enough (in applications):
 E.g. recent empirical observations in finance suggest the stoch. modeling of volatilities of stock prices by means of integral processes w.r.t. a fractional Brownian motion B^H for Hurst parameters $H \leq \frac{1}{2}$, which is not a semi-martingale.

Definition (fract. Bm)

Let $0 < H < 1$. The fractional Brownian motion with Hurst parameter H is a continuous Gaussian process B^H on $[0, T]$ with $B_0^H = 0$, $E[B_t^H] = 0$ and

$$E[B_t^H \cdot B_s^H] = \frac{1}{2} (t^{2H} + s^{2H} - |t-s|^{2H})$$

→ (i) B^H for $H = \frac{1}{2}$ standard Brownian motion

(ii) paths of B^H are α -Hölder-continuous for all $\alpha < H$ with probability 1

(iii) B^H is not a semi-martingale for $H \neq \frac{1}{2}$

→ concept of Itô-integration fails

→ crucial objective in rough path theory:

Definition of a rough path integral

$$\int_0^T z_s dX_s$$

for "rough" driving signals X in \mathbb{R}^d (i.e. $X \in C^\alpha$ for $\alpha \leq \frac{1}{2}$ as e.g. $X = B^H$ for $H \leq \frac{1}{2}$) and "rough" integrands $z \in C^\alpha$, $\alpha \leq \frac{1}{2}$)

→ integration concept, which is path by path in contrast to Itô integration and which is not within the framework of Young integration

⑤ What is this type of integration theory good for?

→ It allows e.g. for the study of the following problems:

1. Pathwise (i.e. deterministic) study of stochastic differential equations (SDE's): To explain this consider the $\mathbb{S}t\hat{o}$ -SDE

$$Y_t = \beta + \int_0^t f(Y_s) dB_s, \beta \in \mathbb{R}^d \quad (7)$$

If f is Lipschitz continuous, Picard iteration gives a unique adapted solution $Y = \Phi(B) = \Phi_{f,\beta}(B)$

→ map Φ ($\mathbb{S}t\hat{o}$ -map) defined on the path space is measurable, but not continuous in general

→ Example (discont. Φ):

$$\Phi(B) = \left(\int_0^t B^{(i)}(s) dB^{(j)}(s) \right) \quad (8) \quad (B^{(i)}, B^{(j)} \text{ 1-dim b.m.})$$

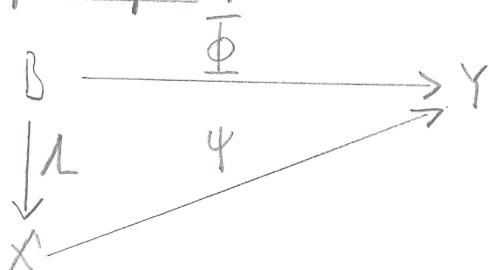
as the solution to the 2-dim. SDE

$$Y_t^{(1)} = B_t^{(1)} + \int_0^t Y_s^{(1)} dB_s^{(2)}$$

See e.g. T. Lyons 1991

However the integrals in (8) contain all information to obtain the following continuity result!

Rough path principle:



where

$$X = (B, \left(\int_0^t B^{(i)}(s) dB^{(j)}(s) \right)_{i,j}) \quad (\text{"enhanced rough path"})$$

and where

⑥ Ψ is the Sto-Lyons map, which is continuous
 (in the rough path topology)
 \rightarrow This striking fact allows a path by path
 analysis of SDE's

2. Deterministic study of (non-linear) stochastic partial differential equations (SPDE's) :

E.g. study of the Kardar-Parisi-Zhang (KPZ) equation

$$\partial_t h = \partial_x^2 h + (\partial_x h)^2 - C + \{\leftarrow \text{space-time white noise} \quad (9)$$

(as a model in e.g. the field of interacting particle systems) in the framework of a unifying theory of rough paths ("regularity structures")

3. Stochastic regularization : To explain this, consider e.g. the deterministic transport equation:

$$\frac{\partial u}{\partial t} + (b \cdot \nabla)^{\text{gradient}} u = 0, \quad u|_{t=0} = u_0 \quad (10)$$

for a given vector field $b: [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^d$, an initial condition $u_0: \mathbb{R}^d \rightarrow \mathbb{R}$ and the unknown scalar field $u: [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}$

If b is not a Lipschitz function, then uniqueness or even existence of solutions to (10) may fail!

In order to restore well-posedness of (10) in the sense of uniqueness, existence and regularity of solutions one may "regularize" (10) by adding a noise $\{\}_t$ to it:

$$du + (b \cdot \nabla) u dt + d\{\}_t = 0, \quad u|_{t=0} = u_0, \quad (11)$$

where e.g.

$$d\{\}_t = \sum_{i=1}^d \partial_{x_i} u \circ dB_t^{(i), H} \iff \{\}_t = \sum_{i=1}^d \int_0^t \partial_{x_i} u \circ dB_s^{(i), H}$$

- ⑦ for indep. fract. 1-dim. Bm's $B^{(i)H}$, $i=1, \dots, d$
 with Hurst parameter $H \in (0, \frac{1}{2}]$
 Here $odB_s^{(i)H}$ stands for a Stratonovich type of integration w.r.t. $B^{(i)H}$ (see later)
- If e.g. $H = \frac{1}{2}, b$ is bounded and measurable, no smooth (or in C_b^1) then (II) has a unique Sobolev differentiable (weak) solution process to (II).
- Related equations to (II) are e.g. stochastic continuity equations with even C^K -solutions under mild conditions on the coefficients (see later)

4. Generalization and simplification of proofs of central results in stochastic analysis:

E.g. Hörmander's theorem in the case of fBm $B^H, H \in [\frac{1}{2}, 1]$:

Consider the SDE

$$dX_t = V_0(X_t)dt + \sum_{i=1}^m V_i(X_t) \overset{\text{Stratonovich integration}}{\circ} dB_t^{(i)H}, X_0 = y \in \mathbb{R}^m,$$

where $B_t^H = (B_t^{(1)H}, \dots, B_t^{(m)H})^T$ transposed
 (space of inf. diff. funct. with bounded partial derivatives of all orders)

Define

$$[V, W](x) := D\overset{\text{derivative of } V}{V}(x) \cdot W(x) - D\overset{\text{derivative of } W}{W}(x) \cdot V(x) \quad (\text{Lie bracket})$$

for cont. diff. $V, W: \mathbb{R}^d \rightarrow \mathbb{R}^d$

Assume Hörmander's condition: For all $x \in \mathbb{R}^d$ the vectors

$V_{j0}(x), [V_{j0}, V_{j1}](x), [[V_{j0}, V_{j1}], V_{j2}](x), \dots, 0 \leq j_0, j_1, \dots, j_m \leq m$
 span \mathbb{R}^d .

Then X_t has a probability density w.r.t. the Lebesgue meas. for all $t > 0$

If $H = \frac{1}{2}$ (i.e. the case of Bm) then this density is smooth
 → can be used to construct smooth fundamental solutions to the Cauchy problem:

$$\textcircled{8} \quad \begin{cases} \frac{\partial u}{\partial t}(t, x) = \Delta u(t, x), t > 0, x \in \mathbb{R}^d \\ u(t, \cdot) \rightarrow f \text{ as } t \rightarrow 0 \end{cases}$$

where $Dg = \sum_{i,j=1}^d \beta_{ij}(x) \frac{\partial^2 g(x)}{\partial x_i \partial x_j} + \sum_{i=1}^d b_i(x) \frac{\partial g(x)}{\partial x_i}$

5. Applications to machine learning, statistics and finance

Course programme:

We aim at discussing e.g. the following topics

1. Integration of controlled rough paths
2. Doob-Meyer type decomposition for rough paths
3. Itô's formula for rough paths and applications
4. SDE's driven by rough paths
 - (i) Continuity of the Itô-Lyons map
 - (ii) Flows of rough path driven SDE's
 - (iii) Wong-Zakai theorem
 - (iv) Hörmander's theorem
5. SPDE's driven by rough paths
6. Regularity structures with applications (e.g. KPZ equation)

⑨ 2. The space of rough paths

Motivation: Consider the diff. eq.

$$Y_t = z + \int_0^t F(Y_u) dX_u \quad (2.1)$$

$\stackrel{0}{=} (F_{ij}(Y_u))_{ij}$

for smooth F and $X = (X^{(1)}, \dots, X^{(d)})$

$$\Rightarrow Y_t^{(i)} = z^{(i)} + \sum_{j=1}^d \int_0^t F_{ij}(Y_u) dX_u^{(j)}, \quad i=1, \dots, m$$

→ first-order Euler approximation:

$$Y_t^{(i)} - Y_s^{(i)} \approx \sum_{j=1}^d F_{ij}(Y_s) \int_s^t dX_u^{(j)}, \quad i=1, \dots, m \quad (2.2)$$

Then Taylor's expansion applied to (2.1) gives

a 2-step Euler approximation:

$$Y_t^{(i)} - Y_s^{(i)} = \sum_{j=1}^d F_{ij}(Y_s) \int_s^t dX_u^{(j)} \\ + \sum_{j=1}^d \int_s^t (F_{ij}(Y_u) - F_{ij}(Y_s)) dX_u^{(j)}$$

$$\stackrel{\text{Taylor}}{\approx} \sum_{j=1}^d F_{ij}(Y_s) \int_s^t dX_u^{(j)}$$

$$+ \sum_{j,k=1}^d \sum_{\ell=1}^m \frac{\partial}{\partial x_\ell} F_{ij}(Y_s) F_{\ell k}(Y_s) \int_s^t \int_s^u dX_r^{(k)} dX_u^{(i)}, \quad (2.3)$$

