

# ECON 4140 - Seminar 8

## Problem 7-01

$$\dot{x} = x + y + t \quad (1)$$

$$\dot{y} = -x + 2y \quad (2)$$

~~$\ddot{x} = \dot{x} + \dot{y} = x + 2y + 1$~~

$$(2) \text{ gives } x = 2y - \dot{y} \Rightarrow \dot{x} = 2\dot{y} - \ddot{y}$$

$$\text{Thus, (1) becomes } 2\dot{y} - \ddot{y} = 2y - \dot{y} + y + t \text{ i.e. } \ddot{y} - 3\dot{y} + 3y = -t \quad (*)$$

$$\frac{1}{4}(-3)^2 - 3 = \frac{9}{4} - 3 = \frac{9-12}{4} < 0$$

$$\Rightarrow x = e^{\frac{3}{2}t} (A \cos \frac{\sqrt{3}}{2}t + B \sin \frac{\sqrt{3}}{2}t) \text{ where } p = \sqrt{\frac{3}{4}} = \frac{\sqrt{3}}{2}$$

$$x = e^{\frac{3}{2}t} \left( A \cos \left( \frac{\sqrt{3}}{2}t \right) + B \sin \left( \frac{\sqrt{3}}{2}t \right) \right)$$

$$v^* = A\dot{t} + B \quad j^* = A \quad \ddot{v}^* = 0$$

$$\Rightarrow \text{inserted in } (*) \text{ gives } -3A + 3A\dot{t} + 3B = -t \Rightarrow 3A = -1 \quad (A = -\frac{1}{3})$$

$$-3A + 3B = 0 \quad 3B = -1 \quad (B = -\frac{1}{3}) \Rightarrow v^* = -\frac{1}{3}t - \frac{1}{3}$$

$$\Rightarrow \text{General solution of } x : \underline{x = e^{\frac{3}{2}t} \left( A \cos \left( \frac{\sqrt{3}}{2}t \right) + B \sin \left( \frac{\sqrt{3}}{2}t \right) \right) - \frac{1}{3}t - \frac{1}{3}}$$

$$\Rightarrow \dot{x} = \frac{3}{2}e^{\frac{3}{2}t} \left( A \cos \left( \frac{\sqrt{3}}{2}t \right) + B \sin \left( \frac{\sqrt{3}}{2}t \right) \right) + e^{\frac{3}{2}t} \left( -\frac{\sqrt{3}}{2}A \sin \left( \frac{\sqrt{3}}{2}t \right) + \frac{\sqrt{3}}{2}B \cos \left( \frac{\sqrt{3}}{2}t \right) \right) - \frac{1}{3}$$

$$\Rightarrow y = \dot{x} - x - v^* = \underline{\frac{1}{2}e^{\frac{3}{2}t} \left[ A \cos \left( \frac{\sqrt{3}}{2}t \right) + B \sin \left( \frac{\sqrt{3}}{2}t \right) \right] + e^{\frac{3}{2}t} \left[ \frac{\sqrt{3}}{2}B \cos \left( \frac{\sqrt{3}}{2}t \right) - \frac{\sqrt{3}}{2}A \sin \left( \frac{\sqrt{3}}{2}t \right) \right] - \frac{2}{3}t}$$

Problem 7-04) a & b

$$\begin{aligned} \dot{x} &= y - x^2 - xy = f(x,y) \\ \dot{y} &= x - y^2 - xy = g(x,y) \end{aligned}$$

a)  $\dot{x}=0 \Rightarrow y-x^2-xy=0 \Rightarrow xy=y-x^2$

$$y=0 \Rightarrow x-y^2-xy=0$$

$$x-y^2-xy+x^2=0 \quad x+x^2=y+y^2 \Rightarrow \underline{x=y}$$

$$\Rightarrow x-2x^2=0 \quad x^2-\frac{1}{2}x=0 \quad x(x-\frac{1}{2})=0 \quad x=0 \text{ or } x=\frac{1}{2}$$

$$\Rightarrow (x,y) = (0,0) \text{ or } (x,y) = (\frac{1}{2}, \frac{1}{2})$$

~~partial derivatives w.r.t. x goes to zero~~

$$f'_1 = -2x-y \quad f'_2 = 1-x$$

$$g'_1 = 1-y \quad g'_2 = -2y-x$$

$$A(0,0) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \Rightarrow \text{tr}(A(0,0)) = 0, |A(0,0)| = -1 < 0$$

Since the determinant is negative,  $(0,0)$  is saddle point

$$A(\frac{1}{2}, \frac{1}{2}) = \begin{pmatrix} -\frac{3}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{3}{2} \end{pmatrix} \Rightarrow \text{tr}(A(\frac{1}{2}, \frac{1}{2})) = -3 < 0 \quad |A(\frac{1}{2}, \frac{1}{2})| = \frac{9}{4} - \frac{1}{4} = 2 > 0$$

