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Life Insurance and Finance

Lecture 11: Stochastic integration

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STK4500

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Preliminaries

Recall that we already defined stochastic integrals of the form

$$(Y \cdot A)_t := \int_0^t Y(s, \omega) \, d\underline{A(s, \omega)}$$
 integrator (1)

where $A = \{A(t, \omega), t \geq 0, \omega \in \Omega\}$ (cash flow) is a **stochastic process** on a given probability space $(\Omega, \mathcal{A}, \mathbb{P})$ with paths which are right-continuous with existing left limits and of bounded variation.

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<u>Problem</u>: Can we define (1) for more general integrators $X(s, \omega)$ as e.g.

$$X(s,\omega) = A(s,\omega) + B(s,\omega),$$

where $B(s,\omega)$ is a Brownian motion or more generally, for processes $X_s = X(s,\omega)$ of the form

$$X_{s}=X_{0}+A_{s}+M_{s}$$

where M is a martingale or more generally a local martingale?

In order to define local martingales we need two concepts:

Definition (Usual hypotheses)

A filtration $\mathcal{F}=\{\mathcal{F}_t\}_{t\geq 0}$ (e.g. market information flow) is said to satisfy the *usual hypotheses* if

- (i) \mathcal{F}_0 contains all $N \in \mathcal{A}$ with $\mathbb{P}(N) = 0$. Meaning that market traders are aware of the possible occurrence of extremely rare market events N.
- (ii) F is right-continuous, that is

$$\mathcal{F}_t = \bigcap_{u>t} \mathcal{F}_u, \quad t \geq 0,$$

meaning that the market information flow does not "jump" when a market analyst looks back into history.

Remark

Implication of this: $X = \{X_t, t \geq 0\}$ adapted to \mathcal{F} (i.e. X_t is \mathcal{F}_{t} -measurable for all $t \geq 0$) and $Y = \{Y_t, t \geq 0\}$ a stochastic process such that $X_t = Y_t$ with probability one, then Y is also \mathcal{F} adapted.

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Definition (Stopping time)

A random variable τ with values in $[0, \infty]$ is a stopping time if

$$\{\tau \leq t\} \in \mathcal{F}_t$$

for all $t \geq 0$.

Example (Stopping time)

 S_t , $t \ge 0$ (right-continuous) stock price process. Define

$$\tau := \inf \{ t \geq 0 : S_t = 100 \}$$

first time that S_t reaches 100\$. Here, $\inf \emptyset = \infty$ by convention.

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Example (Not stopping time)

 S_t , $t \ge 0$ (right-continuous) stock price process. Define

$$\tau := \operatorname{argmax} \{ S_t, t \in [0, T] \}$$

the maximum value of the stock on the time frame [0, T]. The event $\{\tau > t\}$ is not in our knowledge in \mathcal{F}_t .

Definition (Local martingale)

An adapted process $M = \{M_t, t \geq 0\}$ with right-continuous paths and existing left limits (i.e. an adapted càdlàg process) is a local martingale if there are increasing stopping times τ_n , $n \geq 1$ with $\tau_n \to \infty$ as $n \to \infty$ with probability one such that

(i) the stopped process (on $\{\tau_n > 0\}$)

$$M_t^{\tau_n} \triangleq M_{t \wedge \tau_n} \mathbf{1}_{\{\tau_n > 0\}}$$

is a martingale for each *n*, that is

$$\mathbb{E}[M_t^{\tau_n}|\mathcal{F}_s] = M_s^{\tau_n}, \quad t \geq s$$

for each $n \ge 1$, and

Definition (Local martingale)

$$\sup_{t>0} \mathbb{E}\left[|M^{\tau_n}_t|\mathbb{I}_{\{|M^{\tau_n}_t|\geq m\}}\right] \xrightarrow{m\to\infty} 0$$

for each $n \ge 1$ (uniform integrability).

Comment:

- Every martingale is a local martingale.
- Every local martingale that is bounded from below is a supermartingale, and every local martingale that is bounded from above is a submartingale. Hence, every bounded local martingale is a martingale. However, in general a local martingale is not a martingale, because its expectation can be distorted by large values of small probability.

