

A primer on Structural VARs

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Refresh: what is a VAR?

- VAR (p) :

$$y_t = v + B_1 y_{t-1} + \dots + B_p y_{t-p} + u_t, \quad (1)$$

where

$$y_t = \begin{pmatrix} y_{1t} & \dots & y_{Kt} \end{pmatrix}'$$

 $K \times 1$

$$B_i = K \times K \text{ coefficient matrices}$$

$$v_t = \begin{pmatrix} v_1 & \dots & v_K \end{pmatrix}' \text{ vector of intercepts}$$

 $K \times 1$

$$u_t = \begin{pmatrix} u_{1t} & \dots & u_{Kt} \end{pmatrix}' \text{ white noise}$$

 $K \times 1$

$$E(u_t) = 0, \quad E(u_t u_t') = \Sigma_u, \quad E(u_t u_s') = 0, \quad \forall s \neq t$$

Example

Example: VAR(1) with three variables: GDP growth (y_t), inflation (π_t), interest rate(r_t)

$$\begin{pmatrix} y_t \\ \pi_t \\ r_t \end{pmatrix} = \begin{pmatrix} v_y \\ v_\pi \\ v_r \end{pmatrix} + \begin{pmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \\ b_{13} & b_{23} & b_{33} \end{pmatrix} \begin{pmatrix} y_{t-1} \\ \pi_{t-1} \\ r_{t-1} \end{pmatrix} + \begin{pmatrix} u_{yt} \\ u_{\pi t} \\ u_{rt} \end{pmatrix} \quad (2)$$

Use of VAR

So far...

- Describe and summarize macroeconomic time series.
- Compute forecasts.

From Now...

- Understand how variables interact.
- Understand the effect of a shock over time on the different variables.
- Understand the contribution of a shock to the behaviour of the different variables.

Reduced-form VAR

$$y_t = By_{t-1} + u_t, \quad (3)$$

$$u_t \sim N(0, \Sigma_u) \quad (4)$$

- Estimation: **OLS**.
- The constant is **not** the mean nor the long-run equilibrium value of the variable.
- The correlation of the residuals reflects the **contemporaneous** relation between the variables.

Reduced-form VAR: interpretation

- Reduced-form VARs do not tell us anything about the structure of the economy.
- We cannot interpret the reduced-form error terms (u_t) as structural shocks.
- In order to perform policy analysis we want to have:
 - 1 Orthogonal shocks...
 - 2 ...with economic meaning.
- We need a **structural representation**.

Structural VAR

Ideally we want to know

$$Ay_t = By_{t-1} + e_t, \quad e_t \sim N(0, I) \quad (5)$$

where the ε_t are **serially uncorrelated and independent of each other**.

Estimation of structural VARs

- We cannot estimate the structural form with OLS because it violates one important assumption: **the regressors are correlated with the error term.**
- The A matrix is problematic, since it includes all the contemporaneous relation among the endogenous variables.

How to solve the estimation issue

- Premultiply the SVAR in eq. (5) by A^{-1} :

$$A^{-1}Ay_t = A^{-1}By_{t-1} + A^{-1}e_t, \quad e_t \sim N(0, I) \quad (6)$$

$$\implies$$

$$y_t = Fy_{t-1} + u_t, \quad u_t \sim N(0, \Sigma_u) \quad (7)$$

- The VAR in eq. (7) is the usual one we are used to estimate: the reduced-form VAR!

From the reduced-form back to the structural form

- From

$$y_t = Fy_{t-1} + u_t, \quad u_t \sim N(0, \Sigma_u) \quad (8)$$

- Back to

$$Ay_t = By_{t-1} + e_t, \quad e_t \sim N(0, I). \quad (9)$$

- We know that:

$$F = A^{-1}B, \quad (10)$$

$$u_t = A^{-1}e_t, \quad (11)$$

$$\Sigma_u = A^{-1}IA^{-1'} = A^{-1}A^{-1'}. \quad (12)$$

Identification of A and B

- If we know $A^{-1} \implies B = AF$.
- If we know $A^{-1} \implies e_t = Au_t$.
- **Identification:** how to pin down A^{-1} .

Identification problem

$$\underbrace{\Sigma_u}_{\text{symmetric}} = A^{-1}A^{-1'} \quad (13)$$

$$\underbrace{\begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{12} & \sigma_{22} & \sigma_{23} \\ \sigma_{13} & \sigma_{23} & \sigma_{33} \end{bmatrix}}_{\text{6 values}} = \underbrace{\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}}_{\text{9 unknowns}}^{-1} \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}^{-1'}$$

- We have 9 unknowns (the elements of A) but only 6 equations (because the variance-covariance matrix is symmetric)
- **The system is not identified!**

Identification schemes

- Zero short-run restrictions (also known as Choleski identification, recursive identification)
- Sign restrictions

and not covered in this primer...

