

Differential eq's (ordinary, not partial)
↓ ordinary derivatives only ↓ involving partial derivatives

Math 2: first order.

→ separable

→ linear

Math 3:

→ one non-separable nonlinear first-order type (Bernoulli) if time permits

→ second-order: not the "2nd order generalization of separable" (autonomous...)

→ second-order linear

→ linear first-order systems $\dot{\vec{x}} = A\vec{x} + \vec{b}$

Recall terminology:

→ particular solution

→ general solution

Recall 1st order linear:

$$\dot{x} + a(t)x = f(t) \quad \textcircled{2}$$

→ Formula

→ Can: $\frac{d}{dt} (x e^{A(t)}) = (\dot{x} + \dot{A}(t)x) e^{A(t)}$

Let $\dot{A}(t) = a(t)$; then this equals

$f(t) e^{A(t)}$, Integrate:

$$x e^{A(t)} = C + \int f(t) e^{A(t)} dt$$

any antiderivative,
when we write the "C"

A could be any antiderivative of a.

→ Note:

The general solution of $\textcircled{2}$

= the general solution of $\dot{x} + a(t)x = 0$
(the "corresponding homogeneous equation")

+

any particular solution of $\textcircled{2}$.

Ex: $\dot{x} + 2x = 3$; $\dot{x} + 2x = 0$ has general

↓ solution $C e^{-2t}$
 $x = \frac{3}{2}$ is a particular solution

So: $x = \underline{\underline{\frac{3}{2} + C e^{-2t}}}$

Compare with algebraic eq. $\vec{M}\vec{x} = \vec{b}$, $\textcircled{2}$
 \vec{x} = general sol'n of $\vec{M}\vec{x} = \vec{0}$ + some solution of $\textcircled{2}$

2nd order: $\ddot{x} = F(t, x, \dot{x})$ ($G(t, x, \dot{x}, \ddot{x}) = 0 \dots$)

Example:

$\ddot{x} = 2$ Gen. sol.: $\dot{x} = t^2 + C_1 + D_1$

* Two constants!

→ No "separable" diff. eq;

→ but the autonomous ones, $\dot{x} = F(x, \dot{x})$

have a somewhat related method

Sketch: $y = \dot{x}$, $\frac{dy}{dt} \left(\frac{dt}{dx} \frac{dx}{dt} \right) = F(x, y)$
 $y \frac{dy}{dx} = F(x, y)$

solve for y as function of x

(disregard that x was originally the unknown!)

get $y = h(x)$, $y = \dot{x}$, so

$\dot{x} = h(x)$ to solve for x .

→ Focus of this course: linear:

$\ddot{x} + a(t)\dot{x} + b(t)x = f(t)$, (4)

→ will soon assume a, b constant, but not f !

Again:

Homogeneous eq.

$\ddot{x} + ax + bx = 0$ (4')

(4) has general sol. =

gen. sol. of (4)
 + some sol. u^* of (4')

So we proceed to solve

$$(H) \quad \ddot{x} + ax + bx = 0$$

(\ddot{f} to
be covered
later)

Fact: If we have two
non-proportional particular
solutions u_1 and u_2 of (H),
then the general solution is

$$C_1 u_1(t) + C_2 u_2(t)$$

Example:

$$\ddot{x} = \rho^2 x$$

Hint:

$$e^{\rho t} \quad \rho^2 e^{\rho t} = \rho^2 e^{\rho t}$$
$$C_1 e^{\rho t} + C_2 e^{-\rho t}$$

- $C_1 u_1 + C_2 u_2 + c^*$ holds whether const. coeffs or not.
- One 2nd order ^{homogeneous} with non-constant coeffs:

$$t^{p+2} \ddot{x} + \alpha t^{p+1} \dot{x} + \beta t^p x = 0$$

$$t^q: \left[q(q-1) t^{p+q} + \alpha q t^{p+q} + \beta t^{p+q} \right] t^{p+q} = 0$$

$$q^2 + (\alpha-1)q + \beta = 0$$

$$q = \frac{1}{2} \left[1-\alpha \pm \sqrt{(1-\alpha)^2 - 4\beta} \right]$$

Two solutions q_1, q_2 if $(1-\alpha)^2 > 4\beta$.

