



## Life Insurance and Finance

Lecture 2: Numerical methods for ODEs

David R. Banos







University of Oslo

# **ODEs**

University of Oslo

Let  $d \ge 0$  and  $(t_0, x_0) \in \mathbb{R} \times \mathbb{R}^d$  some fixed starting time and position. Let  $f : [t_0, \infty) \times \mathbb{R}^d \to \mathbb{R}^d$  be a time dependent vector field. A first-order differential equation is a Cauchy problem, also called initial value problem (IVP) of the form

$$x'(t) = f(t, x(t)), \quad t \in [t_0, \infty), \quad x(t_0) = x_0 \in \mathbb{R}^d.$$
 (1)

Let  $d \ge 0$  and  $(t_0, x_0) \in \mathbb{R} \times \mathbb{R}^d$  some fixed starting time and position. Let  $f : [t_0, \infty) \times \mathbb{R}^d \to \mathbb{R}^d$  be a time dependent vector field. A first-order differential equation is a Cauchy problem, also called initial value problem (IVP) of the form

$$x'(t) = f(t, x(t)), \quad t \in [t_0, \infty), \quad x(t_0) = x_0 \in \mathbb{R}^d.$$
 (1)

## Example

If 
$$f(t, y) = y$$
 then  $f(t, x(t)) = x(t)$  and hence  $x'(t) = x(t)$ .

Let  $d \ge 0$  and  $(t_0, x_0) \in \mathbb{R} \times \mathbb{R}^d$  some fixed starting time and position. Let  $f : [t_0, \infty) \times \mathbb{R}^d \to \mathbb{R}^d$  be a time dependent vector field. A first-order differential equation is a Cauchy problem, also called initial value problem (IVP) of the form

$$x'(t) = f(t, x(t)), \quad t \in [t_0, \infty), \quad x(t_0) = x_0 \in \mathbb{R}^d.$$
 (1)

#### Example

If f(t, y) = y then f(t, x(t)) = x(t) and hence x'(t) = x(t). A function who derivative is itself is of the form  $x(t) = Ce^t$ . If  $x(t_0) = x_0$  then  $x(t) = x_0e^{t-t_0}$ ,  $t \in [t_0, \infty)$ .

**First-order** means that only the first derivative of *x* appears in the equation, and higher derivatives are absent.

**Higher-order** differential equations can be reduced to first-order by increasing the dimension.

**First-order** means that only the first derivative of *x* appears in the equation, and higher derivatives are absent.

**Higher-order** differential equations can be reduced to first-order by increasing the dimension.

For example, the second-order equation x''(t) = f(t, x(t)) can be reduced by defining  $y(t) \triangleq x'(t)$ .

Then y'(t) = x''(t) = f(t, x(t)) and we have the equation

$$z'(t)=F(t,z(t)),$$

where  $z(t) = (x(t), y(t))^t$  and  $F(t, u_1, u_2) = (u_2, f(t, u_1))^t$ . We managed to do so by increasing the dimension by one.

# **Euler's method**

We know that

$$x'(t) = \lim_{h\to 0} \frac{x(t+h) - x(t)}{h}.$$

We know that

$$x'(t) = \lim_{h\to 0} \frac{x(t+h) - x(t)}{h}.$$

Based on

$$x'(t) pprox rac{x(t+h) - x(t)}{h}$$

for a small h > 0.

University of Oslo

We know that

$$x'(t) = \lim_{h\to 0} \frac{x(t+h) - x(t)}{h}.$$

Based on

$$x'(t) pprox rac{x(t+h) - x(t)}{h}$$

for a small h > 0. Recall

$$x'(t)=f(t,x(t)).$$

University of Oslo

We know that

$$x'(t) = \lim_{h\to 0} \frac{x(t+h) - x(t)}{h}.$$

Based on

$$x'(t) pprox rac{x(t+h) - x(t)}{h}$$

for a small h > 0. Recall

$$x'(t)=f(t,x(t)).$$

Subtitute:

$$\frac{x(t+h)-x(t)}{h}\approx f(t,x(t)).$$

University of Oslo

We know that

$$x'(t) = \lim_{h\to 0} \frac{x(t+h) - x(t)}{h}.$$

Based on

$$x'(t) pprox rac{x(t+h) - x(t)}{h}$$

for a small h > 0. Recall

$$x'(t)=f(t,x(t)).$$

Subtitute:

$$\frac{x(t+h)-x(t)}{h}\approx f(t,x(t)).$$

Isolate x(t+h):

$$x(t+h) \approx x(t) + hf(t, x(t)).$$

University of Oslo

We know that

$$x'(t) = \lim_{h\to 0} \frac{x(t+h) - x(t)}{h}.$$

Based on

$$x'(t) pprox rac{x(t+h) - x(t)}{h}$$

for a small h > 0. Recall

$$x'(t)=f(t,x(t)).$$

Subtitute:

$$\frac{x(t+h)-x(t)}{h}\approx f(t,x(t)).$$

Isolate x(t+h):

$$x(t+h) \approx x(t) + hf(t, x(t)).$$

If t is such that x(t) is known then we can quess x at a later time t + hDavid R. BanosLife Insurance and FinanceSTK45006/13

At  $t_0$ ,  $x(t_0) = x_0$  is known. Thus the value of x at time  $t_0 + h$  can be approximated by

 $x(t_0 + h) \approx x(t_0) + hf(t, x(t_0)) = x_0 + hf(t, x_0).$ 

UiO **Contemportation** Department of Mathematics University of Oslo

At  $t_0$ ,  $x(t_0) = x_0$  is known. Thus the value of x at time  $t_0 + h$  can be approximated by

$$x(t_0 + h) \approx x(t_0) + hf(t, x(t_0)) = x_0 + hf(t, x_0)$$

More generally, consider a partition of  $[t_0, \infty)$  with points defined by

$$t_i \triangleq t_0 + ih, \quad i = 0, 1, \ldots$$

and denote

$$x_i \triangleq x(t_i)$$

the value of the solution at  $t_i = t_0 + ih$ .

UiO **Contemportation** Department of Mathematics University of Oslo

At  $t_0$ ,  $x(t_0) = x_0$  is known. Thus the value of x at time  $t_0 + h$  can be approximated by

$$x(t_0 + h) \approx x(t_0) + hf(t, x(t_0)) = x_0 + hf(t, x_0)$$

More generally, consider a partition of  $[t_0, \infty)$  with points defined by

$$t_i \triangleq t_0 + ih, \quad i = 0, 1, \ldots$$

and denote

$$x_i \triangleq x(t_i)$$

the value of the solution at  $t_i = t_0 + ih$ . Then, knowing  $x_i$ , that is  $(t_i, x_i)$ , allows us to find  $x_{i+1}$  by

$$x_{i+1} = x_i + hf(t_i, x_i), \quad i = 0, 1, \ldots$$

## Example

$$x'(t) = x(t), \quad x(0) = 1.$$

## Example

$$x'(t) = x(t), \quad x(0) = 1.$$

■ Partition of points:  $t_i = ih$ , h > 0 step size, i = 0, ..., n.

## Example

$$x'(t) = x(t), \quad x(0) = 1.$$

- Partition of points:  $t_i = ih$ , h > 0 step size, i = 0, ..., n.
- $x_i$  is an approximation of x at  $t_i$ , i.e.  $x_i \approx x(t_i)$ .

#### Example

$$x'(t) = x(t), \quad x(0) = 1.$$

- Partition of points:  $t_i = ih$ , h > 0 step size, i = 0, ..., n.
- $x_i$  is an approximation of x at  $t_i$ , i.e.  $x_i \approx x(t_i)$ .
- The first value is known, namely  $x(t_0) = x(0) = x_0 = 1$ . Then

$$x_{i+1} = x_i + hf(t, x_i) = x_i + hx_i = x_i(1+h), \quad i = 0, ..., n.$$

#### Example

$$x'(t) = x(t), \quad x(0) = 1.$$

- Partition of points:  $t_i = ih$ , h > 0 step size, i = 0, ..., n.
- $x_i$  is an approximation of x at  $t_i$ , i.e.  $x_i \approx x(t_i)$ .
- The first value is known, namely  $x(t_0) = x(0) = x_0 = 1$ . Then

$$x_{i+1} = x_i + hf(t, x_i) = x_i + hx_i = x_i(1+h), \quad i = 0, ..., n.$$

Recursively,

$$x_i = (1 + h)^i$$
,  $i = 0, ..., n$ .

