

Forecasting

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An "optimality theory" for forecasting

- A forecast is any statement about the future.
- An "optimal" forecast requires that:
 - ① the empirical model is a good representation of the economy;
 - ② the structure of the economy will remain unchanged.

General properties

- An in-sample congruent encompassing model should dominate in forecasting.
- Forecast accuracy should decline as the forecast horizon increases, because more innovation errors accrue and so predictability falls.
- While adding causally relevant variables should improve forecasts, adding irrelevant variables should generally worsen forecasts from unnecessary parameter-estimation uncertainty.

Forecasting from an AR model

- Assumptions:
 - The AR model holds for $t = 1, 2, \dots, T, T + 1, \dots, T + H$.
 - We know the parameters of the process (we abstract from the estimation problem).
 - We know the history of the time series y_t without measurement error (we abstract from the real-time problem).

Loss function

- The forecasting **loss function is quadratic**, i.e. we are interested in minimizing the **mean of squared forecast errors** (MSFE):

$$MSFE = \frac{1}{H} \sum_{h=1}^H (y_{T+h} - \hat{y}_{T+H|T})^2. \quad (1)$$

- **The optimal forecasts are the conditional expectations based on the period T information set (\mathcal{I}_T):**

$$\hat{y}_{T+H|T} = E(y_{T+h} | \mathcal{I}_T) \quad (2)$$

Forecasting an AR(1) process I

- 1-step-ahead:

$$y_{t+1} = \mu + \theta y_t + \varepsilon_{t+1} \quad (3)$$

$$E(y_{t+1} | \mathcal{X}_t) = \mu + \theta y_t \quad (4)$$

- 2-step-ahead:

$$y_{t+2} = \mu + \theta y_{t+1} + \varepsilon_{t+2} \quad (5)$$

$$= \mu + \theta(\mu + \theta y_t + \varepsilon_{t+1}) + \varepsilon_{t+2}$$

$$= (\mu + \theta\mu) + \theta^2 y_t + \theta\varepsilon_{t+1} + \varepsilon_{t+2}$$

$$E(y_{t+2} | \mathcal{I}_t) = (\mu + \theta\mu) + \theta^2 y_t \quad (6)$$

Forecasting an AR(1) process II

- **Note:** this is a "recursive" approach: equivalent to (**only for linear models!**)

$$y_{t+2} = \mu + \theta y_{t+1} + \varepsilon_{t+2} \quad (7)$$

$$\begin{aligned} E(y_{t+2} | \mathcal{I}_t) &= \mu + \theta \hat{y}_{t+1} & (8) \\ &= \mu + \theta (\mu + \theta y_t) \end{aligned}$$

- *h*-step-ahead:

$$y_{t+h} = \mu + \theta y_{t+h-1} + \varepsilon_{t+h} \quad (9)$$

$$\begin{aligned} &= \left(\mu + \theta\mu + \dots + \theta^{h-1}\mu \right) + \theta^h y_t \\ &\quad + \theta^{h-1}\varepsilon_{t+1} + \dots + \varepsilon_{t+h} \\ E(y_{t+h} | \mathcal{I}_t) &= \left(\mu + \theta\mu + \dots + \theta^{h-1}\mu \right) + \theta^h y_t \quad (10) \end{aligned}$$

Forecasting an AR(1) process III

- The above formulas hold even in the case of $\theta = 1$ (non-stationarity, Random Walk).
- However, for the stationary case we have that when $h \rightarrow \infty$

$$E(y_{t+h} | \mathcal{I}_t) \rightarrow \frac{\mu}{1 - \theta} = E(y_t) \quad (11)$$

which is the unconditional mean of the process.