$i=1, \dots, m$ for small $|t-s|$

→ the approximation (2.3) suggests that
in addition to

$$\left(\int_s^t dX_u^{(j)} \right)_{j=1, \dots, d}$$

also the information contained in

$$\textcircled{10} \quad \left(\sum_s^t \sum_u^u dX_r^{(K)} dX_u^{(j)} \right)_{K,j=1,\dots,d} \quad (2.4)$$

or equivalently in tensor notation form

$$\sum_s^t (X_u - X_s) \otimes dX_u \quad (2.5)$$

may play a crucial role in the definitions of the integral

$$\int F(Y_u) dX_u$$

w.r.t. to rough paths X or more generally of integrals of the form

$$\int Z_u dX_u$$

for controlled rough paths Z as integrands (see later)

Since rough path theory is also valid for paths X with values in inf. dim. spaces, we shall recall here (in view of applications later on) tensor products of Banach spaces w.r.t. the projective tensor norm:

Def. 2.1 (alg. tensor product)

Let V, W be vector spaces over \mathbb{R} . Set $S = V \times W$

Define the vector space F by

$$F := \left\{ f: S \rightarrow \mathbb{R} : f(i) \neq 0 \text{ for at most finitely many } i \right\}$$

Define $1_i \in F$ by

$$1_i(j) = \begin{cases} 1 & \text{if } j=i \\ 0 & \text{else} \end{cases}$$

(consider the subspace U of F spanned by the vectors

$$1_{(v_1, w_1 + w_2)} - 1_{(v_1, w_1)} - 1_{(v_1, w_2)}$$

$$1_{(v_1 + v_2, w)} - 1_{(v_1, w)} - 1_{(v_2, w)}$$

$$1_{(2v, w)} - 21_{(v, w)}$$

⑩

$$1_{(v_1, w)} = \lambda 1_{(v, w)}$$

for $v_i \in V, w_i \in W, i=1, 2, \lambda \in \mathbb{R}$

Then the tensor product of V and W denoted by $V \otimes W$
is defined as

$$V \otimes W = F/U$$

$$(= \{f+U : f \in F\}, (f_1+U) + (f_2+U) := f_1 + f_2 + U$$

$$\lambda(f+U) := (\lambda f) + U, f+U := \{f+U : u \in U\}$$

Rem. : (i) $v \in V, w \in W \rightarrow v \otimes w := 1_{(v, w)} + U$

→ $V \otimes W$ linear in V and W

(ii) $(e_i)_{i \in I_1}, (e'_j)_{j \in J_2}$ bases of V, W , resp.

→ $(e_i \otimes e'_j)_{i \in I_1, j \in J_2}$ basis of $V \otimes W$

Consider now a Banach space V with norm $\|\cdot\|_1$,

that is a complete vector space w.r.t. $\|\cdot\|_1$ (i.e.

$$\|x_n - x_m\|_1 \xrightarrow[n, m \rightarrow \infty]{} 0 \Rightarrow \text{there is } a x \in V : \|x_n - x\|_1 \xrightarrow[n \rightarrow \infty]{} 0$$

Let W another Banach space w.r.t. to the norm $\|\cdot\|_2$

Consider $Z := V \otimes W$ as in Def. 2.1 and define

the norm $\|\cdot\|$ (projective norm) on Z by

$$\|u\| := \inf \left\{ \sum_{i=1}^n \|v_i\|_1 \|w_i\|_2 : u = \sum_{i=1}^n v_i \otimes w_i \right\} \quad (2.6)$$

Denote by \hat{Z} the Banach space given by

the completion of Z w.r.t. $\|\cdot\|$ (which we also

denote by $V \otimes W$ from now on by convenience)

Then one shows that

$$\|v \otimes w\| = \|v\|_1 \cdot \|w\|_2 \quad (2.7)$$

for all $v \in V, w \in W$.

(12) Let F be another Banach space w.r.t. the norm $\|\cdot\|_3$.
 Now let $A : V \times W \rightarrow F$ be a bounded bilinear map, i.e.

$$(i) \quad A(v_1 + v_2, w) = A(v_1, w) + A(v_2, w), \quad A(2v, w) = 2A(v, w)$$

$$|| \qquad \qquad || \qquad \qquad , \quad A(v, 2w) = 2A(v, w)$$

((i)) A bounded, i.e.:

$$|A| := \sup_{v \neq 0, w \neq 0} \frac{\|A(v, w)\|_3}{\|v\|_1 \cdot \|w\|_2} < \infty \quad (2.8)$$

Denote by $L(V \times W; F)$ the space of all such maps A
 $\longrightarrow Q := L(V \times W, F)$ Banach space with norm $|A|$

Further, we also denote for another Banach space R with norm $\|\cdot\|_R$ by

$$L(R, F)$$

the space of linear maps $B : R \rightarrow F$ which are bounded, i.e.

$$|B|_* := \sup_{r \neq 0} \frac{\|B(r)\|_3}{\|r\|_R} < \infty \quad (2.9)$$

$\longrightarrow E := L(R, F)$ Banach space with norm $|B|_*$

\longrightarrow Theorem 2.2 (Lifting theorem)

Let $A \in L(V \times W, F)$ and $R := V \otimes W$ with projective norm $\|\cdot\|$. Then there exists a unique $B \in L(R, F)$ such that

$$A(v, w) = B(v \otimes w) \quad \text{for all } v \in V, w \in W$$

Furthermore

$$|A| = |B|_* \quad (2.10)$$

(isometry)

Rem. 2.3. So the linear map $A \mapsto B$

is one-to-one onto $L(R, F)$ and distance preserving in the sense of the isometry (2.10)

$$\longrightarrow L(V \times W, F) \cong L(V \otimes W, F)$$

⑬ \rightarrow any (bounded) bilinear map can be turned into a (bounded) linear map

Example 2.4 : $V = \mathbb{R}^d$, $W = \mathbb{R}^m$ with norms

$$\|v\|_1 = (\sqrt{v_1^2 + \dots + v_d^2})^{1/2}, v = (v_1, \dots, v_d),$$

$$\|w\|_2 = (\sqrt{w_1^2 + \dots + w_m^2})^{1/2}, w = (w_1, \dots, w_m)$$

$$\rightarrow \|v \otimes w\| = \|v\|_1 \cdot \|w\|_2 \text{ and}$$

matrix norm $v \otimes w$ can be identified with

$$v \cdot w^T \stackrel{\text{transposed}}{=} (v_i \cdot w_j)_{1 \leq i \leq d, 1 \leq j \leq m} = \begin{pmatrix} v_1 w_1, \dots, v_1 w_m \\ \vdots \\ v_d w_1, \dots, v_d w_m \end{pmatrix}$$

So $\mathbb{R}^d \otimes \mathbb{R}^m$ can be identified with $\mathbb{R}^{d \times m}$

Consider now $V = \mathbb{R}^d$ and a smooth path

$$X : [0, T] \rightarrow V \text{ with } X_t = (X_t^{(1)}, \dots, X_t^{(d)}).$$

Then

$$(X_u - X_s) \otimes (X_t - X_u) \stackrel{\text{Ex. 2.4}}{=} ((X_u^{(i)} - X_s^{(i)}) \cdot (X_t^{(j)} - X_u^{(j)}))_{1 \leq i, j \leq d} \quad (2.11)$$

Let $s \leq u \leq t$. Then integration by parts gives

$$\begin{aligned} (X_u^{(i)} - X_s^{(i)}) (X_t^{(j)} - X_u^{(j)}) &= \int_0^T \mathbf{1}_{[s, u]}(r) dX_r^{(i)} \cdot \int_0^T \mathbf{1}_{[u, t]}(r) dX_r^{(j)} \\ &= \underbrace{\int_0^T \int_0^T \mathbf{1}_{[s, u]}(r) dX_r^{(i)} \mathbf{1}_{[u, t]}(\tau) dX_\tau^{(j)}}_{=0} \\ &\quad + \underbrace{\int_0^T \int_0^T \mathbf{1}_{[u, t]}(r) dX_r^{(j)} \mathbf{1}_{[s, u]}(\tau) dX_\tau^{(i)}}_{=0} \\ &= \int_u^t (X_u^{(i)} - X_s^{(i)}) dX_r^{(j)} \\ &\quad =: X_{s, u}^{(i)} \end{aligned} \quad (2.12)$$

On the other hand, we have that

$$\begin{aligned} &\underbrace{\int_s^t X_{s, r}^{(i)} dX_r^{(j)} - \int_s^u X_{s, r}^{(i)} dX_r^{(j)}}_{= \int_u^t X_{s, r}^{(i)} dX_r^{(j)}} - \int_s^t X_{u, r}^{(i)} dX_r^{(j)} \\ &= \int_u^t (X_{s, r}^{(i)} - X_{u, r}^{(i)}) dX_r^{(j)} = \int_u^t (X_u^{(i)} - X_s^{(i)}) dX_r^{(j)} \end{aligned} \quad (2.13)$$

(14)

Define the matrices

$$M_{\ell,r} = \left(\int_0^r X_{\ell,t}^{(i)} dX_r^{(j)} \right)_{1 \leq i,j \leq d} \in \mathbb{R}^{d \times d}$$

(2.11), (2.12)
(2.13)

$$M_{s,t} - M_{s,u} - M_{u,t} = X_{s,u} \otimes X_{u,t}, \quad (2.14)$$

where

$$X_{\ell,r} := X_r - X_\ell \quad (2.15)$$

Assume now that a sequence of smooth paths $X^{(n)}$ approximates a rough path X . Then one may expect that

$$X_{s,u}^{(n)} \otimes X_{u,t}^{(n)} \xrightarrow{n \rightarrow \infty} X_{s,u} \otimes X_{u,t} \quad (2.16)$$

and

$$M_{s,t}^{(n)} - M_{s,u}^{(n)} - M_{u,t}^{(n)} \xrightarrow{n \rightarrow \infty} X_{s,t} - X_{s,u} - X_{u,t} \quad (2.17)$$

for a (continuous) function $\mathbb{X} : [0,T] \times [0,T] \rightarrow \mathbb{R}^{d \times d}$