Example |

An example of a local martingale which is not a martingale is: $X_t = \log |W_t - 1|$, $t \ge 0$, where W is a complex-valued Brownian motion. Also, the solution of the SDE $dX_t = X_t^{\alpha} dW_t$ where $\alpha > 1$ is a local martingale.

Also, if you consider a geometric Brownian motion, i.e. $X_t = X_0 e^{-\frac{1}{2}\sigma^2 t + \sigma W_t}$, then X is a martingale for $t \geq 0$, now define $Y_t = X_{f(t)}$ where $f(t) = \tan((\pi/2)t)$, then Y is a local martingale on [0,1] but not a martingale. Any stochastic integral $\int_0^t f(s) dW_s$ where $f = f(s,\omega)$ is such that $\int_0^T |f(s)|^2 dt < \infty$ P - a.s. is a local martingale, not necessarily a martingale. If, in addition, $\int_0^T \mathbb{E}[|f(s)|^2] dt < \infty$ then it is a martingale.

Definition (Semimartingale)

An \mathcal{F} -adapted càdlàg process X is a semimartingale if

$$X_t = X_0 + A_t + M_t, \quad t \ge 0, \tag{2}$$

where A and M are càdlàg adapted processes such that A is of bounded variation (with probability one) and M is a local martingale.

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Remark

If $A_0 = M_0 = 0$ and A is continuous in t then the decomposition of X in (2) is unique, i.e.

$$X_t = 0, \quad t \geq 0 \iff A_t = 0, M_t = 0, t \geq 0.$$

Local martingales in...

... stochastic analysis: The Itô integral is classically only constructed for processes ξ_s that are in $L_a^2([0,T])$ and the Itô integral is a martingale. If we want to extend the construction more generally to ξ which are not square-integrable, we can, but then the integral is a local-martingale.

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... finance: When pricing contracts, we use a pricing formula based on martingality:

$$\widetilde{V}_t = \mathbb{E}_{\mathbb{Q}}[\widetilde{V}_T | \mathcal{F}_t],$$

where V_t is the value of a hedging portfolio at time t and \mathbb{Q} is a so-called pricing measure. We want to hedge some r.v. $V_T = H$. Even if the (discounted) underlying tradable assets are martingales under \mathbb{Q} , the associated portfolio V need not be a martingale, but merely a local martingale. Then the price may be wrong. Local martingales are hence used for explaining **financial bubbles**.

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Motivation

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Motivation of how to define a stochastic integral:

$$\int_0^t Y_s dX_s. \tag{3}$$

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Recall the **Riemann integral**:

$$\int_0^T f(s)ds = \lim_{|\pi| \to 0} \sum_{i=1}^{n-1} f(\xi_i)(t_{i+1} - t_i), \tag{4}$$

for partitions $\pi = \{t_i\}_{i=0}^n$ of [0, T] with mesh $|\pi| = \max_{i=1,...,n-1} |t_{i+1} - t_i| \to 0, \ 0 = t_0 < t_1 < \cdots < t_n = T, \xi_i \in [t_i, t_{i+1}].$

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If *f* is a step function, i.e.

$$f(s) = \sum_{i=0}^{n-1} a_i \mathbb{I}_{(t_i,t_{i+1}]}(s), \quad s \in (0,T]$$

for $0 = t_0 < t_1 < \cdots < t_n = T$ then

$$\int_0^T f(s)ds = \sum_{i=0}^{n-1} a_i(t_{i+1} - t_i) = \sum_{i=0}^{n-1} a_i \Delta t_i,$$
 (5)

where $\Delta t_i = t_{i+1} - t_i$, i = 0, ..., n-1.