Forecasting an AR(2) process I

- 1-step-ahead:

$$y_{t+1} = \mu + \theta_1 y_t + \theta_2 y_{t-1} + \varepsilon_{t+1} \quad (12)$$

$$E(y_{t+1} | \mathcal{X}_t) = \mu + \theta_1 y_t + \theta_2 y_{t-1} \quad (13)$$

- 2-step-ahead:

$$y_{t+2} = \mu + \theta_1 y_{t+1} + \theta_2 y_t + \varepsilon_{t+2} \quad (14)$$

$$E(y_{t+2} | \mathcal{X}_t) = \mu + \theta_1 \hat{y}_{t+1} + \theta_2 y_t \quad (15)$$

$$= \mu + \theta_1 (\mu + \theta_1 y_t + \theta_2 y_{t-1}) + \theta_2 y_t$$

Evaluate the forecasts I

- Forecast error:

$$\varepsilon_{t+h|t} = y_{t+h} - y_{t+h|t} \quad (16)$$

- Forecasts are unbiased:

$$E(y_{t+h} - y_{t+h|t}) = 0 \text{ for all } h \quad (17)$$

- Variance of the forecast error:

$$\text{Var}(\varepsilon_{t+h|t}) = \text{Var}(y_{t+h} - y_{t+h|t}) \xrightarrow{H \rightarrow \infty} \text{Var}(y_t) \quad (18)$$

- The variance of the forecast error is used in constructing prediction confidence intervals.
- The prediction intervals typically increase with the forecast horizon, but they stabilize as the horizon gets longer.

Evaluate the forecasts: AR(1) example I

- Forecast error:

$$y_{t+h} = \theta^h y_t + \varepsilon_{t+h} + \theta \varepsilon_{t+h-1} + \dots + \theta^{h-1} \varepsilon_{t+1} \quad (19)$$

$$y_{t+h|t} = \theta^h y_t \quad (20)$$

$$\varepsilon_{t+h|t} = \varepsilon_{t+h} + \theta \varepsilon_{t+h-1} + \dots + \theta^{h-1} \varepsilon_{t+1} \quad (21)$$

- Variance of the forecast error:

$$\text{Var}(\varepsilon_{t+h|t}) = \left(1 + \theta^2 + \dots + \theta^{2(h-1)}\right) \sigma_\varepsilon^2 \quad (22)$$

Failures in forecasting

- In practice:
 - ① We do not know the structure of the true model.
 - ② We do not know the parameter values.
 - ③ Data are revised and measured with errors.
 - ④ There are structural breaks in the forecast period.
- 1. and 2. can be solved by methodology.
- 3. is nuisance (it matters mainly at short horizons).
- 4. is the main problem!

Forecasting bias due to structural breaks I

- We look again at a stationary AR(1) example.
- Let us first write the model in equilibrium form (remember: the mean of the process is $\frac{\mu}{1-\theta}$):

$$y_t = \mu + \theta y_{t-1} + u_t, \quad (23)$$

$$y_t = \frac{\mu}{1-\theta} + \theta \left(y_{t-1} - \frac{\mu}{1-\theta} \right) + u_t, \quad (24)$$

$$y_t = y^* + \theta (y_{t-1} - y^*) + u_t. \quad (25)$$

Forecasting bias due to structural breaks II

- We assume that there is a structural break: $E(y_t)$ changes from y^* to $y^* + d$.
- The true conditional expectation is:

$$E(y_{T+h|T}) = y^* + d + \theta^h (y_T - (y^* + d)). \quad (26)$$

- Our forecast will be

$$E(\hat{y}_{T+h|T}) = y^* + \theta^h (y_T - y^*). \quad (27)$$

- The forecast error will then be:

$$E(y_{T+h|T} - \hat{y}_{T+h|T}) = (1 - \theta^h) d \neq 0. \quad (28)$$

- There is a systematic **bias**.

Forecasting bias due to structural breaks III

- The forecast corrects towards the wrong equilibrium.
- After one period has passed, we can produce a new forecast that condition on y_{T+1} , where the break appears.
- However, it will still not be enough to get the correct forecast.
- Model based forecasts are not good at adapting to structural breaks.