→ ~~We~~ We skip the other ~~two~~ cases

Constant coeff's. " = f " (abn)

$$\ddot{x} + a\dot{x} + b = 0$$

Try e^{rt}

$$r^2 e^{rt} + a r e^{rt} + b e^{rt} = 0$$

$$r^2 + ar + b = 0$$

$$r = -\frac{a}{2} \pm \sqrt{\left(\frac{a}{2}\right)^2 - b}$$

• So if $\left(\frac{a}{2}\right)^2 - b > 0$ then OK:

$$C_1 e^{r_1 t} + C_2 e^{r_2 t}$$

• If $\left(\frac{a}{2}\right)^2 = b$? $(Ae + B)e^{rt}$
 (insert & see it works!)
 Why? $(C_1 + C_2)e^{r_1 t} + C_2(-e^{r_1 t} + e^{r_2 t})$

Put $C_2 = \frac{A}{r_2 - r_1}$ $r_2 - r_1 = \frac{2\sqrt{\quad}}{h}$

$$\frac{e^{(r_1 + \frac{A}{h})t} - e^{r_1 t}}{h} \rightarrow t$$

Q: What if $(\frac{a}{2})^2 < b$?

Consider $\ddot{x} = -bx, \quad b > 0.$

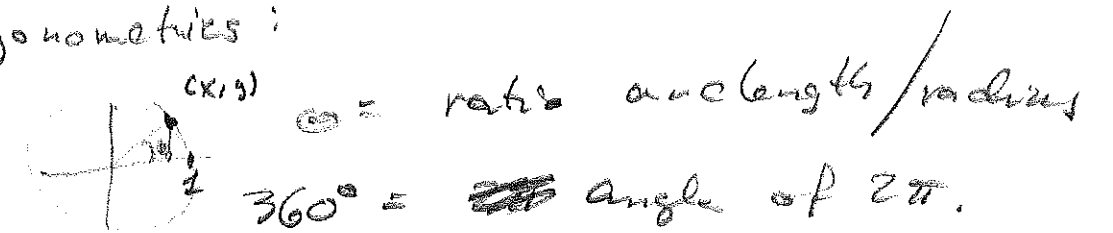
\rightarrow concave when $x > 0$

\rightarrow convex when $x < 0$

In fact:



Trigonometrics:



Let radius = 1, so (x, y)
satisfies $x^2 + y^2 = 1$

Define the functions "cos" and "sin"

$$\text{by } \begin{array}{l} \cos \theta = x \\ \sin \theta = y \end{array} \quad \left| \begin{array}{l} x/\text{radius} \\ y/\text{radius} \end{array} \right.$$

~~No~~ Trig has some \rightarrow odd notations:

$\cos 2\theta$ for $\cos(2\theta)$

$\cos^2 \theta$ for $(\cos(\theta))^2$

etc.

Trigonometry for differential eq.'s

Want: To solve diff. eq's of the form

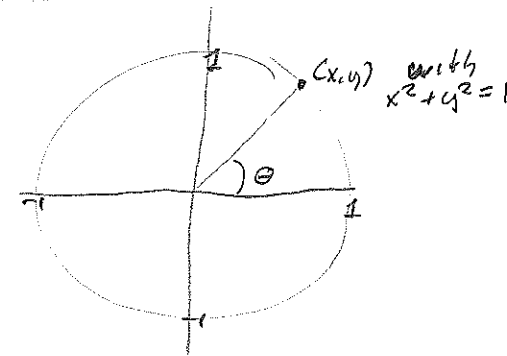
$$\ddot{x} + a\dot{x} + bx = f(t).$$

Special case: $\ddot{x} + bx = 0$

Has solutions $x = e^{\pm\sqrt{|b|}t}$ if $b < 0$.

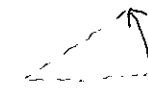
Need other functions if $b > 0$.

Sin & cos: "Unit circle definitions"



θ in radians, i.e.