(2.14), (2.16), (2.17) a Hölder continuous rough path $X : [0,T] \rightarrow V$ should satisfy the following condition (which also reflects the additivity property of integrals):
Chen's relation:

$$\mathbb{X}_{s,t} - \mathbb{X}_{s,u} - \mathbb{X}_{u,t} = X_{s,u} \otimes X_{u,t}, \quad s, u, t \in [0,T] \quad (2.18)$$

for a continuous function $\mathbb{X} : [0,T] \times [0,T] \rightarrow V \otimes V$ In view of (2.16) and (2.17) we denote $\mathbb{X}_{s,t}$ by

$$\int_s^t X_{s,r} \otimes dX_r$$

Rem. 2.5 :(i) $s=u=t$ in (2.18) $\rightarrow \mathbb{X}_{t,t} = \emptyset$ (ii) \mathbb{X} is determined up to an increment of a cont. function $F : [0,T] \rightarrow V \otimes V$:With $\mathbb{X}_{\ell,r}$ also $\mathbb{X}_{\ell,r} + F_r - F_\ell$ satisfies (2.18)

On the other hand:

(15) If X, \bar{X} satisfy (2.18), then it follows from (2.18) that

$$G_{S,t} = G_{0,t} + G_{S,0}$$

$$\text{for } G_{S,t} := X_{S,t} - \bar{X}_{S,t}$$

$$\xrightarrow{s=0} G_{0,t} = \underline{G}_{0,t} - \overline{G}_{0,t}$$

(ii) Using Itô's formula w.r.t. the Brownian motion $B = (B^{(1)}, \dots, B^{(d)})$, one shows (2.18) for $\bar{X}_{S,t} = \left(\int_s^t (B_r^{(i)} - B_s^{(i)}) dB_r^{(i)} \right)$

Itô-formula: $f(B_t) = f(0) + \sum_{i=1}^d \int_0^t \frac{\partial}{\partial x_i} f(B_s) dB_s^{(i)} + \sum_{i=1}^d \int_0^t \frac{\partial^2}{\partial x_i^2} f(B_s) ds$ (2.19)

$$\xrightarrow{d=1, f(x)=\frac{1}{2}x^2} \int_s^t (B_r - B_s) dB_r = \frac{1}{2} (B_t - B_s)^2 - \frac{1}{2} (t-s) = \bar{X}_{S,t} \text{ for } d=1 \quad (*)$$

$$B \in C^k([0, T]; \mathbb{R}) \text{ for all } k < \frac{1}{2}$$

$$\xrightarrow{(*)} \sup_{S \neq t} \frac{|\bar{X}_{S,t}|}{|t-s|^{2k}} < \infty \text{ with prob. 1}$$

→ suggests the following def. of a rough path space:

Def. 2.6 (Rough path space)

Let $\alpha \in (\frac{1}{2}, \frac{1}{2}]$. Then the space of α -Hölder rough paths denoted by $\mathcal{C}^\alpha([0, T], V)$ is the collection of all $Z := (X, \bar{X})$ satisfying (2.18) and

$$\|X\|_\alpha := \sup_{S \neq t} \frac{|X_{S,t}|}{|t-s|^\alpha} < \infty, \quad \|\bar{X}\|_{2\alpha} := \sup_{S \neq t} \frac{|\bar{X}_{S,t}|}{|t-s|^{2\alpha}} < \infty$$

Rem 2.7:

(i) $\mathcal{C}^\alpha([0, T], V)$ is not a vector space

(ii) $\mathcal{C}^\alpha([0, T], V)$ becomes a complete metric space with metric s_α given by

distance between Z_1 and Z_2 → $s_\alpha(Z_1, Z_2) \stackrel{\text{def.}}{=} |X_0 - Y_0| + \|X - Y\|_\alpha + \|\bar{X} - \bar{Y}\|_{2\alpha}$

$$\text{for } Z_1 = (X, \bar{X}), Z_2 = (Y, \bar{Y}) \in \mathcal{C}^\alpha([0, T], V)$$

→ deficiency of Chen's relation:

It captures the basic property of additivity of

(16) integrals, but not integration by parts as e.g.
in the case of smooth paths:

Let $V = \mathbb{R}^d$ and $X = (X^{(1)}, \dots, X^{(d)})$ be a smooth path

$$\xrightarrow[\text{by parts}]{\text{integration}} X_{s,t}^{(i)} X_{s,t}^{(j)} = (X_t^{(i)} - X_s^{(i)}) \cdot (X_t^{(j)} - X_s^{(j)}) \quad \cancel{X_{s,t}^{(ij)}} \\ = \int_s^t (X_r^{(i)} - X_s^{(i)}) dX_r^{(j)} + \int_s^t (X_r^{(j)} - X_s^{(j)}) dX_r^{(i)} \\ \quad s = X_{s,r}^{(i)} \quad \quad \quad s = X_{s,r}^{(j)}$$

Now choosing a sequence of smooth $X^{(n)}$ approximating a rough path X (in some reasonable sense) we can argue just as in (2.16) and (2.17) and postulate that

$$X_{s,t}^{(i,j)} + X_{s,t}^{(j,i)} = X_{s,t}^{(i)} X_{s,t}^{(j)}, \quad 1 \leq i, j \leq d, \quad s, t \in [0, T]$$

or equivalently

$$\text{Sym}(X_{s,t}) = \frac{1}{2} X_{s,t} \otimes X_{s,t}, \quad s, t \in [0, T] \quad (2.20)$$

holds for a continuous function $\mathbb{X}: [0, T] \times [0, T] \rightarrow V \otimes V$,

$$\text{Sym}(A) \stackrel{\text{def. } \in \mathbb{R}^{\text{diag}}}{=} \frac{1}{2} (A + A^T)^{\text{transposed}}$$

Rem. 2.8: Using Itô's formula (2.19) we find that

$$X_{s,t} \stackrel{\text{def. }}{=} B_{s,t}^{\text{stat}} \stackrel{\text{def. }}{=} \left(\int_s^t (B_r^{(i)} - B_s^{(i)}) \text{od } B_r^{(j)} \right)_{1 \leq i, j \leq d}$$

satisfies (2.18) and (2.20), where

$$\int_s^t (B_r^{(i)} - B_s^{(i)}) \text{od } B_r^{(j)} \stackrel{\text{def. }}{=} \int_s^t (B_r^{(i)} - B_s^{(i)}) d B_r^{(j)} + \frac{1}{2} (t-s) \circledast_{ij} \stackrel{\{1, if i=j\}}{=} \stackrel{\{\text{else}\}}{=}$$

is a Stratonovich integral and $B = (B^{(1)}, \dots, B^{(d)})$ a Bm

→ space of geometric rough paths $\mathcal{E}_g^d \subset \mathcal{E}^d$

Def. 2.9 (Geometric rough paths)

Let $d \in \{\frac{1}{2}, 1, 2\}$. The space of geometric rough paths, denoted by \mathcal{E}_g^d , is defined as the set of all $(X, \mathbb{X}) \in \mathcal{E}^d$ satisfying in addition to (2.18) the relation (2.20).

Rem: $\mathcal{E}_g^d \subset \mathcal{E}^d$ closed subspace w.r.t. the metric S_d

(17)

→ interpretation of rough paths as paths with values in Lie groups:

Let $V = \mathbb{R}^d$ and $(X, \dot{X}) \in \mathcal{C}^k([0, T], V)$. Then

$$\begin{aligned}\mathbb{X}_{s,t} &:= (1, X_{s,t}, \dot{X}_{s,t}) \in \sum_{i=0}^N (\overset{\circ}{\otimes} V) = \mathbb{R} \times V \times (V \otimes V) = \\ &= \mathbb{R} \times \mathbb{R}^d \times \mathbb{R}^{d \times d} =: T^{(2)}(\mathbb{R}^d) = T^{(N)}(V) \quad (2.21)\end{aligned}$$

for $N=2$ ($\overset{\circ}{\otimes}_{j=0}^N V \stackrel{\text{def}}{=} \mathbb{R}$)

→ $T^{(2)}(\mathbb{R}^d) = T^{(N)}(\mathbb{R}^d)$ is a vector space over \mathbb{R}

If $g = (g_0 \in \mathbb{R}, g_1 \in \mathbb{R}^d, g_2 \in \mathbb{R}^{d \times d})$, $h = (h_0, h_1, h_2) \in T^{(2)}(\mathbb{R}^d)$,

define multiplication \otimes of g and h by

$$g \otimes h \stackrel{\text{def}}{=} \sum_{K=0}^N \left(\sum_{i=0}^K g_{K-i} \otimes h_i \right) \quad (2.22)$$

$$\stackrel{N=2}{=} (g_0 \cdot h_0, h_0 \cdot g_1 + g_0 \cdot h_1, h_0 \cdot g_2 + g_1 \otimes h_1 + g_0 \cdot h_2)$$

Recall: $x \otimes y = x \cdot y T$, $x, y \in \mathbb{R}^d$

→ map A given by $A(g, h) = g \otimes h$, $g, h \in T^{(2)}(\mathbb{R}^d)$ is bilinear and the multiplication is associative:

$$(a \otimes b) \otimes c = a \otimes (b \otimes c) \text{ for all } a, b, c \in T^{(2)}(\mathbb{R}^d)$$

⇒ $T^{(2)}(\mathbb{R}^d) = T^{(N)}(\mathbb{R}^d)$ becomes an associative algebra under \otimes , called truncated tensor algebra of level $N=2$

$$\begin{aligned}\text{Ex. 2.10: } \mathbb{X}_{s,u} \otimes \mathbb{X}_{u,t} &\stackrel{(2.22)}{=} (1, \underset{= X_{s,t}}{\underset{\substack{X_u - X_s \\ X_{s,u} + X_{u,t}}} \overbrace{X_{s,u} + X_{u,t}}}, \underset{\substack{X_{s,u} \otimes X_{u,t} + X_{u,t}}} \overbrace{X_{s,u} \otimes X_{u,t} + X_{u,t}}) \\ &= \mathbb{X}_{s,t}\end{aligned}$$

Now define

$$T_a^{(2)}(\mathbb{R}^d) \stackrel{N=2}{=} T_a^{(N)}(\mathbb{R}^d) := \left\{ \left(\overset{\circ}{\otimes} \overset{\circ}{\otimes} \overset{\circ}{\otimes} V \right)^{\otimes N} : g_0 = a \right\} \quad (2.23)$$

In fact for $a = 1$, $T_1^{(2)}(\mathbb{R}^d)$ is a group

w.r.t. \otimes with unit element $(1, 0, 0)$, since e.g.