Parameters of interest when forecasting

- When we estimate a model for policy purposes or for testing a hypothesis, the parameters of interest are the derivative coefficients.
- When the purpose is forecasting, the parameters of interest are the conditional means of the endogenous variables.
- There can be breaks in the conditional means and not in the derivative coefficients, e.g. a break in the constant.
- This means that a model can be good for policy analysis, even though it forecasts badly.

Forecasting a time series model in practice I

Example: *AR(1) process. Sample: 1990m1 - 2010m12.*

1-step-ahead recursive forecast

- Divide the sample in estimation sample (1990m1-1999m12) and evaluation sample (2000m1-2010m12)
- Recurive forecasting exercise:
 - 1 Estimate the AR(1) on the sample 1990m1-1999m12 \implies obtain $\hat{\theta}^{(1)}, \hat{\sigma}^{(1)}$
 - 2 With $\hat{\theta}^{(1)}, \hat{\sigma}^{(1)}$ and $y_{1999m12}$ forecast \hat{y}_{2000m1}
 - 3 Estimate the AR(1) on the sample 1990m1-2000m1 \implies obtain $\hat{\theta}^{(2)}, \hat{\sigma}^{(2)}$
 - 4 With $\hat{\theta}^{(2)}, \hat{\sigma}^{(2)}$ and y_{2000m1} forecast \hat{y}_{2000m2}
 - 5 ...

Forecasting a time series model in practice II

Example: $AR(1)$ process. Sample: 1990m1 - 2010m12.

2-step-ahead recursive forecast

- Divide the sample in estimation sample (1990m1-1999m12) and evaluation sample (2000m1-2010m12)
- Recurive forecasting exercise:
 - 1 Estimate the $AR(1)$ on the sample 1990m1-1999m12 \implies obtain $\hat{\theta}^{(1)}, \hat{\sigma}^{(1)}$
 - 2 With $\hat{\theta}^{(1)}, \hat{\sigma}^{(1)}$ and $y_{1999m12}$ forecast \hat{y}_{2000m1}
 - 3 With $\hat{\theta}^{(1)}, \hat{\sigma}^{(1)}$ and \hat{y}_{2000m1} forecast \hat{y}_{2000m2}
 - 4 Estimate the $AR(1)$ on the sample 1990m1-2000m1 \implies obtain $\hat{\theta}^{(2)}, \hat{\sigma}^{(2)}$
 - 5 ...

How to compute the MSE in practice

- Collect all the h -step ahead forecasts you obtain in a vector:
 $\{\hat{y}_{2000m1}, \dots, \hat{y}_{2010m12}\}$
- Compute the MSE as

$$\frac{\sum_{t=2000m1}^{2010m12} (\hat{y}_t - y_t)^2}{N} \quad (29)$$

where N is the number of recursive samples (e.g. "months") in your forecasting sample.

Forecasts from a Keynesian type macro model

Example: Medium term macro model:

$$C_t = a + b(GDP_t - TAX_t) + cC_{t-1} + \varepsilon_{Ct} \quad (30)$$

$$TAX_t = d + eGDP_t + \varepsilon_{TAXt} \quad (31)$$

$$GDP_t = C_t + I_t \quad (32)$$

$$I_t = \mu_I + \varepsilon_{It} \quad (33)$$

- C_t , GDP_t and TAX_t are endogenous. $C_{t-1} = C_{t-1}$ is predetermined.
- I_t is strictly exogenous with $E(I_t) = \mu_I$ and $Var(I_t) = \sigma_I^2$.
- The error terms are independent.