Although it is tedious, one can compute integrals via its definition:

Example

Let
$$f(x) = x^2$$
 and $\pi = \{t_i\}_{i=0}^n$, $t_i = \frac{i}{n}$, $i = 0, \dots, n$ then

$$\int_{0}^{1} f(x)dx = \lim_{n} \sum_{i=1}^{n-1} f(t_{i})(t_{i+1} - t_{i}) = \lim_{n} \sum_{i=1}^{n-1} t_{i}^{2} \frac{1}{n}$$

$$= \lim_{n} \frac{1}{n} \sum_{i=1}^{n-1} \left(\frac{i}{n}\right)^{2} = \lim_{n} \frac{1}{n^{3}} \sum_{i=1}^{n-1} i^{2}$$

$$= \lim_{n} \frac{1}{n^{3}} \frac{(n-1)n(2n-1)}{6} = \frac{1}{3}.$$

Construction via simple predictable processes

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It is reasonable to define the stochastic integral (3) of **stochastic step** functions Y_t , $t \ge 0$ similarly to (5), that is if

$$Y_s = H_0 \mathbf{1}_{\{0\}}(s) + \sum_{i=1}^n H_i \mathbb{I}_{\{T_i, T_{i+1}\}}(s),$$
 (6)

where H_0, H_1, \ldots, H_n and T_1, \ldots, T_{n+1} are **random variables** instead of real numbers t_i and a_i as before. Then...

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$$\int_{0}^{t} Y_{s} dX_{s} := H_{0} X_{0} + \sum_{i=1}^{n} H_{i} \underbrace{(X_{t \wedge T_{i+1}} - X_{t \wedge T_{i}})}_{X_{T_{i+1}} - X_{T_{i}}} \text{ if } t \geq T_{i+1}$$

$$(7)$$

for $0 = T_1 \le T_2 \le \cdots \le T_{n+1} < \infty$.

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In applications to finance and insurance, however, Y is typically given by a **hedging strategy** with respect to a **financial instrument** X or a discount factor based on stochastic interest rates integrated against a **stochastic cash flow** X. In order to rule out portfolio strategies Y of an insider, it is assumed that Y is based on **market information** up to time t (i.e. \mathcal{F}_t), that is Y is adapted to \mathcal{F} .

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Definition (Stopping time σ -algebra \mathcal{F}_{τ})

For a stopping time τ we define the **stopping** σ -algebra as

$$\mathcal{F}_{\tau} := \{ A \in \mathcal{A} : A \cap \{ \tau \leq t \} \in \mathcal{F}_t \text{ for all } t \geq 0 \}.$$

Definition (Stochastic integral of stochastic step functions)

Let $Y = \{Y_t, t \ge 0\}$ be given by (6) with $0 = T_0 \le T_1 \le \cdots \le T_{n+1} < \infty$ and H_i are random variables on $(\Omega, \mathcal{F}_{T_i}, P)$ such that $|H_i| < \infty$ with probability one, $i = 0, \ldots, n$. Then the stochastic integral of Y with respect to X is defined as in (7),

$$\int_0^t Y_s dX_s := H_0 X_0 + \sum_{i=1}^n H_i (X_{t \wedge T_{i+1}} - X_{t \wedge T_i})$$
 (8)

and denoted by

$$\int_0^t Y_s dX_s \quad \text{or} \quad (Y \cdot X)_t. \tag{9}$$

Remark

- (i) Processes of the form (6) are also called simple predictable and the collection of those processes is usually denoted by S or S.
- (ii) The definition of (9) is **independent** of the specific representation in (6).

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- (ii) The definition of (9) is **independent** of the specific representation in (6).

In view of applications we find that the class *S* of integrand processes is rather small.

The natural approach is to define

$$\int_0^t Y_s dX_s$$

for more general integrand processes Y by approximation of Y through stochastic step functions $Y^{(n)} \in S$.

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In general, this approximation can **not** be as in (4) in the sense of convergence in \mathbb{R} , since e.g. the Brownian motion $X_s = B_s$ is not of bounded variation.