## Example (continued)

We know  $x(t) = e^t$ . What is the error we commit?

## Example (continued)

We know  $x(t) = e^t$ . What is the error we commit? The Global Truncation Error (GTE) we commit is:

$$\begin{aligned} \mathsf{GTE} &\triangleq \max_{i=0,...,n} |x(t_i) - x_i| \ &= \max_{i=0,...,n} |e^{ih} - (1+h)^i| \ &\leq |e^{nh} - (1+h)^n| \ &= \left| e - \left( 1 + rac{1}{n} 
ight)^n 
ight|. \end{aligned}$$

## Example (continued)

We know  $x(t) = e^t$ . What is the error we commit? The Global Truncation Error (GTE) we commit is:

$$\begin{aligned} \mathsf{GTE} &\triangleq \max_{i=0,\dots,n} |x(t_i) - x_i| \ &= \max_{i=0,\dots,n} |e^{ih} - (1+h)^i| \ &\leq |e^{nh} - (1+h)^n| \ &= \left| e - \left(1+rac{1}{n}
ight)^n 
ight|. \end{aligned}$$

which goes to zero as  $h \rightarrow 0$  or as  $n \rightarrow \infty$ .

## Example (Disability model)

We wish to solve

$$\frac{d}{dt}P(s,t)=P(s,t)\Lambda(t)$$

if we go for the forward equation.

## Example (Disability model)

We wish to solve

$$\frac{d}{dt}P(s,t)=P(s,t)\Lambda(t)$$

if we go for the forward equation.

The matrix P of the unknowns (unknown functions) is given by

$$P(s,t) = \begin{pmatrix} p_{**}(s,t) & p_{*\diamond}(s,t) & p_{*\dagger}(s,t) \\ p_{\diamond*}(s,t) & p_{\diamond\diamond}(s,t) & p_{\diamond\dagger}(s,t) \\ p_{\dagger*}(s,t) & p_{\dagger\diamond}(s,t) & p_{\dagger\dagger}(s,t) \end{pmatrix},$$

UiO **Contemportation** Department of Mathematics University of Oslo

## Example (Disability model)

We wish to solve

$$\frac{d}{dt}P(s,t)=P(s,t)\Lambda(t)$$

if we go for the forward equation.

The matrix P of the unknowns (unknown functions) is given by

$$m{P}(m{s},t) = egin{pmatrix} m{p}_{**}(m{s},t) & m{p}_{*\diamond}(m{s},t) & m{p}_{*\dagger}(m{s},t) \ m{p}_{\diamond\diamond}(m{s},t) & m{p}_{\diamond\diamond}(m{s},t) & m{p}_{\diamond\dagger}(m{s},t) \ m{p}_{\dagger*}(m{s},t) & m{p}_{\dagger\diamond}(m{s},t) & m{p}_{\dagger\dagger}(m{s},t) \ m{p}_{\dagger\diamond}(m{s},t) & m{p}_{\dagger\dagger}(m{s},t) \ m{p}_{\dagger\dagger}(m{s},t) & m{p}_{\dagger\dagger}(m{s},t) \ m{p}_{\dagger}(m{s},t) & m{p}_{\dagger\dagger}(m{s},t) \ m{p}_{\dagger}(m{s},t) & m{p}_{\dagger\dagger}(m{s},t) \ m{p}_{\dagger}(m{s},t) & m{p}_{\dagger\dagger}(m{s},t) \ m{p}_{\dagger}(m{s},t) \ m{s},t \ m{s},$$

but the last row is exactly 0 0 1 which can be omitted. Hence, we rather look at

$$P(s,t) = \begin{pmatrix} p_{**}(s,t) & p_{*\diamond}(s,t) \\ p_{\diamond*}(s,t) & p_{\diamond\diamond}(s,t) \end{pmatrix}.$$

#### Example (continued)

The (matrix) vector field in this case is a linear  $2 \times 2$ -transformation

 $f(t, M) = M \cdot \Lambda(t),$ 

where  $t \ge 0$  and *M* is a 2 × 2-matrix. **NB!** Respect the order of the matrices.