Reduced form

- Our purpose is to forecast $C_{T+1}, C_{T+2}, \dots, C_{T+H}$ based on data up to period T .
- We generate our forecasts from the reduced form equation for C_t :

$$C_t = \underbrace{\frac{a + bd}{1 - b(1 - e)}}_{\beta_0} + \underbrace{\frac{b(1 - e)}{1 - b(1 - e)}}_{\beta_1} I_t + \underbrace{\frac{c}{1 - b(1 - e)}}_{\beta_2} C_t + \underbrace{\frac{\varepsilon_{C_t} - be\varepsilon_{TAX_t}}{1 - b(1 - e)}}_{\varepsilon_t}. \quad (34)$$

- The model is an ARDL, with the reduced form coefficients β_0, β_1 and $\beta_2 = \beta_2$ estimated by OLS from a sample $t = 1, 2, \dots, T$.

1-step ahead forecast

- The 1-step ahead forecast for C_{T+1} is:

$$E(C_{T+1} | C_T, I_T) = \beta_0 + \beta_1 E(I_{T+1} | C_T, I_T) + \beta_2 C_T. \quad (35)$$

- We need to compute the forecast for I_{T+1} (we need the forecast also for exogenous variables!):

$$E(I_{T+1} | C_T, I_T) = \mu_I. \quad (36)$$

- Therefore the forecast for C_{T+1} is:

$$E(C_{T+1} | C_T, I_T) = \beta_0 + \beta_1 \mu_I + \beta_2 C_T. \quad (37)$$

- The parameters in the forecast are unknown: typically we replace them with the parameter estimates:

$$E(\hat{C}_{T+1} | C_T, I_T) = \hat{\beta}_0 + \hat{\beta}_1 \hat{\mu}_I + \hat{\beta}_2 C_T. \quad (38)$$

h-step ahead forecast

- The h-step ahead forecast for C_{T+1} is:

$$E\left(\widehat{C}_{T+h} | C_T, I_T\right) = \sum_{j=0}^{h-1} \widehat{\beta}_2^j \left(\widehat{\beta}_0 + \widehat{\beta}_1 \widehat{\mu}_I\right) + \widehat{\beta}_2^h C_T, \quad (39)$$

where

$$\widehat{\gamma} = \left(\widehat{\beta}_0 + \widehat{\beta}_1 \widehat{\mu}_I\right) \quad (40)$$

- For $h \rightarrow \infty$

$$E\left(\widehat{C}_{T+h} | C_T, I_T\right) = \frac{\widehat{\beta}_0 + \widehat{\beta}_1 \widehat{\mu}_I}{1 - \widehat{\beta}_2} \quad (41)$$

Forecast errors: Bias

- Forecast error:

$$C_{T+h} - \hat{C}_{T+h} = (\gamma - \hat{\gamma}) \sum_{j=0}^{h-1} \hat{\beta}_2^j + (\beta_2^h - \hat{\beta}_2^h) C_T + \sum_{j=0}^{h-1} \beta_2^j \varepsilon_{t+j}. \quad (42)$$

- Bias:

$$E(C_{T+h} - \hat{C}_{T+h}) = \sum_{j=0}^{h-1} E[(\gamma - \hat{\gamma}) \hat{\beta}_2^j] + C_T E(\beta_2^h - \hat{\beta}_2^h). \quad (43)$$

- The bias should be small if the estimation sample is long enough.

Forecast errors: Variance

- Variance:

$$\text{Var} \left(C_{T+h} - \widehat{C}_{T+h} \right) = \underbrace{\text{Var} \left(\sum_{j=0}^{h-1} \left[(\gamma - \widehat{\gamma}) \widehat{\beta}_2^j \right] \right)}_{\text{estimation uncertainty}} + \sigma^2 \sum_{j=0}^{h-1} \beta_2^{2j}. \quad (44)$$

- The estimation uncertainty should be small if the estimation sample is long enough.
- For $h \rightarrow \infty$

$$\text{Var} \left(C_{T+h} - \widehat{C}_{T+h} \right) = \text{Var} (C_t) = \frac{\sigma^2}{1 - \beta_2^2}, \quad (45)$$

that is we expect that the variance of the forecast error converge to the theoretical variance of the forecasted variable.