Since determinant positive and trace negative,  $(\frac{1}{2}, \frac{1}{2})$  is asymptotically stable

b)  $z = x+y \quad \dot{z} = \dot{x} + \dot{y} = y - x^2 - xy + x - y^2 - xy = x+y - (x^2+2xy+y^2) = z-z^2$

$$\Rightarrow \dot{z} = z - z^2 \quad \text{Bernoulli form, i.e. } \underline{\dot{z} - z = -z^2}$$

$$\Rightarrow w = \frac{1}{z} \quad \dot{w} = -\frac{1}{z^2} \Rightarrow \dot{w} + w = -1 \quad \dot{w} + w = 1 \quad \frac{d(e^t w)}{dt} = e^t \quad e^t w = e^t + C$$

~~$w = \frac{1}{z} = \frac{1}{e^t + C}$~~ 

$$w = 1 + Ce^t \Rightarrow z = \frac{1}{1+Ce^t} \quad \underline{\underline{z = \frac{e^t}{e^t + C}}}$$

Exam 2008, Problem 1

a)  $C_k = \begin{pmatrix} k & 2 & k \\ 2 & 3 & 0 \\ k & 0 & k \end{pmatrix}$   $D_k = \begin{pmatrix} k & 2 & k & k \\ 2 & 3 & 0 & k+1 \\ k & 0 & k & ke^k \end{pmatrix}$

$$|C_k| = k \begin{vmatrix} 3 & 0 \\ 0 & k \end{vmatrix} - 2 \begin{vmatrix} 2 & 0 \\ k & k \end{vmatrix} + k \begin{vmatrix} 2 & 3 \\ k & 0 \end{vmatrix} = 3k^2 - 4k - 3k^2 = -4k$$

$k \neq 0 \Rightarrow \text{Rank}(C_k) = 3$

$\Rightarrow \text{Rank}(D_k) = 3 \text{ for } k \neq 0$

$k=0 \Rightarrow \text{Rank}(C_0) = 2$

$k=0 \Rightarrow D_0 = \begin{pmatrix} 0 & 2 & 0 & 0 \\ 2 & 3 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \Rightarrow \text{Rank}(D_0) = 2$

Has solution for all  $k \neq 0$

b)  $A = C_0 = \begin{pmatrix} 0 & 2 & 0 \\ 2 & 3 & 6 \\ 0 & 6 & 0 \end{pmatrix}$

i)  $\begin{pmatrix} 0 & 2 & 0 \\ 2 & 3 & 6 \\ 0 & 6 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 4 \begin{pmatrix} x \\ y \\ z \end{pmatrix} \quad \begin{pmatrix} 2x \\ 2x+3y \\ 0 \end{pmatrix} = \begin{pmatrix} 4x \\ 4y \\ 0 \end{pmatrix} \quad \Rightarrow \underline{z=0} \quad \underline{y=2x}$   
 $2x+6x=8x$

$\Rightarrow \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \underline{\underline{+}} \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}$

ii)  $\begin{pmatrix} 0 & 2 & 0 \\ 2 & 3 & 0 \\ 0 & 6 & 0 \end{pmatrix} \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} = \lambda_2 \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} \quad \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2\lambda_2 \\ -\lambda_2 \\ 0 \end{pmatrix} \quad \Rightarrow \underline{\lambda_2 = -1}$

iii) ~~trace~~ trace(A) =  $\lambda_1 + \lambda_2 + \lambda_3 = 3$

$4 - 1 + \lambda_3 = 3 \quad \underline{\underline{\lambda_3 = 0}}$

d) ~~j~~  $\begin{pmatrix} \ddot{x} \\ \dot{x} \\ x \end{pmatrix} = \begin{pmatrix} 0 & 2 & 0 \\ 2 & 3 & 0 \\ 0 & 0 & 6 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2y \\ 2x+3y \\ 0 \end{pmatrix}$

$\ddot{z} = 0 \Rightarrow \underline{\underline{z = C}}$   $\dot{x} = 2y \quad \underline{\underline{y = \frac{1}{2}\dot{x}}} \quad \dot{y} = 2x+3y \quad \underline{\underline{y = \frac{1}{2}\ddot{x}}}$

$\frac{1}{4}q+4>0 \Rightarrow x = A e^{4t} + B e^{-8t}$   $\Rightarrow \frac{1}{2}\ddot{x} = 2x + \frac{3}{2}\dot{x} \Rightarrow \ddot{x} - 3\dot{x} - 4x = 0$   
 $\frac{9+16}{4} = \frac{25}{4}$   $y = 2A e^{4t} - \frac{1}{2}B e^{-8t}$