However, this approximation can be in the sense of convergence in **probability** (or L^2) or more precisely, in the following sense:

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However, this approximation can be in the sense of convergence in **probability** (or L^2) or more precisely, in the following sense: Let Y and Z be processes. We define the distance between Y and Z as

$$d(Y,Z) := \sum_{n\geq 1} \frac{1}{2^n} \mathbb{E}\left[1 \wedge \sup_{0\leq s\leq n} |Y_s - Z_s|\right],$$

where $x \wedge y := \min\{x, y\}$. Then

$$Y^{(n)} \xrightarrow{n \to \infty} Y$$

with respect to d, if, and only if

$$d(Y^{(n)},Y) \xrightarrow{n \to \infty} 0. \tag{10}$$

Remark

The convergence in (10) is equivalent to: for all sequences there exists a subsequence $\{n_k\}_{k\geq 0}\subset \mathbb{N}$ of the latter such that

$$Y_t^{(n_k)} \xrightarrow{k \to \infty} Y_t \tag{11}$$

with probability one **uniformly** in t (on compact intervals).

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with probability one **uniformly** in *t* (on compact intervals).

In the following denote by $\mathbb D$ the collection of adapted processes with **right-continuous paths** and **existing left-limits** (càdlag) and by $\mathbb L$ the class of adapted processes with **left-continuous paths** and **existing right-limits** (làdcàg). Obviously, $\mathbb L\supset S$.

The following lemma is the starting point for the construction of stochastic integrals of $Y \in \mathbb{L}$.

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Lemma

Each $Y \in \mathbb{L}$ can be approximated by $\{Y^{(m)}\}_{m \geq 1} \subset S$ in the sense of (10), or equivalently of (11).

Definition (Stochastic integral for $\{Y_t\}_{t>0} \in \mathbb{L}$)

Let $\{Y_t^{(m)}\}_{t\geq 0}\subset S$ be a sequence of simple predictable stochastic processes as defined in (6) and $\{Y_t\}_{t\geq 0}\in \mathbb{L}$ such that $\{Y_t^{(m)}\}_{m\geq 1}$ approximates Y in the sense of (10), or equivalently of (11). The then unique process $Z\in \mathbb{D}$ with

$$d\left(\int_0^{\cdot} Y_s^{(m)} dX_s, Z\right) \xrightarrow{m \to \infty} 0$$

is called stochastic integral of Y with respect to X and denoted by

$$Z_t = \int_0^t Y_s dX_s$$
, or $Z_t = (Y \cdot X)_t$, $t \ge 0$.

Some properties of the stochastic integral

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(i)
$$\int_0^t Y_s d(\alpha X_s + \beta V_s) = \alpha \int_0^t Y_s dX_s + \beta \int_0^t Y_s dV_s.$$

(ii) $V_t := \int_0^t Y_s dX_s$, $\{R_t\}_{t \ge 0} \in \mathbb{L}$ then V is a semimartingale and

$$\int_0^t R_s dV_s = \int_0^t R_s Y_s dX_s.$$

(iii) X a local martingale. Then

$$M_t:=\int_0^t Y_s dX_s, \quad t\geq 0$$

is a local martingale, too.

(iv) τ stopping time, then

$$\int_0^{t\wedge\tau} Y_s dX_s = \int_0^t Y_s \mathbf{1}_{[0,\tau]}(s) dX_s.$$

(iv) *⊤* stopping time, then

$$\int_0^{t\wedge\tau} Y_s dX_s = \int_0^t Y_s \mathbf{1}_{[0,\tau]}(s) dX_s.$$

(v)
$$\Delta f(t) := f(t) - f(t^-)$$
 and $V_t := \int_0^t Y_s dX_s$, then $\Delta V_t = Y_t \Delta X_t$.

