# ECON4510 – Finance Theory Lecture 11

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#### Stochastic processes

- These are stochastic variables which evolve over time.
- Some of you may know about these from
  - time series econometrics,
  - other applications in microeconomics or macroeconomics.
- Purpose here: Analyze prices of stocks and options.
- Binomial tree example of stochastic process in discrete time.
- "Discrete time:" Process only defined at certain time points.
- Black-Scholes-Merton option values based on another process.

#### Stochastic processes, contd.

- In continuous time, i.e., stock values  $S_t$  change continuously.
- (Although we typically observe only at some points in time.)
- Also continuous-valued, i.e.,  $S_t$  can be any positive number.
- (In typical markets, S<sub>t</sub> only has two or three decimals.)
- Could just define that process directly.
- Will instead follow Hull, 9th ed., ch. 14.<sup>1</sup>
- First some rather simple, motivating points.
- Will then develop motivation for more complications.

<sup>1</sup>8th ed., ch. 13, 7th ed., ch. 12

## The Markov property

- $S_t$  called a *Markov* process if (the *Markov* property:) the probability distribution of all  $S_{t+\Delta t}$  for all later dates  $t + \Delta t$ , as seen from date t, depends on  $S_t$  only.
- For instance, if  $S_t$  is a given number, knowledge of particularly high outcomes for  $S_{t-2}$  and  $S_{t-1}$ , or for  $S_{t-0.2}$  and  $S_{t-0.1}$ , will not affect the probability distribution of  $S_{t+0.1}$  or  $S_{t+0.2}$  or ....
- Alternatively, we could think that the probability distribution of  $S_{t+\Delta t}$  could depend on the whole history of S's, or some part of it, say  $S_{t-s}$  for some interval before t. Not Markov.

### The Markov property, contd.

- One possible type of dependence, called momentum, is that a falling sequence  $S_{t-2} > S_{t-1} > S_t$  increases the probability of an outcome  $S_{t+1}$  less than  $S_t$  (i.e., most likely, the fall continues). This is not Markov. For a Markov process, a rising sequence  $S_{t-2} < S_{t-1} < S_t$  will, if it has the same value for  $S_t$ , imply exactly the same probability distribution for  $S_{t+1}$  as the falling sequence  $S_{t-2} > S_{t-1} > S_t$ .
- Exist many types of Markov processes, with many different types of probability distributions for, e.g., *S*<sub>t+1</sub> conditional on *S*<sub>t</sub>.
- "Markov processes" should thus be viewed as a wide class of stochastic processes, with one particular common characteristic, the Markov property.

## The Markov property, economic implications

- Connection to weak-form market efficiency.
- All available information reflected in today's  $S_t$ .
- Probabilities of future  $S_{t+\Delta t}$  depend on  $S_t$ .
- But historical S values cannot matter.
- Implication of  $S_{t-\Delta t}$  for  $S_{t+\Delta t}$ ? Already in  $S_t$ .

#### Implications of Markov property for variance

- Markov:  $S_2 S_1$  is stochastically independent of  $S_1 S_0$ .
- Also  $S_3 S_2$ , etc.
- Assume we are at time 0, know  $S_0$ .
- Can write  $S_2 = S_0 + (S_1 S_0) + (S_2 S_1)$ .
- As seen from time 0,  $S_0$  has no variance.

• Then:

1

$$var(S_2) = var[(S_2 - S_1) + (S_1 - S_0)] = var(S_2 - S_1) + var(S_1 - S_0).$$

• The last equality is due to stochastic independence.

### Implications for variance, contd.

- Assume all changes  $S_{t+1} S_t$  have same variance.
- Then  $\operatorname{var}(S_2) = \operatorname{var}(S_2 S_1) + \operatorname{var}(S_1 S_0) = 2\operatorname{var}(S_{t+1} S_t).$
- More precisely, introduce conditional variance, given  $S_0$ .
- $var(S_2|S_0) = 2var(S_{t+1} S_t)$ .
- Likewise:  $var(S_3|S_0) = 3var(S_{t+1} S_t)$ .
- Generally:  $var(S_T|S_0) = T var(S_{t+1} S_t)$ .
- Implication: (conditional) variance proportional to time.
- Standard deviation proportional to square root of time.
- (In what follows, like Hull, use  $\tilde{X} \sim \phi(E(\tilde{X}), \operatorname{var}(\tilde{X}))$  to indicate that  $\tilde{X}$  has a normal distribution, but use  $N(x) = \Pr(\frac{\tilde{X} E(\tilde{X})}{\sqrt{\operatorname{var}(\tilde{X})}} \leq x)$  to denote the standard normal cumulative distribution function.)