⑧ if $g = (1, g_1, g_2) \in T_1^{(2)}(\mathbb{R}^d)$, then the inverse of g is

$$g^{-1} = \sum_{K=0}^N (-1)^K \left(\bigotimes_{i=0}^K g \right) = (1, -g_1, -g_2 + g_1 \otimes g_2) \quad (2.24)$$

for $N=2$, $g = (0, g_1, g_2)$, i.e.

$$g \otimes g^{-1} = (1, g_1, g_2) \otimes (1, -g_1, -g_2 + g_1 \otimes g_2) = (1, 0, 0)$$

Further, $T_1^{(2)}(\mathbb{R}^d) = T_1^{(N)}(\mathbb{R}^d)$ is a Lie group, that is a smooth manifold M , which is a group w.r.t. \cdot such that the maps

$$\text{and } \begin{aligned} (x, y) &\mapsto x \cdot y \\ x &\mapsto x^{-1} \end{aligned} \quad (2.25)$$

are smooth.

→ here: $M = T_1^{(2)}(\mathbb{R}^d)$ ($\cong \mathbb{R}^{d+d^2}$) and $\cdot = \otimes$
 (take the chart $(T_1^{(2)}(\mathbb{R}^d), \varphi)$ with
 $\varphi(1, g_1, g_2) = (g_1, g_2) \in \mathbb{R}^{d+d^2}$)

Ex. 2.10 $\Rightarrow \mathbb{X}_{u,t} = \mathbb{X}_{s,u}^{-1} \otimes \mathbb{X}_{s,t} \stackrel{s \circ o}{\Rightarrow} \mathbb{X}_{u,t} = \mathbb{X}_{0,u}^{-1} \otimes \mathbb{X}_{0,t}$

Similarly to the classical we can introduce an exponential function

$$\text{Exp}: T_0^{(N)}(\mathbb{R}^d) \longrightarrow T_1^{(N)}(\mathbb{R}^d) \text{ by} \quad (2.26)$$

$$\text{Exp}(g) \stackrel{\text{def.}}{=} 1 + \sum_{K=1}^N \frac{1}{K!} g \otimes K \text{ with } g \otimes K \stackrel{\text{def.}}{=} \bigotimes_{i=1}^K g$$

and

a logarithmic function

$$\text{Log}: T_1^{(N)}(\mathbb{R}^d) \longrightarrow T_0^{(N)}(\mathbb{R}^d) \text{ by} \quad (2.27)$$

$$\text{Log}(h) \stackrel{\text{def.}}{=} \sum_{K=1}^N \frac{(-1)^{K+1}}{K} \tilde{h} \otimes K \text{ with } \tilde{h} = (0, h_1, \dots, h_N)$$

$$\text{for } h = (1, h_1, \dots, h_N)$$

for $N=2$

A direct calculation shows that

$$\text{Exp}(\text{Log}(h)) = h \text{ and } \text{Log}(\text{Exp}(g)) = g \quad (2.28)$$

$$\textcircled{9} \Rightarrow T_1^{(N)}(\mathbb{R}^d) = \text{Exp}[T_0^{(N)}(\mathbb{R}^d)]$$

However : $\text{Exp}(a+b) \neq \text{Exp}(a) \otimes \text{Exp}(b)$ in general

But for $N=2$ we find that

$$\begin{aligned} \text{Exp}(a) \otimes \text{Exp}(b) &\stackrel{\text{def.}}{=} (1+a+a^{\otimes 2}) \otimes (1+b+\frac{b^{\otimes 2}}{2}) \\ &= 1+a+b+\frac{1}{2}(a \otimes b - b \otimes a) + \frac{(a+b)^{\otimes 2}}{2} \\ &= \text{Exp}(a+b+\frac{1}{2}[a,b]), \end{aligned} \quad (2.29)$$

where

$$[a,b] \stackrel{\text{def.}}{=} a \otimes b - b \otimes a$$

is a Lie bracket on $T_0^{(N)}(\mathbb{R}^d)$

→ $T_0^{(N)}(\mathbb{R}^d)$ is a Lie algebra, that is it is (2.30)
a vector space U with a bilinear map
 $[\cdot, \cdot] : U \times U \rightarrow U$ satisfying the conditions

$$(i) [g,h] = -[h,g], \quad g,h \in U \quad (\text{anticommutativity (aw)})$$

$$(ii) [g,[h,k]] + [h,[k,g]] + [k,[g,h]] = 0, \quad g,h,k \in U \quad (\text{Jacobi identity})$$

In fact, one can generalize (2.29) and gets for $N > 2$

Th. 2.11 (Campbell-Baker-Hausdorff)

$$\text{Log}(\text{Exp}(a) \otimes \text{Exp}(b)) = b + \sum_{n=0}^N \frac{(-1)^n}{n+1} e^{t \text{ada}}(e^{t \text{adb}}(a)) dt,$$

where

$\text{ada} : T_0^{(N)}(\mathbb{R}^d) \rightarrow T_0^{(N)}(\mathbb{R}^d)$ defined by

$$(\text{ada})(g) = [a, g] \quad (2.31)$$

and

$$e^{t \text{ada}}(g) := \sum_{n=0}^N \frac{t^n}{n!} (\text{ada})^n(g)$$

$$A^n = A \circ \dots \circ A \quad (\text{n times}) \quad \text{for a map}$$

$$\rightarrow \text{here} : A = \text{ada}$$

②0 Rem.: $(ada)^n = \theta$ for $n > N$ (2.32)

(consider now the vector space $g^{(N)(\mathbb{R}^d)} \subset T_0^{(N)}(\mathbb{R}^d)$
spanned by vectors from

$$V, [V, V], [V, [V, V], \dots, \underbrace{[V, \dots, [V, V]]]}_{N-1 \text{ brackets}},$$

where $V \stackrel{\text{def}}{=} \{(0, a, 0, \dots, 0) : a \in \mathbb{R}^d\}$

and $[Z, W] \stackrel{\text{def}}{=} \{[a, b] : a \in Z, b \in W\},$

for $Z, W \subseteq T_0^{(N)}(\mathbb{R}^d)$

$\rightarrow g^{(N)(\mathbb{R}^d)}$ Lie algebra w.r.t. $[\cdot, \cdot]$, called free step- N nilpotent Lie algebra

$$\xrightarrow{(2.22)} g^{(N)(\mathbb{R}^d)} = V \oplus [V, V] \oplus \dots \oplus [V, [V, \dots, [V, V]]] \quad (2.33)$$

Define

$$G^{(N)}(\mathbb{R}^d) = \{\text{Exp}(a) : a \in g^{(N)(\mathbb{R}^d)}\} \quad (2.34)$$

$$\subseteq T_1^{(N)}(\mathbb{R}^d)$$

\rightarrow group w.r.t. \otimes because of (2.29) for $N=2$ or
because of Th. 2.11 for $N > 2$

It is also a Lie group

(take the chart w.r.t. Log , where
 $\Pi((0, g_1, \dots, g_N)) := (g_1, \dots, g_N) \in \mathbb{R}^d \times \dots \times \mathbb{R}^{dN}$)

Let now $(X_{s,t}, R_{s,t}) \in \mathcal{C}_g^k$ be a geometric rough path

Then, for $\mathbb{X}_{s,t} = (1, X_{s,t}, R_{s,t})$

$$\text{Log}(\mathbb{X}_{s,t}) \stackrel{(2.27)}{=} ((0, X_{s,t}), R_{s,t}) - \frac{1}{2} (0, X_{s,t}, R_{s,t}) \otimes 2$$

$$\stackrel{(2.22)}{=} (0, X_{s,t}, R_{s,t}) - (0, 0, \underbrace{\frac{1}{2} X_{s,t} \otimes R_{s,t}}_{= \text{Sym}(R_{s,t})})$$

$$\stackrel{?}{=} (0, X_{s,t}, R_{s,t} - \text{Sym}(R_{s,t}))$$

$$\in [V, V]$$

(21) since e.g. $e_i \otimes e_j - \text{Sym}(e_i \otimes e_j) = \frac{1}{2} (e_i \otimes e_j - e_j \otimes e_i)$
 $= \frac{1}{2} [e_i, e_j]$ for basis elements e_i
 $\Rightarrow \text{Log}(x_{s,t}) \in \mathcal{G}^{(N)}(\mathbb{R}^d)$

$$\stackrel{(2.34)}{\Rightarrow} (1, x_{s,t}, x_{s,t}) = (1, x_{s,t}^{(1)}, x_{s,t}^{(2)}, \dots, x_{s,t}^{(N)}) \in \mathcal{G}^{(N)}(\mathbb{R}^d) \text{ for } N=2 \quad (2.35)$$

In fact one can introduce a metric on $\mathcal{G}^{(N)}(\mathbb{R}^d)$ by means of the Carnot-Caratheodory norm $\|\cdot\|_C$:

Consider the step-N signature of a smooth path γ :

$$\begin{aligned} S^{(N)}(\gamma)_{s,t} &= (1, \sum_{\substack{s < u < t \\ u_1, \dots, u_N}} d\gamma_{u_1}, \dots, \sum_{\substack{s < u, u_1, \dots, u_N < t \\ u_2}} d\gamma_{u_1} \otimes \dots \otimes d\gamma_{u_N}) \\ &\stackrel{N=2}{=} (1, \sum_s d\gamma_{u_1}, \sum_t \left(\sum_u d\gamma_{u_1} \otimes d\gamma_{u_2} \right)) \\ &= (1, \gamma_t - \gamma_s, \sum_s (\gamma_{u_2} - \gamma_s) \otimes d\gamma_{u_2}) \in \mathcal{G}^{(N)}(\mathbb{R}^d) \end{aligned}$$

$$\rightarrow \|g\|_C \stackrel{\text{def}}{=} \inf \left\{ \int_0^1 |\dot{\gamma}_t| dt : \gamma \in C^1([0, 1]; \mathbb{R}^d), S^{(N)}(\gamma)_{0,1} = g \right\} \quad (2.36)$$

\rightarrow metric d_C on $\mathcal{G}^{(N)}(\mathbb{R}^d)$ defined by

$$d_C(g, h) = \|g^{-1} \otimes h\|_C \quad (2.37)$$

\rightarrow properties:

(i) d_C left invariant: $d_C(g \otimes h, g \otimes k) = d_C(h, k)$

(ii) $\|g\|_C = 0 \iff g = (1, 0, \dots, 0)$

(iii) sub-additivity: $\|g \otimes h\|_C \leq \|g\|_C + \|h\|_C$

(iv) symmetry: $\|g\|_C = \|g^{-1}\|_C$

(v) homogeneity: $g = (1, g_1, \dots, g_N), g_\lambda := (1, \lambda g_1, \dots, \lambda^N g_N)$

$$\Rightarrow \|g_\lambda\| = |\lambda| \|g\|, \lambda \in \mathbb{R}$$

(vi) $\exists c_1, c_2 > 0$: $c_1 (1|g_1| + |g_2|^{1/2}) \leq \|g\|_C \leq$

$$\text{for } N=2 \quad c_2 \cdot (1|g_1| + |g_2|^{1/2}) \quad \text{for all } g = (1, g_1, g_2) \in \mathcal{G}^{(N)}(\mathbb{R}^d)$$

$$(22) \quad \xrightarrow{\text{if } X_{0,t} = X_{0,0} \otimes X_{0,t} =: \tilde{X}_t} C_1 \|X\|_{K,[0,T]} \leq \sup_{s \in [0,T]} \frac{d_C(X_{s,t}, \tilde{X}_t)}{|t-s|^K} \leq C_2 \|X\|_{K,[0,T]}, \quad (2.38)$$

where

$$\|X\|_{K,[0,T]} \stackrel{\text{def}}{=} \sup_{\substack{s,t \in [0,T] \\ s \neq t}} \frac{|X_{s,t}|}{|s-t|^K} + \sup_{\substack{s,t \in [0,T] \\ s \neq t}} \frac{|X_{s,t}|^{1/2}}{|s-t|^{K/2}}$$

for $C_1, C_2 > 0$

→ Prop. 2.12 (Characterization of geometric rough paths)

Let $\alpha \in (\beta, \frac{1}{2}]$. Then

$$1. (X, \tilde{X}) \in \mathcal{C}_g^K$$

$$\iff 2. \tilde{X}_t = (1, X_{0,t}, X_{0,t}) \in G^{(N)}(\mathbb{R}^d) \text{ and } \tilde{X} \text{ is } K \text{ Hölder continuous w.r.t. the metric } d_C$$

Prop. 2.13 : Let $\beta \in (\frac{1}{2}, \frac{1}{2}]$. Then for all $(X, \tilde{X}) \in \mathcal{C}_g^\beta([0,T]; \mathbb{R}^d)$ there exists a sequence of smooth paths $X^n : [0,T] \rightarrow \mathbb{R}^d$ such that

$$X_t^n \xrightarrow{n \rightarrow \infty} X_t \text{ uniformly in } t,$$

$$\tilde{X}_{s,t}^n = \int_s^t X_{s,r}^n \otimes dX_r^n \xrightarrow{n \rightarrow \infty} \tilde{X}_{s,t} \text{ unif. in } s,t$$

$$\text{with } \sup_n (\|X^n\|_\beta + \|\tilde{X}^n\|_{2\beta}) \leq c < \infty. \quad (2.39)$$

Lemma 2.14 : Let $(X^n, \tilde{X}^n) \in \mathcal{C}^\beta$, $n \geq 1$ satisfying (2.39) with $X_{s,t}^n \xrightarrow{n \rightarrow \infty} X_{s,t}$, $\tilde{X}_{s,t}^n \xrightarrow{n \rightarrow \infty} \tilde{X}_{s,t}$ uniformly in s,t . Then

$$\text{Sd}((X^n, \tilde{X}^n), (X, \tilde{X})) \xrightarrow{n \rightarrow \infty} 0$$

for all $\alpha \in (\frac{1}{2}, \beta)$.

②③ Proof: We find that

$$|X_{s,t}| = \lim_{n \rightarrow \infty} |X_{s,t}^n| \leq C|t-s|^\beta,$$

$$|\mathbb{X}_{s,t}| = \lim_{n \rightarrow \infty} |\mathbb{X}_{s,t}^n| \leq C|t-s|^{2\beta} \text{ for all } s,t$$

$$\Rightarrow (X, \mathbb{X}) \in \mathcal{E}^\beta$$

On the other hand, uniform convergence and (2.39) give for a $\varepsilon_n \rightarrow 0$ that

$$|X_{s,t} - X_{s,t}^n| \leq \varepsilon_n, \quad |\mathbb{X}_{s,t}^n - \mathbb{X}_{s,t}| \leq \varepsilon_n$$

and $|X_{s,t}^n - X_{s,t}^n| \leq 2C|t-s|^\beta, \quad |\mathbb{X}_{s,t}^n - \mathbb{X}_{s,t}^n| \leq 2C|t-s|^{2\beta}$

Then using

$$\min(a, b) \leq a^{1-\theta} b^\theta, \quad a, b > 0, \quad \theta \in (0, 1).$$

for $\theta = \frac{\alpha}{\beta}$ we see that means: inequality up to a constant

$$|X_{s,t} - X_{s,t}^n| \lesssim \varepsilon_n^{1-\alpha/\beta} |t-s|^\alpha$$

and

$$|\mathbb{X}_{s,t}^n - \mathbb{X}_{s,t}| \lesssim \varepsilon_n^{1-\alpha/\beta} |t-s|^{2\alpha}$$

$$\Rightarrow S_\alpha((X_{s,t}^n, \mathbb{X}_{s,t}^n), (X_{s,t}, \mathbb{X}_{s,t}))$$

$$= |X_0^n - X_0| + \sup_{s \neq t} \frac{|X_{s,t}^n - X_{s,t}|}{|t-s|^\alpha} + \sup_{s \neq t} \frac{|\mathbb{X}_{s,t}^n - \mathbb{X}_{s,t}|}{|t-s|^{2\alpha}} \\ \leq \overbrace{\varepsilon_n^{1-\alpha/\beta}}$$

$\xrightarrow[n \rightarrow \infty]{} 0$

\Rightarrow proof.

(24)

3. Rough path integrals

Objective: Definition of integral(s) of the type

$$\int Y_s dX_s, \quad (3.1)$$

where $(X, \dot{X}) \in C^k([0, T], V)$.

→ natural starting point: integration w.r.t.
to integrands given by

$$Y_s = F(X_s)$$

for smooth functions (i.e. 1-forms)

$$F: V \rightarrow L(V, W) \stackrel{\text{matrix entries}}{\leftarrow} \mathbb{R}^{m \times d} \text{ if } V = \mathbb{R}^d, W = \mathbb{R}^m$$

since Y_s "looks like" X_s

→ 3.1 Integration of 1-forms

Motivation: $F(X_s) = (F_{ij}(X_s))_{\substack{1 \leq i \leq m \\ 1 \leq j \leq d}}$, $V = \mathbb{R}^d, W = \mathbb{R}^m$,

$$X_t = (X_t^1, \dots, X_t^d)$$

$[s, t]$ small time interval

$$\int_s^t F(X_r) dX_r = \int_s^t F(X_s) dX_r + \int_s^t (F(X_r) - F(X_s)) dX_r$$

Taylor approximation \approx $F(X_s) X_{s,t} + \int_s^t DF(X_s) X_{s,r} dX_r$
 $\mathbb{R}^m \ni (\sum_{j=1}^d F_{ij}(X_s) X_{s,t}^j)^T \stackrel{\text{matrix entries}}{\leftarrow} \left(\sum_{l=1}^d \frac{\partial}{\partial x_l} F_{ij}(X_s) X_{s,r}^l \right)_{1 \leq i \leq m, 1 \leq j \leq d} \in \mathbb{R}^{m \times d}$

$$= F(X_s) X_{s,t} + \left(\sum_{j=1}^d \left(\sum_{l=1}^d \frac{\partial}{\partial x_l} F_{ij}(X_s) X_{s,r}^l dX_r^j \right) \right)$$

$$+ \left(\sum_{j=1}^d \left(\sum_{l=1}^d \frac{\partial}{\partial x_l} F_{mj}(X_s) X_{s,r}^l dX_r^j \right) \right)$$

$$= F(X_s) X_{s,t} + DF(X_s) (\underbrace{\int_s^t X_{s,r}^j dX_r}_{= X_{s,t}}), \quad (3.1)$$

$$= X_{s,t} = \left(\int_s^t X_{s,r}^l dX_r^j \right)_{1 \leq l, j \leq d}$$

(25) where $\mathbb{R}^{d \times d} = \mathbb{R}^{d^2}$ and \mathbb{R}^m
 $DF(X_s) : V \otimes V \rightarrow W$ is given by transposition
 $DF(X_s)(v \otimes w) = \left(\sum_{i,j=1}^d \frac{\partial}{\partial x_i} F_{ij}(X_s) v_i w_j \right)_{1 \leq i \leq m}$
 See the Lifting theorem (Th. 2.2) in the case
 of Banach spaces.