(iv) *τ* stopping time, then

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- (v) $\Delta f(t) := f(t) f(t^-)$ and $V_t := \int_0^t Y_s dX_s$, then $\Delta V_t = Y_t \Delta X_t$.
- (vi) **Itô isometry**: $X_t = B_t$, $t \ge 0$, Brownian motion. Then $\mathbb{E}\left[\int_0^t Y_s dB_s\right] = 0$ and

$$\mathbb{V}ar\left[\int_0^t Y_s dB_s\right] = \mathbb{E}\left[\left(\int_0^t Y_s dB_s\right)^2\right] = \mathbb{E}\left[\int_0^t Y_s^2 ds\right].$$

The above fact comes from

$$\left[\int_0^{\cdot\cdot} \mathsf{Y}_{\mathsf{S}} d\mathsf{B}_{\mathsf{S}}, \int_0^{\cdot\cdot} \mathsf{Y}_{\mathsf{S}} d\mathsf{B}_{\mathsf{S}}\right]_t = \int_0^t \mathsf{Y}_{\mathsf{S}}^2 d\mathsf{s}.$$

Quadratic covariation

Definition (Quadratic covariation)

Then the covariation of two processes $X = \{X_t, t \in [0, T]\}$ and $Y = \{Y_t, t \in [0, T]\}$ is defined as

$$[X,Y]_t = \lim_{|\pi| \to 0} \sum_{i=1}^n (X_{t_i} - X_{t_{i-1}})(Y_{t_i} - Y_{t_{i-1}})$$

whenever the limit exists, understood in the probability sense.

Definition (Quadratic variation)

The quadratic variation of a process $X = \{X_t, t \in [0, T]\}$ is defined as

$$[X]_t = [X, X]_t,$$

whenever the limit exists, in probability.

Definition (Quadratic variation process)

The process [X] is the unique continuous increasing adapted process vanishing at zero such that $M_t \triangleq X_t^2 - [X]_t$ is a martingale.

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Definition (Quadratic covariation process)

Let $V = \{V_t\}_{t \ge 0}$ and $Z = \{Z_t\}_{t \ge 0}$ be semimartingales. Then the quadratic covariation process of V and Z is defined as the process

$$[V,Z]_t := V_t Z_t - \int_0^t V_{s-} dZ_s - \int_0^t Z_{s-} dV_s, \quad t \ge 0.$$
 (12)

Some properties of the quadratic variation

- (i) $[X, X] \in \mathbb{D}$ and increasing.
- (ii) $[X, X]_0 = X_0^2$ and $\Delta[X, X]_t = (\Delta X_t)^2$.
- (iii) $0 = \tau_0^n \le \tau_1^n \le \cdots \le \tau_{k_n}^n$, $n \ge 1$ stopping times with

$$\sup_k \tau_k^n \xrightarrow{n \to \infty} \infty \text{ and } \sup_k |\tau_{k+1}^n - \tau_k^n| \xrightarrow{n \to \infty} 0,$$

i.e. a random partition with vanishing mesh. Then

$$X_0^2 + \sum_{i>1} \left(X_{t \wedge \tau_{i+1}^n} - X_{t \wedge \tau_i^n} \right)^2 \xrightarrow{n \to \infty} [X, X]_t$$

in the sense of (10), or equivalently of (11).

(iv) $\{X_t\}_{t\geq 0}\in \mathbb{D}$, X of bounded variation. Then

$$[X, X]_t = X_0^2 + \sum_{0 < s < t} (\Delta X_s)^2.$$

Alternative way to construct stochastic integrals via an isometry

The following theorem provides an alternative way of defining the stochastic integral $Z_t = (Y \cdot X)_t$ of Y w.r.t. a semimartingale X.

Theorem (Stochastic integral)

Let X and Y be two adapted square-integrable martingales, then $(Y \cdot X)$ is the unique element such that $[(Y \cdot X), N] = Y \cdot [X, N]$, for all N. Then the map $Y \mapsto (Y \cdot X)$ is an isometry on right spaces.

Remark (Isometry property)

$$[K \cdot X, H \cdot Y]_t = \int_0^t K_s H_s d[X, Y]_s.$$

In particular,

$$[K \cdot X, K \cdot X]_t = \int_0^t |K_s|^2 d[X, X]_s.$$

Itô formula (chain rule)

In view of applications, the definition of stochastic integrals (via limit of integrals of simple predictable processes) gives rise to the following problem: **How can we compute?**

$$\int_0^t Y_s dX_s ?$$

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Method: Direct use of the definition of stochastic integral. But this is, as mentioned, in general rather tedious.