- Zero long-run restrictions (also known as Blanchard-Quah)
- Theory based restrictions
- Via heteroskedasticity

Zero short-run restrictions (Choleski identification)

- Assume A (or equivalently A^{-1}) to be lower triangular:

$$Ay_t = By_{t-1} + e_t \quad (14)$$

$$y_t = A^{-1}By_{t-1} + A^{-1}e_t \quad (15)$$

$$y_t = \tilde{B}y_{t-1} + \tilde{A}e_t \quad (16)$$

with

$$\tilde{A} = \begin{pmatrix} \tilde{a}_{11} & 0 & 0 \\ \tilde{a}_{21} & \tilde{a}_{22} & 0 \\ \tilde{a}_{13} & \tilde{a}_{23} & \tilde{a}_{33} \end{pmatrix} \quad (17)$$

Zero short-run restrictions (Choleski identification)

- In our example:

$$\begin{pmatrix} y_t \\ \pi_t \\ r_t \end{pmatrix} = \begin{pmatrix} \tilde{b}_{11} & \tilde{b}_{12} & \tilde{b}_{13} \\ \tilde{b}_{21} & \tilde{b}_{22} & \tilde{b}_{23} \\ \tilde{b}_{13} & \tilde{b}_{23} & \tilde{b}_{33} \end{pmatrix} \begin{pmatrix} y_{t-1} \\ \pi_{t-1} \\ r_{t-1} \end{pmatrix} + \begin{pmatrix} \tilde{a}_{11} & 0 & 0 \\ \tilde{a}_{21} & \tilde{a}_{22} & 0 \\ \tilde{a}_{13} & \tilde{a}_{23} & \tilde{a}_{33} \end{pmatrix} \begin{pmatrix} \varepsilon_{yt} \\ \varepsilon_{\pi t} \\ \varepsilon_{rt} \end{pmatrix} \quad (18)$$

- Remember: identification problem, we had 6 equations and 9 unknowns.
- Now: we set three elements of A equal to 0 \implies **6 equations and 6 unknowns: identification!**

Zero short-run restrictions (Choleski identification)

- **Choleski decomposition:**

$$\Sigma_u = P'P \quad (19)$$

with P' lower triangular.

- Since we have .

$$\Sigma_u = A^{-1}A^{-1'} \quad (20)$$

with A^{-1} lower triangular

- Then $P' = A^{-1} \implies$ **Choleski allows identification!**

Choleski identification: interpretation

- Choleski identification is also called **recursive** identification. Why?
- Let's rewrite the VAR in eq. (18) one by one:

$$y_t = \dots + \tilde{a}_{11}\varepsilon_{yt} \quad (21)$$

$$\pi_t = \dots + \tilde{a}_{21}\varepsilon_{yt} + \tilde{a}_{22}\varepsilon_{\pi t} \quad (22)$$

$$r_t = \dots + \tilde{a}_{31}\varepsilon_{yt} + \tilde{a}_{32}\varepsilon_{\pi t} + \tilde{a}_{33}\varepsilon_{rt} \quad (23)$$

Choleski identification: interpretation

- Let's look at the shocks:
 - ε_{yt} affects contemporaneously all the variables.
 - $\varepsilon_{\pi t}$ affects contemporaneously π_t and r_t , but not y_t .
 - ε_{rt} affects contemporaneously only r_t , but not y_t and π_t .
- **The order of the variables matters!**
 - The variable placed on top is the most exogenous (it is affected only by a shock to itself).
 - Each variable contemporaneously affects all the variables ordered afterwards, but it is affected with a delay by them.

Sign restrictions

- Remember Choleski:

$$\Sigma_u = P'P, \quad (24)$$

where P is lower triangular.

- This decomposition is **not unique**.
- Take an orthonormal matrix, i.e. any matrix S such that:

$$S'S = I, \quad (25)$$

- Then we can write

$$\Sigma_u = P'P = P'IP = P'S'SP = \mathcal{P}'\mathcal{P}. \quad (26)$$

- \mathcal{P} is generally not lower triangular anymore.

Sign restrictions

- We can draw as many S as we want \implies we can have as many \mathcal{P} as we want.
- Question: **is P plausible?**
- We want to check whether the impulse responses implied by \mathcal{P} satisfy a set of sign restrictions, typically theory-driven.

Sign restrictions: a very intuitive example

- **How is a monetary policy shock affecting output?** (Simplified version of Uhlig (JME, 2005)).
- A contractionary monetary policy should (conventional wisdom and theory):
 - ① Raise the federal fund rate,
 - ② Lower prices.
- What happens to output? Since it is the question we want to answer, **we leave output unrestricted, i.e. we do not make any assumption on it!**
- We keep only the matrices which generate the responses to a monetary policy shock coherent with 1. and 2.

Steps to implement sign restrictions

- 1 Estimate the reduced-form VAR and obtain F and Σ_u .
- 2 Compute $P' = chol(\Sigma_u)$.
- 3 Draw a random orthonormal matrix S .
- 4 Compute $A^{-1} = \mathcal{P} = P'S'$.
- 5 Compute the impulse responses associated with A^{-1} .
- 6 Are the sign restrictions satisfied?
 - If yes, store the impulse response.
 - If no, discard the impulse response.
- 7 Repeat 3-6 until you obtain N replications.
- 8 Report the mean or median impulse response (and its confidence interval).

Impulse response functions

- The impulse response function traces the effect of a one-time shock to one of the structural errors on the current and future values of all the endogenous variables.
- This is possible only when the errors are uncorrelated \implies structural form!

How to compute the IRFs

- Remember previous classes on VAR...
- The impulse responses are derived from the MA representation of the VAR.
- Rewrite the VAR(p) in canonical form (i.e. as VAR(1)), as

$$y_t = Fy_{t-1} + A^{-1}e_t \quad (27)$$

$$IRF(0) = A^{-1} = P' \quad (28)$$

$$IRF(1) = FA^{-1} \quad (29)$$

$$IRF(2) = F^2A^{-1} \quad (30)$$

Variance decomposition

- The variance decomposition separates the variation in a endogenous variable into the component shocks of the VAR.
- It tells what portion of the variance of the forecast error in predicting $y_{i,T+h}$ is due to the structural shock e_j .
- It provides information about the relative importance of each innovation in affecting the variables.

Historical decomposition

- The historical decomposition tells what portion of the deviation of $y_{i,t}$ from its unconditional mean is due to the shock e_j .
- The structural shocks push the variables away from their equilibrium values.