Consider $\{t_i\}_{i=1}^n$ with $0 = t_1 < \dots < t_n = T$
 \longrightarrow partition $\mathcal{P} = \{[t_i, t_{i+1}] : i=1, \dots, n-1\}$
 of $[0, T]$,
mesh of \mathcal{P} : $|\mathcal{P}| := \max_{i=1}^{n-1} |t_i - t_{i+1}|$

Now by "sewing" together the local approximations in (3.1) on small intervals $[s, t]$ to a global approximation on $[0, T]$, we can expect that

$$\begin{aligned} \int_0^T F(X_r) dX_r &= \sum_{[s,t] \in \mathcal{P}} \int_s^t F(X_r) dX_r \\ &\approx \sum_{[s,t] \in \mathcal{P}} F(X_s) X_{s,t} + DF(X_s)(X_{s,t}), \end{aligned} \quad (3.2)$$

if $|\mathcal{P}|$ is small enough

\longrightarrow natural question :

Why should (3.2) be a good approximation of the integral?

\longrightarrow reason : We could have also applied in our previous reasoning w.r.t. (3.1) the 3rd order Taylor approximation similarly and we would have arrived at

$$\int_0^T F(X_r) dX_r \approx \sum_{[s,t] \in \mathcal{P}} F(X_s) X_{s,t} + DF(X_s)(X_{s,t}) + \frac{1}{2} D^2 F(X_s)(X_{s,t})^{(3)}, \quad (3.3)$$

where

$$\textcircled{26} \quad D^2 F(X_s) (h^1 \otimes h^2 \otimes h^3) = \left(\sum_{\substack{i_1 i_2 i_3 \\ 1 \leq i \leq m}} \frac{\partial^2}{\partial x_{j_1} \partial x_{j_2}} F_{i_1 i_2 i_3}(X_s) h_{j_1}^1 h_{j_2}^2 h_{j_3}^3 \right)_1$$

for $h^l = (h_{1,l}, \dots, h_{d,l})_{l=1,2,3}$

and $\frac{\partial h}{\partial t}^{pd^2}$

$$\begin{aligned} X_{s,t}^{(3)} &= \int_s^t \left(\int_s^u X_{s,r} \otimes dX_r \right) \otimes dX_u \\ &= \left(\int_s^t \int_s^u X_{s,r}^{i_1} dX_r^{i_2} dX_u^{i_3} \right)_{1 \leq i_1, i_2, i_3 \leq d} \end{aligned}$$

Since for $\alpha \in (\frac{1}{3}, \frac{1}{2}]$

$$|X_{s,t}| \lesssim |s-t|^\alpha \text{ and } |X_{s,t}| \lesssim |s-t|^{2\alpha}$$

we may expect that

$$3\alpha > 1 \quad |X_{s,t}^{(3)}| \lesssim |s-t|^{3\alpha}$$

$$\Rightarrow \frac{|X_{s,t}^{(3)}|}{|s-t|} \xrightarrow{|s-t| \rightarrow 0} 0 \quad \text{, that is}$$

$$|X_{s,t}^{(3)}| = o(|s-t|) \text{ for } |s-t| \rightarrow 0$$

F bounded
derivatives

$$|D^2 F(X_s) X_{s,t}^{(3)}| = o(|s-t|)$$

$$\Rightarrow \lim_{|\beta| \rightarrow 0} \sum_{[s,t] \in \beta} |D^2 F(X_s) X_{s,t}^{(3)}| \lesssim \lim_{|\beta| \rightarrow 0} |\beta|^{3\alpha-1} = 0$$

\Rightarrow third term in (3.3) negligible

\Rightarrow we should have (as we will see later on)

$$\int_0^T F(X_s) dX_s = \lim_{|\beta| \rightarrow 0} \sum_{[s,t] \in \beta} F(X_s) X_{s,t} + DF(X_s) X_{s,t} \quad (3.4)$$

\rightarrow definition of the rough path integral,
if the limit exists

We need the following auxiliary result:

Lemma 3.1: Let $F: V \rightarrow L(V, W)$ be in C_b^2 (space of twice cont. diff. functions with bounded derivatives) and let $(X, X') \in C^\alpha$ for some $\alpha \in (\frac{1}{3}, \frac{1}{2}]$. Further,

(27) set $Y_s := F(X_s)$, $Y'_s := DF(X_s)$ and

$R_{s,t}^Y := Y_{s,t} - Y'_s X_{s,t}$ (in view of the definition of the Grabinelli derivative Y' in a more general framework later on). Then

$$\|Y\|_\alpha \leq \|DF\|_\infty \|X\|_\alpha,$$

$$\|Y'\|_\alpha \leq \|D^2F\|_\infty \|X\|_\alpha,$$

$$\|RY\|_{2\alpha} \leq \frac{1}{2} \|D^2F\|_\infty \|X\|_\alpha^2,$$

where $\|DF\|_\infty = \sup_{x \in V} \|DF(x)\|$, $\|D^2F\|_\infty = \sup_{x \in V} \|D^2F(x)\|$.

Rem. 3.2 : $V = \mathbb{R}^d$, $W = \mathbb{R}^m$ matrix

$$(i) R_{s,t}^Y = \left(F_{ij}(X_t) - F_{ij}(X_s) \right)_{1 \leq i \leq m, 1 \leq j \leq d} - \left(\sum_{\ell=1}^d \frac{\partial}{\partial x_\ell} F_{ij}(X_s) \cdot X_{s,\ell}^\ell \right)_{1 \leq i \leq m, 1 \leq j \leq d}$$

$X_{s,\ell}$ equivalent

$$(ii) \|DF(x)\| \sim \left(\sum_{\ell_1, \ell_2=1}^d \sum_{i=1}^m \left(\frac{\partial}{\partial x_{\ell_1}} F_{ij}(x) \right)^2 \right)^{1/2},$$

$$\|D^2F(x)\| \sim \left(\sum_{\ell_1, \ell_2, \ell_3=1}^d \sum_{i=1}^m \left(\frac{\partial^2}{\partial x_{\ell_1} \partial x_{\ell_2}} F_{ij}(x) \right)^2 \right)^{1/2}$$

Proof of L.J.1 : The mean value theorem gives

$$Y_{s,t} = F(X_t) - F(X_s) = DF(X_s + \beta X_{s,t}) X_{s,t}$$

for some $\beta \in (0,1)$

$$\Rightarrow |Y_{s,t}| = |DF(X_s + \beta X_{s,t}) X_{s,t}| \leq \|DF(X_s + \beta X_{s,t})\| |X_{s,t}|$$

$$\leq \|DF\|_\infty |X_{s,t}|$$

$$\Rightarrow \|Y\|_\alpha \stackrel{\text{def.}}{=} \sup_{s \neq t} \frac{|Y_{s,t}|}{|s-t|^\alpha} \leq \|DF\|_\infty \sup_{s \neq t} \frac{|X_{s,t}|}{|s-t|^\alpha} = \|X\|_\alpha$$

Similarly, we get the estimate for $\|Y'\|_\alpha$

Using Taylor expansion, we find that

$$R_{s,t}^Y \stackrel{\text{def.}}{=} F(X_t) - F(X_s) - DF(X_s) X_{s,t} = \frac{1}{2} D^2F(X_s + \beta X_{s,t}) [X_{s,t}, X_{s,t}]$$

for some $\beta \in (0,1)$

$$\Rightarrow |R_{s,t}^Y| \leq \frac{1}{2} \|D^2F(X_s + \beta X_{s,t})\| |X_{s,t}| |X_{s,t}| \leq \|D^2F\|_\infty \|X\|_\alpha^2$$

$$\Rightarrow \|R_{s,t}^Y\|_{2\alpha} \leq \frac{1}{2} \|D^2F\|_\infty \left(\sup_{s \neq t} \frac{|X_{s,t}|}{|s-t|^\alpha} \right)^2 \Rightarrow \|X\|_\alpha^2 \Rightarrow \text{proof}$$

(28) Our next aim is to "sew" the local approximations

$$\Pi_{s,t} = F(X_s)X_{s,t} + DF(X_s)\bar{X}_{s,t} \quad (3.5)$$

in (3.1) together to an integral

$$J\Pi = \int_s^t F(X_s) dX_s$$

It turns out that this procedure can be also done for more general choices of Π than in (3.5) as functions in $C_2^{\alpha, \beta}([0, T], W)$ defined as the space of functions Π on $0 \leq s \leq t \leq T$ with values in W such that

$$\begin{aligned} \Pi_{t,t} &= 0 \text{ for all } t, \\ \| \Pi \|_{\alpha, \beta} &\stackrel{\text{def.}}{=} \| \Pi \|_\alpha + \| \delta \Pi \|_\beta < \infty \end{aligned} \quad (3.6)$$

where $\| \Pi \|_\alpha = \sup_{s \leq t} \frac{|\Pi_{s,t}|}{|t-s|^\alpha}$ and where

$$\delta \Pi_{s,u,t} \stackrel{\text{def.}}{=} \Pi_{s,t} - \Pi_{s,u} - \Pi_{u,t}, \quad \| \delta \Pi \|_\beta \stackrel{\text{def.}}{=} \sup_{s \leq u \leq t} \frac{|\delta \Pi_{s,u,t}|}{|t-s|^\beta}$$

→ Lemma 3.3 (Sewing Lemma)

Let $0 < \alpha \leq 1 < \beta$. Then there exists a unique bounded linear map $J : C_2^{\alpha, \beta}([0, T], W) \rightarrow C^\alpha([0, T], W)$ such that $(J\Pi)_0 = 0$ and

$$|(J\Pi)_{s,t} - \Pi_{s,t}| \leq C |t-s|^\beta, \quad (3.7)$$

where $C = C(\beta, \| \delta \Pi \|_\beta)$ is a constant.