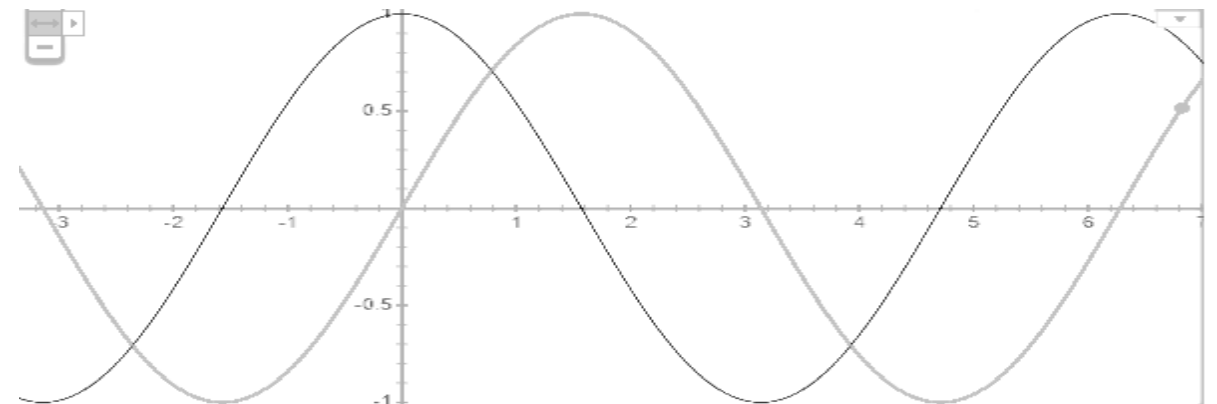
$\theta =$ arc length



Def: $\cos \theta =$ the x coordinate $\in [-1, 1]$

$\sin \theta =$ the y coordinate, $\in [-1, 1]$

Plots: dark = cos, lighter but thicker = sin



$$\cos \theta = \sin \left(\theta + \frac{\pi}{2} \right) \quad ; \quad \sin \theta = -\cos \left(\theta + \frac{\pi}{2} \right)$$

Some facts

Periodicity $\sin(\theta \pm 2\pi) = \sin \theta$ $\cos(\theta \pm 2\pi) = \cos \theta$
 Translates of each other (prev page) $\sin \theta = \cos(\theta - \frac{\pi}{2})$ $\cos \theta = \sin(\theta + \frac{\pi}{2})$
 Concavity/convexity? Inflect at the zeroes
 odd/even? Odd: $\sin(-\theta) = -\sin \theta$ even: $\cos(-\theta) = \cos \theta$
 Lin. comb... Any $A \cos \theta + B \sin \theta$ can be written
 $= C \cos(\omega + \theta)$ $= D \sin(\psi + \theta)$

Derivatives? $\sin' = \cos, \sin'' = -\sin$ $\cos' = -\sin, \cos'' = -\cos$
 "Inverses": \sin^{-1} = the inverse of $\sin \theta; \theta \in [-\frac{\pi}{2}, \frac{\pi}{2}]$ \cos^{-1} = the inverse of $\cos \theta; \theta \in [0, \pi]$

(natural) algebraic formulae: a lot ! Only a few here.
 $(\sin \theta)^2 + (\cos \theta)^2 = 1$

Typical notation: $\cos^2 \theta$ for $(\cos \theta)^2$ etc
 $\cos 3t$ for $\cos(3t)$ etc

Example: $\int \frac{\cos \theta}{\sin \theta} d\theta = \int \frac{du}{u} = C + \ln|u| = C + \ln|\sin \theta|$
 $u = \sin \theta$
 $du = \cos \theta d\theta$

Also: $\int \frac{1}{\sqrt{1-x^2}} dx = \int \frac{\cos \theta d\theta}{\sqrt{\cos^2 \theta}} = \int \pm 1 d\theta = C \pm \sin^{-1} x \Big|_{\pm?}$
 $x = \sin \theta; 1-x^2 = 1-\sin^2 = \cos^2$
 $dx = \cos \theta d\theta$
 $= C + \sin^{-1} x$
 after testing.

sin & cos: "series definition"

$$\exp \theta = 1 + \theta + \frac{\theta^2}{2} + \frac{\theta^3}{3!} + \frac{\theta^4}{4!} + \dots$$

Turns out: $\exp(\theta) = e^\theta$, $e = \lim_{n \rightarrow \infty} \left(1 + \frac{1}{n}\right)^n$.

Define:

$$\cos \theta = 1 - \frac{\theta^2}{2} + \frac{\theta^4}{4!} - \frac{\theta^6}{6!} + \dots$$

$$\sin \theta = \theta - \frac{\theta^3}{3!} + \frac{\theta^5}{5!} - \frac{\theta^7}{7!} + \dots$$

(Every other term; alternating signs.)

If you differentiate term-by-term

[which is OK here, but not obviously OK!]

you get $\exp' = \exp$, $\sin' = \cos$, $\cos' = -\sin$.

(If you accept complex numbers: Let $i^2 = -1$.

Then $\cos(i\theta) = \sum \text{even-order terms, all with } +$

$\sin(i\theta) = i \cdot \sum \text{odd-order terms with } +$

$$\exp(i\theta) = \cos \theta + i \sin \theta$$

and famously, Euler's formula

$$e^{i\pi} + 1 = 0$$

"the most remarkable formula
in mathematics", quoting Feynman