## Example (continued)

The (matrix) vector field in this case is a linear  $2 \times 2$ -transformation

$$f(t,M)=M\cdot\Lambda(t),$$

where  $t \ge 0$  and *M* is a 2 × 2-matrix. **NB!** Respect the order of the matrices.

$$\Lambda(t) = egin{pmatrix} \mu_{**}(t) & \mu_{*\diamond}(t) \ \mu_{\diamond*}(t) & \mu_{\diamond\diamond}(t) \end{pmatrix}.$$

Hence,

$$\frac{d}{dt}P(s,t)=P(s,t)\Lambda(t),\quad t\geq 0,\quad P(s,s)=Id.$$

#### Example (continued)

The (matrix) vector field in this case is a linear 2  $\times$  2-transformation

$$f(t,M)=M\cdot\Lambda(t),$$

where  $t \ge 0$  and *M* is a 2 × 2-matrix. **NB!** Respect the order of the matrices.

$$\Lambda(t) = egin{pmatrix} \mu_{**}(t) & \mu_{*\diamond}(t) \ \mu_{\diamond*}(t) & \mu_{\diamond\diamond}(t) \end{pmatrix}.$$

Hence,

$$\frac{d}{dt}P(s,t)=P(s,t)\Lambda(t),\quad t\geq 0,\quad P(s,s)=Id.$$

Next step: discretize time and approximate  $P(s, t_i)$ , i = 0, dots.

## Example (continued)

Take small *h*. Let  $t_i \triangleq s + ih$ ,  $i \ge 0$ .

#### Example (continued)

Take small *h*. Let  $t_i \triangleq s + ih$ ,  $i \ge 0$ . Denote by  $P_i$  an approximation of the matrix  $P(s, t_i)$ .

#### Example (continued)

Take small *h*. Let  $t_i \triangleq s + ih$ ,  $i \ge 0$ . Denote by  $P_i$  an approximation of the matrix  $P(s, t_i)$ . Euler's method gives the following scheme:

$$P_{i+1} = P_i + hP_i\Lambda(t_i) = P_i \left( Id + h\Lambda(t_i) \right) = P_i \left( Id + h\Lambda(s + ih) \right), \quad i \ge 0.$$

UiO **Contemportation** Department of Mathematics University of Oslo

#### Example (continued)

Take small *h*. Let  $t_i \triangleq s + ih$ ,  $i \ge 0$ . Denote by  $P_i$  an approximation of the matrix  $P(s, t_i)$ . Euler's method gives the following scheme:

$$P_{i+1} = P_i + hP_i \Lambda(t_i) = P_i \left( Id + h\Lambda(t_i) \right) = P_i \left( Id + h\Lambda(s + ih) \right), \quad i \geq 0.$$

Let us use the matrix  $\Lambda(t)$  from the book, see Example 2.4.2 on page 18 and Example 4.2.2 on page 30.

 $\mu_*(t) = \mu_{*\diamond}(t) + \mu_{*\dagger}(t), \quad \mu_{*\diamond}(t) = 0.0004 + 10^{0.06t - 5.46}, \ \mu_{\diamond*}(t) = 0.05, \qquad \qquad \mu_{\diamond}(t) = \mu_{\diamond*}(t) + \mu_{\diamond\dagger}(t).$ 

UiO **Contemportation** Department of Mathematics University of Oslo

#### Example (continued)

We start at age s = 30 and look at  $t_i = 30 + ih$  with  $h = \frac{1}{12}$  monthly steps. We run the algorithm until t = 110 years, i.e. i = 0, 1, ..., 1080 = n where  $n = 120 \cdot \frac{1}{h}$ .



David R. Banos

Life Insurance and Finance



## Life Insurance and Finance

Lecture 2: Numerical methods for ODEs