Proof:

1. Uniqueness of J : Suppose $F := J_1 \Pi \neq \bar{F} := J_2 \Pi$ with J_1, J_2 satisfying the above cond.

$$\begin{aligned} \Rightarrow F_0 - \bar{F}_0 &= 0 \text{ and } |F_{s,t} - \bar{F}_{s,t}| = |F_{s,t} - \Pi_{s,t} + \Pi_{s,t} - \bar{F}_{s,t}| \\ &\leq |F_{s,t} - \Pi_{s,t}| + |\Pi_{s,t} - \bar{F}_{s,t}| \stackrel{(3.7)}{\leq} \sum |t-s|^\beta \end{aligned}$$

3 partition of $[0, u]$

$$\begin{aligned} \Rightarrow |F_u - \bar{F}_u| &= \left| \sum_{[a,b] \in \mathcal{P}} (F_{a,b} - \bar{F}_{a,b}) \right| \leq \sum_{[a,b] \in \mathcal{P}} |F_{a,b} - \bar{F}_{a,b}| \\ &\leq \sum_{[a,b] \in \mathcal{P}} |b-a|^\beta \leq |\mathcal{P}|^{\beta-1} \left(\sum_{[a,b] \in \mathcal{P}} |b-a| \right) \xrightarrow{|\mathcal{P}| \rightarrow 0} 0 \end{aligned}$$

$\Rightarrow F_t = \bar{F}_t \text{ for all } t \Rightarrow F = \bar{F} \Rightarrow \text{uniqueness}$

(29)

2. Existence of \int : Let \mathcal{P} be a partition of $[s, t]$.

Define

$$\sum_{\mathcal{P}} = \sum_{[u_i, v_i] \in \mathcal{P}} \mu_{uv} \quad (3.8)$$

We want to show that $\sum_{\mathcal{P}}$ converges for $|\mathcal{P}| \rightarrow 0$

Let r be the number of intervals in \mathcal{P}

Claim: If $r \geq 2$, then there ex. $a \in [s, t]$ with $[u_{-1}, u_1], [u_i, u_{i+1}] \in \mathcal{P}$ s.t.

$$|u_i - u_{i-1}| \leq \frac{2}{r-1} |t-s| \quad (*)$$

→ otherwise: there ex. u_1, \dots, u_{r-1} such points s.t.

$$|(u_i)_+ - (u_i)_-| > \frac{2}{r-1} |t-s| \text{ for all } i=1, \dots, r-1$$

$$\Rightarrow \underbrace{\sum_{i=1}^{r-1} |(u_i)_+ - (u_i)_-|}_{\leq |(u_i)_+ - u_i| + |u_i - (u_i)_-|} > 2|t-s| \Rightarrow \frac{1}{2} \leq 2|t-s|$$

⇒ claim

Choose a_{r-1} as in (*). Define

$$\mathcal{P}_r = \mathcal{P} \text{ and } \xrightarrow{\text{i.e. replace } [u_{-1}, u_1], [u_i, u_{i+1}] \text{ by } [u_i] - [u_{i+1}] \text{ in } \mathcal{P}}$$

$$\mathcal{P}_{r-1} = (\mathcal{P} \setminus \{[u_{-1}, u_1], [u_i, u_{i+1}]\}) \cup \{[u_i] - [u_{i+1}]\}$$

⇒ \mathcal{P}_{r-1} with $r-1$ intervals

choose u_2 as in (*) w.r.t. \mathcal{P}_{r-1}

$$\rightarrow \mathcal{P}_{r-2} := (\mathcal{P}_{r-1} \setminus \{[u_2] - [u_2], [u_2, (u_2)_+] \}) \cup \{[u_2] - [u_2]\}$$

$$\vdots \\ \mathcal{P}_1 = \{[s, t]\}$$

$$\Rightarrow |\Pi_{s,t} - \sum_{\mathcal{P}}| = \left| \sum_{\mathcal{P}_1} - \sum_{\mathcal{P}_r} \right| \stackrel{\substack{\text{telescope} \\ \text{sum}}}{=} \left| \sum_{j=0}^{r-2} \left(\sum_{\mathcal{P}_{r-j-1}} - \sum_{\mathcal{P}_{r-j}} \right) \right|$$

$$\leq \sum_{j=0}^{r-2} \left| \sum_{\mathcal{P}_{r-j-1} \cup \mathcal{P}_{r-j}} - \sum_{\mathcal{P}_{r-j}} \right| = \sum_{j=0}^{r-2} \overbrace{16 \sum_{\mathcal{P}_{r-j-1}} \mu_{u_{j+1}-u_{j+1}(u_{j+1})_+}}^{\text{(3.6)}} \leq 16 \sum_{j=0}^{r-2} \mu_{u_{j+1}-u_{j+1}(u_{j+1})_+} \quad (**)$$

$$\stackrel{(3.8)}{=} \mu_{u_{j+1}-u_{j+1}(u_{j+1})_+} - \mu_{u_{j+1}-u_{j+1}(u_{j+1})_+} - \mu_{u_{j+1}(u_{j+1})_+} \stackrel{\text{def.}}{=} \delta \mu_{u_{j+1}-u_{j+1}(u_{j+1})_+}$$

$$(30) \quad |(u_{j+1})_t - (u_j)_t|^\beta \stackrel{(*)}{\leq} 2^\beta \frac{1}{(r-j-1)^\beta} |t-s|^\beta$$

$$\xrightarrow{(**)} |\Pi_{s,t} - \sum_{\beta} \Pi| \leq 2^\beta \|8\Pi\|_\beta |t-s|^\beta \quad (***)$$

$\sum_{j=0}^{T-1} \frac{1}{(r-j-1)^\beta}$

zeta function

$$\leq \sum_{j=0}^{\infty} \frac{1}{j^\beta} = \zeta(\beta)$$

Remains to show that

$$\sup_{|\beta| \vee |\beta'| \leq \varepsilon} |\sum_{\beta} \Pi - \sum_{\beta'} \Pi| \xrightarrow{\varepsilon \searrow 0} 0 \quad (+) \quad (\text{arb } \max(a, b))$$

Since

$$|\sum_{\beta} \Pi - \sum_{\beta'} \Pi| \leq |\sum_{\beta} \Pi - \sum_{\beta \cup \beta'} \Pi| + |\sum_{\beta \cup \beta'} \Pi - \sum_{\beta'} \Pi|$$

we can assume that β' is a refinement of β
(i.e. $\beta \subseteq \beta'$)

$$\Rightarrow \sum_{\beta} \Pi - \sum_{\beta'} \Pi = \sum_{[u,v] \in \beta} (\Pi_{u,v} - \sum_{\substack{[u',v'] \in \beta' \text{ with} \\ [u',v'] \subseteq [u,v]}} \Pi_{u',v'})$$

$$\xrightarrow{(**)} |\sum_{\beta} \Pi - \sum_{\beta'} \Pi|$$

$$\leq 2^\beta \zeta(\beta) \|8\Pi\|_\beta \sum_{[u,v] \in \beta} |v-u|^\beta \quad \Rightarrow (+)$$

provides a partition of $[u,v]$

$$\leq C \cdot |\beta|^{\beta-1} \xrightarrow{|\beta| \searrow 0} 0$$

$$\xrightarrow{(+) \rightarrow} (\mathcal{D}\Pi)_{s,t} \stackrel{\text{def.}}{=} \lim_{|\beta| \searrow 0} \sum_{\beta} \Pi$$

$$\xrightarrow{(\star\star\star) \rightarrow} \lim_{|\beta| \searrow 0} |(\Pi_{s,t} - (\mathcal{D}\Pi)_{s,t})| \leq \zeta(\beta) 2^\beta \|8\Pi\|_\beta |t-s|^\beta$$

$$|a|-|b| \leq |a-b|$$

$$\Rightarrow \sup_{s \neq t} \frac{|(\mathcal{D}\Pi)_{s,t}|}{|t-s|^\alpha} \leq \sup_{s \neq t} \frac{|\Pi_{s,t}| + \zeta(\beta) 2^\beta \|8\Pi\|_\beta T^{\beta-\alpha}}{|s-t|^\alpha} = \|\mathcal{D}\Pi\|_\alpha$$

$$\Rightarrow \|\mathcal{D}\Pi\|_\alpha \leq C (\|\Pi\|_\alpha + \|8\Pi\|_\beta) = C \|\Pi\|_{\alpha, \beta}$$

$\Rightarrow \mathcal{D}$ bounded (linear map) \Rightarrow proof

(31)

Sewing Lemma Th. 3.4 (T. Lyons). Let $\mathbb{X} = (X, \mathbb{R}) \in \mathcal{C}^{\alpha}([0, T], V)$

for $\alpha \in (\frac{1}{3}, \frac{1}{2}]$ and let $F: V \rightarrow L(V, W)$ be in C_b^2 .