In view of applications, the definition of stochastic integrals (via limit of integrals of simple predictable processes) gives rise to the following problem: **How can we compute?**

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In general, this problem is difficult or even impossible to solve. However, in many practical relevant cases we may apply one of the following two methods to evaluate stochastic integrals:

- <u>Method</u>: Direct use of the definition of stochastic integral. But this is, as mentioned, in general rather tedious.
- Method: Itô's formula: it can be considered a chain rule for semimartingales.

Theorem (Itô's formula for semimartingales)

Let X be a semimartingale. Denote by $[X, X]_t^c$ the continuous part of $[X, X]_t$, that is

$$\underbrace{[X,X]_t^c}_{of B.V.} = [X,X]_t - X_0^2 - \sum_{\substack{0 < s \le t \\ abs. \ convergent}} (\Delta X_s)^2.$$

countable sum

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Theorem (Itô's formula for semimartingales)

Let f be a function in $C^2(\mathbb{R})$ (i.e. twice continuously differentiable). Then the process $Z_t := f(X_t)$ is a semimartingale again and

$$f(X_{t}) = f(X_{0}) + \int_{0}^{t} f'(X_{s-}) dX_{s} + \frac{1}{2} \int_{0}^{t} f''(X_{s-}) d[X, X]_{s}^{c}$$

$$+ \sum_{0 < s \le t} \left[f(X_{s}) - f(X_{s-}) - f'(X_{s-}) \Delta X_{s} \right]$$

$$= f(X_{0}) + \int_{0}^{t} f'(X_{s-}) dX_{s} + \frac{1}{2} \int_{0}^{t} f''(X_{s-}) d[X, X]_{s}$$

$$+ \sum_{0 < s \le t} \left[f(X_{s}) - f(X_{s-}) - f'(X_{s-}) \Delta X_{s} - \frac{1}{2} f''(X_{s-}) (\Delta X_{s})^{2} \right].$$
(13)

Proof.

The proof is based on Taylor's formula.

Remark

Convention in (13):

$$f'(X_{0^-}) = 0$$
 and $f''(X_{0^-}) = 0$. (14)

Remark

In the lecture notes you can find a multidimensional version of the Itô formula.

Example

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$$\underbrace{f(X_t)}_{=B_t^2} = \underbrace{f(X_0)}_{=0} + \int_0^t \underbrace{f'(X_{s-})}_{2B_s^- = 2B_s} d\underbrace{X_s}_{B_s} + \frac{1}{2} \int_0^t \underbrace{f''(X_{s-})}_{=2} d\underbrace{[X,X]_s^c}_{=s}.$$

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As a result,

$$\int_0^t B_s dB_s = \frac{1}{2}B_t^2 - \frac{1}{2}t.$$

Itô processes and stochastic differential equations (SDEs)

Although we have (very quickly) seen a theory for integration w.r.t. very general semimartingale processes (even discontinuous), we will focus mostly on the case $X_s = B_s$ and the integral is the classical Itô integral. Hence, we know how to construct integrals with ds (Lebesgue) and with dB_s (Itô). So, given two adapted processes u and v such that $\int_0^t \mathbb{E}[|u_s|]ds < \infty \text{ and } \int_0^t \mathbb{E}[|v_s|^2]ds < \infty \text{ we can look at processes of the form}$

$$X_t = X_0 + \int_0^t u_s ds + \int_0^t v_s dB_s.$$

Such processes are known as **Itô processes**.

If we choose u and v in the previous slide as two deterministic functions on b, σ : $[0, T] \times \mathbb{R} \to \mathbb{R}$ and define $u_s = b(s, X_s)$ and $v_s = \sigma(s, X_s)$ then we are looking at processes like

$$X_t = X_0 + \int_0^t b(s, X_s) ds + \int_0^t \sigma(s, X_s) dB_s.$$
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Written in differential form would be:

$$dX_t = b(t, X_t)dt + \sigma(t, X_t)dB_t, \quad t \in [0, T].$$

The above mathematical expression is known as a stochastic differential equation. It describes the dynamics of X (in differential form) and it has no other meaning than (15)