~~$$x(0) = A + B \stackrel{?}{=} 0 \Rightarrow A = -B$$

$$y(0) = \frac{1}{2}A - \frac{1}{2}B = -\frac{1}{2}B - \frac{1}{2}B = 0 \stackrel{?}{=} 0 \quad B \neq 0 \text{ if } x \neq 0$$~~

ii) We need  $\lim_{t \rightarrow \infty} x = 0$  and  $\lim_{t \rightarrow \infty} y = 0$

Only possible when  $A = 0$

Thus  $x = Be^{-t}$   $y^* = -\frac{1}{2}Be^{-t} \Rightarrow \frac{x^*}{y^*} = -2$  (Here,  $B \neq 0$ ).

### Induction exercise

a)  $0+1+2+\dots+n = \frac{n(n+1)}{2}$

~~• Base case~~  $0+1=1$   $\frac{1(1+1)}{2} = \frac{2}{2} = 1$  ok for base case

• Assume true for  $n$ , is then true for  $n+1$ ?

$$0+1+\dots+n+(n+1) = \frac{n(n+1)}{2} + (n+1) = \frac{n(n+1)}{2} + \frac{2(n+1)}{2} = \frac{n(n+1)+2(n+1)}{2} = \frac{(n+1)(n+2)}{2}$$

Yes, is true for  $n+1$  as well  $\Rightarrow$  Hypothesis true

b) ~~9-1=8~~  $\cdot \frac{9-1}{8} = \frac{8}{8} = 1 \Rightarrow$  Possible for ~~base case~~ base case.

• Assume true for  $n$ , is true for  $n+1$ ? This means  $\frac{9^n-1}{8} = k$   $\leftarrow$  integer

~~$$9^{n+1}-1 = 9 \cdot 9^n - 1 = 9 \cdot (8k+1) - 1 = 9 \cdot 8k + 9 - 1$$~~

$$\text{Then, } \frac{9^{n+1}-1}{8} = \frac{9 \cdot 9^n - 1}{8} = \frac{9 \cdot (8k+1) - 1}{8} = \frac{9 \cdot 8k + 9 - 1}{8}$$

$$= 9k + \frac{9}{8} - \frac{1}{8} = 9k + \frac{8}{8} = 9k + 1 \text{ which is integer since } k \text{ integer.}$$

$\Rightarrow$  Hypothesis true

7-02

$$\dot{x} = ax + by + \gamma \quad (1)$$

$$\dot{y} = cx + dy + \beta \quad (2)$$

$\oplus$

2) (1) gives  $y = \frac{1}{2}\dot{x} - \frac{a}{2}x - \frac{\gamma}{2}$   $\Rightarrow \dot{y} = \frac{1}{2}\ddot{x} - \frac{a}{2}\dot{x}$

Insert in (2):  $\frac{1}{2}\ddot{x} - \frac{a}{2}\dot{x} = cx + \frac{d}{2}\dot{x} - \frac{a^2}{2}x - \frac{\gamma a}{2} + \beta$

$\oplus \Rightarrow \boxed{\ddot{x} - 2a\dot{x} + (a^2 - 4)x = 2\beta - \gamma a}$

"Characteristic coefficient":  $\frac{1}{4}(-2a)^2 - (a^2 - 4) = 4 > 0$

~~$x(t) = Ae^{2at} + Be^{(a-2)t}$~~

$\Rightarrow \underline{x^*(t) = Ae^{(a+2)t} + Be^{(a-2)t}}$

When  $a \neq \pm 2$ , then  $\underline{v^*(t) = \frac{2\beta - \gamma a}{a^2 - 4}}$

When  $a = 2$ ,  $\underline{v^*(t) = \lambda t + \mu} \Rightarrow v'(t) = \lambda, v''(t) = 0$

Thus,  $v^*(t)$  must satisfy  ~~$\lambda t + \mu = \frac{2\beta - \gamma a}{4}$~~

$$-4\lambda = 2\beta - \gamma a \Rightarrow \underline{\lambda = \frac{2\beta - \gamma a}{4}} = \frac{1}{2}(\beta - \gamma)$$

When  $a = -2$ ,  $\underline{v^*(t) = \bar{\lambda}t + \bar{\mu}} \Rightarrow v'(t) = \bar{\lambda}, v''(t) = 0$

$$\Rightarrow \underline{4\bar{\lambda} = 2(\beta + \gamma)} \Rightarrow \underline{\bar{\lambda} = \frac{1}{2}(\beta + \gamma)}$$