Then the rough path integral of $Y_s = F(X_s)$ w.r.t. \mathbb{X} can be defined as the existing limit

$$\int_0^T F(X_s) dX_s = \lim_{|\beta| \rightarrow 0} \sum_{[s, t] \in \beta} F(X_s) X_{s,t} + DF(X_s) \mathbb{R}_{s,t}. \quad (3.9)$$

Further, we have that

$$\begin{aligned} & \left| \int_s^t F(X_r) dX_r - F(X_s) X_{s,t} - DF(X_s) \mathbb{R}_{s,t} \right| \\ & \leq C_\alpha \|F\|_{C_b^2} \left(\|X\|_\alpha^3 + \|X\|_\alpha \cdot \|\mathbb{X}\|_{2\alpha} \right) |t-s|^{3\alpha}, \end{aligned} \quad (3.10)$$

where $\|F\|_{C_b^2} := \|F\|_\infty + \|DF\|_\infty + \|D^2F\|_\infty$

Moreover

$$\left\| \int_0^t F(X_s) dX_s \right\|_\alpha \leq C_{\alpha, T} \|F\|_{C_b^2} (\|\mathbb{X}\|_\alpha V \|\mathbb{X}\|_\alpha^3), \quad (3.11)$$

where

$$\|\mathbb{X}\|_\alpha = \|X\|_\alpha + (\|\mathbb{X}\|_{2\alpha})^{1/2}$$

Proof: idea: Sewing Lemma (L.3.3) applied to

$$\Pi_{s,t} := Y_s X_{s,t} + Y_s^1 \mathbb{R}_{s,t}$$

with $Y_s := F(X_s)$, $Y_s^1 := DF(X_s)$

We have to check in (3.6) that

$$\|\Pi\|_{\alpha, \beta} \stackrel{\text{def.}}{=} \|\Pi\|_\alpha + \|\delta \Pi\|_\beta < \infty \text{ for a } \beta > 1,$$

$$\text{where } \delta \Pi_{s,u,t} = \Pi_{s,t} - \Pi_{s,u} - \Pi_{u,t}$$

We see that

$$|Y_s X_{s,t}| \leq \|F\|_\infty |X_{s,t}| \text{ and } |Y_s^1 \mathbb{R}_{s,t}| \leq \|DF\|_\infty |\mathbb{R}_{s,t}| \stackrel{\leq |t-s|^{2\alpha}}{\sim}$$

$$\Rightarrow \|\Pi\|_\alpha < \infty \quad \left(\sum_{k=1}^d \frac{1}{k} \sum_{i,j} \mathbb{E} |F_{ij}(X_s) X_{s,t}^k|^k \right)^{1/k} \stackrel{\text{if } V=R^d, W=R^m}{\sim}$$

$$\text{Set } R_{s,t}^Y = Y_{s,t} - Y_s^1 X_{s,t}$$

$$(32) \Rightarrow -R_{sin}^Y X_{uit} - \underbrace{Y_{sin}^I X_{uit}}_{\left(\sum_{k=1}^d \frac{\partial}{\partial x_k} F_{ik}(X_s) \right)^T \text{ if } V=R^d, W=R^m}_{\text{if } i \leq m} \quad R_{uit} = (R_{uit}^{ds})_{ds \in \mathcal{D}}$$

$$= -Y_{sin} X_{uit} + Y_s^I [X_{sin}, X_{uit}] - Y_{sin}^I R_{uit} \quad (\text{if } V=R^d)$$

Lifting theorem Th. 2.2

$$-Y_{sin} X_{uit} + Y_s^I (X_{sin} \otimes X_{uit}) - Y_{sin}^I R_{uit}$$

Chen's relation $X_{s,t} = R_{sin} - R_{sin} - R_{uit}$

(linearity of \bar{Y}, \bar{Y}^I)

$$-Y_{sin} X_{uit} + Y_s^I R_{s,t} - Y_s^I R_{sin} - Y_s^I R_{uit} - (Y_s^I - Y_s^I) R_{uit}$$

$$= \boxed{-Y_{sin} X_{uit}} + Y_s^I R_{s,t} - Y_s^I R_{sin} - Y_s^I R_{uit}$$

$$\boxed{Y_s X_{s,t} - Y_s X_{sin} - Y_u X_{uit}}$$

$$= R_{s,t} - R_{sin} - R_{uit} \stackrel{(3.6)}{=} \delta R_{sin,t} \quad (*)$$

$$|R_{sin} X_{uit}| \leq |R_{sin}| \|X_{uit}\|_{2\alpha} \quad \text{and} \quad |Y_{sin}^I R_{uit}| \leq |Y_{sin}^I| \|R_{uit}\|_{2\alpha}$$

$$\beta = 3\alpha > 1 \quad \Rightarrow \quad \|\delta R\|_\beta = \sup_{s \in \mathbb{R}^d} \frac{|\delta R_{s,t}|}{|s-t|^{3\alpha}}$$

$$\leq \|R\|_{2\alpha} \|X\|_\alpha + \|Y\|_\alpha \|R\|_{2\alpha}$$

$$\stackrel{L.3.1}{\leq} \frac{1}{2} \|D^2 F\|_\infty \|X\|_\alpha^3 + \|D^2 F\|_\infty \|X\|_\alpha \|R\|_{2\alpha} < \infty$$

(****) in
the proof of L.3.3, $\beta = 3\alpha$

$$\left| \int_s^t Y_r dX_r - Y_s X_{s,t} - Y_s^I R_{s,t} \right| \quad (**)$$

$$\leq 5(3\alpha) 2^{3\alpha} \|F\|_{C_b^2} \left(\|X\|_\alpha^3 + \|X\|_\alpha \|R\|_{2\alpha} \right) |t-s|^{3\alpha} \Rightarrow (3.10)$$

$$|a| - |b| \leq |a-b| \Rightarrow \left| \int_s^t Y_r dX_r \right| \leq \|F\|_\infty |X_{s,t}| + \|DF\|_\infty \overline{|X_{s,t}|}$$

$$+ 5(3\alpha) 2^{3\alpha} \|F\|_{C_b^2} \left(\|X\|_\alpha^3 + \|X\|_\alpha \|R\|_{2\alpha} \right) |t-s|^{3\alpha}$$

$$\|X\|_\alpha^2 \leq \|X\|_\alpha \sqrt{\|X\|_\alpha^3}$$

$\Rightarrow (3.11) \Rightarrow \text{proof}$

(33)

3.2 Integration of controlled rough paths

Recall that

$$\int_0^T Z_s dX_s = \lim_{|\beta| \rightarrow 0} \sum_{[s,t] \in \beta} Z_s X_{s,t} + Z_s^1 \bar{X}_{s,t}$$

for $Z_s = F(X_s)$, $Z_s^1 = DF(X_s)$

$$\rightarrow Z_{s,t} = Z_s^1 X_{s,t} + R_{s,t}^Z \quad (3.12)$$

where

$$R_{s,t}^Z := Z_{s,t} - Z_s^1 X_{s,t}$$

$$\text{with } \|Z\|_\kappa, \|Z^1\|_\kappa, \|R_{s,t}^Z\|_{2\kappa} < \infty.$$

In order to generalize the class of such integrands Z , one could e.g. consider integrands Y which are obtained as a (formal) limit of $Z^n = F_n(X)$, that is

$$Z^n \xrightarrow[n \rightarrow \infty]{} Y$$

with

$$Z^{1,n} = DF_n(X) \xrightarrow[n \rightarrow \infty]{} Y^1$$

$$R^{Z_n} \xrightarrow[n \rightarrow \infty]{} RY$$

$$\xrightarrow{(3.12)} Y_{s,t} = Y_s^1 X_{s,t} + R_{s,t}^Y \quad (3.13)$$

If we additionally require that

$$\|Y\|_\kappa, \|Y^1\|_\kappa, \|RY\|_{2\kappa} < \infty$$

then we could choose $\Gamma_{s,t} = Y_s X_{s,t} + Y^1 \bar{X}_{s,t}$ in the Sewing Lemma (L.3.3) with

$$\|\delta\Gamma\|_\beta = \|RY\|_{2\kappa} \|X\|_\kappa + \|Y^1\|_\kappa \|\bar{X}\|_{2\kappa} < \infty$$

(see the proof of Th. 3.4)

and define

$$\int_0^T Y_s dX_s = \lim_{|\beta| \rightarrow 0} \sum_{[s,t] \in \beta} Y_s X_{s,t} + Y_s^1 \bar{X}_{s,t} \quad (3.14)$$

(34)

\rightarrow Y^1 Gubinelli derivative of Y for the special case $\bar{W} = L(V, W)$
 in the sense of

Def. 3.5 (Space of controlled rough paths)

Let V, \bar{W} be Banach spaces and let $X \in C^\alpha([0, T], V)$,

$Y \in C^\alpha([0, T], \bar{W})$. Then Y is a controlled rough path of X iff there ex. $Y^1 \in C^\alpha([0, T], V)$ with $\bar{V} = L(V, \bar{W})$ such that

$$Y_{s,t} = Y_s^1 X_{s,t} + R_{s,t}^Y \quad (3.15)$$

for a remainder term R^Y with $\|R^Y\|_{2\alpha} < \infty$.

We denote by

$$\mathcal{D}_X^{2\alpha}([0, T], \bar{W})$$

the vector space of all controlled rough paths (Y, Y^1) .

Further, we define the space disjoint union

$$C^\alpha \times \mathcal{D}_X^{2\alpha} = \bigsqcup_{X \in C^\alpha} \{X\} \times \mathcal{D}_X^{2\alpha}$$

with base space C^α and "fibres" $\mathcal{D}_X^{2\alpha}$.

Ex. 3.6 : (i) $\bar{W} = L(V, W)$, $Y_s = F(X_s)$, $Y_s^1 = DF(X_s)$
 as in Th. 3.4.

(ii) $\bar{W} = W$, $Y_s = \int_s^t F(X_r) dX_r$, $Y_s^1 = F(X_s)$,

$$R_{s,t}^Y = Y_{s,t} - Y_s^1 X_{s,t} = \int_s^t F(X_r) dX_r - F(X_s) X_{s,t}$$

$\|R^Y\|_{2\alpha} < \infty$

$|a-b| \leq |a-b|$

(iii) $Y = F(X)$ controlled by X^1 with Gubinelli derivative $Y^1 = DF(X)$

Let $(X, X^1) \in C^\alpha$ with $\overset{\longleftarrow}{X}$ satisfies Chen's relation

$$\overset{\longleftarrow}{X}_t = X_t \text{ and } \overset{\longleftarrow}{X}_{s,t} = \overset{\longleftarrow}{X}_{s,t} + f(t) - f(s)$$

for some $f \in C^{2\alpha}$

$$\Rightarrow (Y, Y^1) \in \mathcal{D}_X^{2\alpha}, \text{ but }$$