To summarize, for  $x$  we have the following

When  $\alpha \neq \pm 2$ ,  $x(t) = A e^{(\alpha+2)t} + B e^{(\alpha-2)t} + \frac{2\beta - \alpha\alpha}{\alpha^2 - 4}$

When  $\alpha = 2$ ,  $x(t) = A e^{4t} + \frac{1}{2}(\gamma - p)t + \mu$  (†)

When  $\alpha = -2$ ,  $x(t) = B e^{-4t} + \frac{1}{2}(\gamma + p)t + \bar{\mu}$

We know  $y(t) = \frac{1}{2}x - \frac{\alpha}{2}x - \frac{\gamma}{2}$

and  $\dot{x} = \begin{cases} (\alpha+2)Ae^{(\alpha+2)t} + (\alpha-2)Be^{(\alpha-2)t} & \text{when } \alpha \neq \pm 2 \\ 4Ae^{4t} + \frac{1}{2}(\gamma-p) & \text{when } \alpha=2 \\ -4Be^{-4t} + \frac{1}{2}(\gamma+p) & \text{when } \alpha=-2 \end{cases}$

Thus,

$$y(t) = \begin{cases} Ae^{(\alpha+2)t} - Be^{(\alpha-2)t} + \frac{\frac{1}{2}\alpha^2 - \beta\alpha - \frac{1}{2}(\alpha^2 - 4)}{\alpha^2 - 4} & \text{when } \alpha \neq \pm 2 \\ (2 - \frac{\alpha}{2})Ae^{4t} - \frac{\alpha}{4}(\gamma - p)t - \frac{\alpha}{2}\mu + \frac{1}{4}(\gamma - p) - \frac{\gamma}{2} & \text{when } \alpha = 2 \\ -(2 + \frac{\alpha}{2})Be^{-4t} - \frac{\alpha}{4}(\gamma + p)t - \frac{\alpha}{2}\bar{\mu} + \frac{1}{4}(\gamma + p) - \frac{\gamma}{2} & \text{when } \alpha = -2 \end{cases}$$

Thus

$$y(t) = \begin{cases} Ae^{(\alpha+2)t} - Be^{(\alpha-2)t} + \frac{2\gamma - \beta\alpha}{(\alpha^2 - 4)} & \text{when } \alpha \neq \pm 2 \\ Ae^{4t} - \frac{1}{2}(\gamma - p)t - \mu - \frac{1}{4}(\gamma + p) & \text{when } \alpha = 2 \\ -Be^{-4t} + \frac{1}{2}(\gamma + p)t + \bar{\mu} + \frac{1}{4}(\beta - \gamma) & \text{when } \alpha = -2 \end{cases} \quad (\dagger\dagger)$$

(†) and (††) give the solution of the problem

b)  $x=0$  and  $y=0$

$$\begin{aligned} \Rightarrow ax+2y+\alpha &= 0 \\ 2x+ay+\beta &= 0 \end{aligned} \Rightarrow \underbrace{\begin{pmatrix} a & 2 \\ 2 & a \end{pmatrix}}_A \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -\gamma \\ -\beta \end{pmatrix}$$

Since  $a \neq \pm 2$ ,  $\begin{pmatrix} a & 2 \\ 2 & a \end{pmatrix}$  is invertible ( $| \begin{pmatrix} a & 2 \\ 2 & a \end{pmatrix} | = a^2 - 4 \neq 0$ ).

$$\Rightarrow \text{Solution is } \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a & 2 \\ 2 & a \end{pmatrix}^{-1} \begin{pmatrix} -\gamma \\ -\beta \end{pmatrix}.$$

$$\begin{pmatrix} a & 2 \\ 2 & a \end{pmatrix}^{-1} = \frac{1}{a^2 - 4} \begin{pmatrix} a & -2 \\ -2 & a \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} x \\ y \end{pmatrix} = \frac{1}{4-a^2} \begin{pmatrix} a & -2 \\ -2 & a \end{pmatrix} \begin{pmatrix} \gamma \\ \beta \end{pmatrix} = \frac{1}{4-a^2} \begin{pmatrix} a\gamma - 2\beta \\ a\beta - 2\gamma \end{pmatrix}$$

i.e.  $x = \frac{a\gamma - 2\beta}{4-a^2}$  and  $y = \frac{a\beta - 2\gamma}{4-a^2}$  in equilibrium.

Locally asymptotic stable iff globally a.s.

$\Leftrightarrow \text{tr}(A) < 0$  and  $|A| > 0$ ,

$$\text{tr } A = 2a \text{ and } |A| = a^2 - 4$$

Thus, the system is locally asymptotically stable if and only if  $a < -2$ .

When  $|A| < 0$ , we have a saddle point.

Thus, we have a saddle point when  $a \in (-2, 2)$