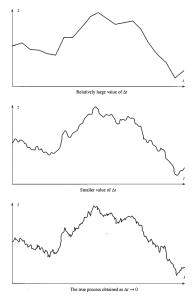
## Wiener processes (also called Brownian motion)

- So far, in addition to the Markov property, have assumed the variance of changes is the same for different periods.
- Assume now in addition that  $var(S_{t+1} S_t | S_t)$  equals 1, and that the expected change  $E(S_{t+1} S_t | S_t)$  equals 0.
- (A bit like looking at a standardized distribution, like  $\phi(0,1)$ . Will call this process  $z_t$  (or sometimes z(t)), not  $S_t$ .)
- This gives us a particular type of Markov process called a *Wiener* process, defined by two properties. *z*<sub>t</sub> is a Wiener process if and only if both are satisfied:
  - The change  $\Delta z$  during a short time interval  $\Delta t$  is  $\Delta z = \epsilon \sqrt{\Delta t}$ , where  $\epsilon$  has a standard normal (Gaussian) distribution (with  $E(\epsilon) = 0$ ,  $var(\epsilon) = 1$ ).
  - The values of  $\Delta z$  for non-overlapping intervals  $\Delta t$  are stochastically independent.

#### Wiener processes, contd.

- Over longer interval, z(T) - z(0) is normally distributed, the sum of Nchanges over intervals of length  $\Delta t$ , i.e.,  $N\Delta t = T$ ;  $z(T) - z(0) = \sum_{i=1}^{N} \epsilon_i \sqrt{\Delta t}$ .
- This implies E(z(T) - z(0)) = 0,  $var(z(T) - z(0)) = N\Delta t = T.$  These do not depend on the length of  $\Delta t.$
- In limit when Δt → 0, dz is change during dt; var(dz) = dt.
- See Fig. 14.1 in Hull 9th (13.1 in 8th, 12.1 in 7th).

Figure 13.1 How a Wiener process is obtained when  $\Delta t \rightarrow 0$  in equation



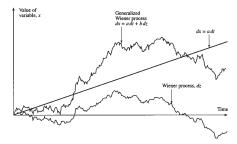
### Generalized Wiener processes

- First multiply the Wiener process *dz* by a constant, *b*.
- b dz has variance  $b^2 var(dz) = b^2 dt$ .
- Then allow for an expected change different from zero,

dx = a dt + b dz

 This amounts to adding a non-stochastic linear growth path to the stochastic *b dz*, and is illustrated in Fig. 14.2 in Hull 9th (13.2 in 8th, 12.2 in 7th).





Generalized Wiener processes, contd.

• The generalized Wiener process X is normally distributed with

$$E(X(T) - X(0)|X(0)) = aT,$$
  
var $(X(T) - X(0)|X(0)) = b^2T.$ 

• The process is also called Brownian motion with drift.

#### Generalized Wiener processes; Itô processes

• A further generalization: Allow a and b to depend on (x, t),

$$dx = a(x, t)dt + b(x, t)dz.$$

- This is called an *Itô process*. In general not normally distributed.
- Over a small time interval  $\Delta t$  we get

$$\Delta x \approx a(x,t)\Delta t + b(x,t)\epsilon\sqrt{\Delta t}.$$

• For non-overlapping intervals the changes in x are stochastically independent, so all Itô processes are Markov processes.

### Stochastic process for a stock price

- Looking for something more realistic than the binomial tree.
- Expected change will not be zero, so cannot use Wiener process.
- Could we use generalized Wiener process?
- Expected change over interval of length T is aT.
- Suppose  $S_0 = 10$ , a = 1, and that T is measured in years.
- Expected stock price in ten years is  $E(S_{10}|S_0 = 10) = 20$ .
- Expected stock price ten years later,  $E(S_{20}|S_0 = 10) = 30$ .
- Also, if  $S_{10}$  equals its expectation,  $E(S_{20}|S_{10}=20)=30$ .

#### Stochastic process for a stock price, contd.

- But the expected growth rate over the time interval (10, 20) is substantially lower than the expected growth rate over (0, 10), since growth rates are relative numbers, and 30/20 < 20/10.
- More likely shareholders require constant expected growth rate.
- Need exponential expected path, not linear expected path.
- Will obtain this by letting  $E(dS) = \mu S dt$ .
- For the non-stochastic part (or, if  $\sigma = 0$ ):  $\frac{dS}{dt} = \mu S$ .
- Integrating between 0 and T:  $S_T = S_0 e^{\mu T}$  when  $\sigma = 0$ .
- This leads to a suggestion of

$$dS = \mu S dt + \sigma dz$$

or, better,

$$dS = \mu \ S \ dt + \sigma \ S \ dz.$$

Stochastic process for a stock price, contd.

• From previous slide: a suggestion of

$$dS = \mu S dt + \sigma dz$$

or

$$dS = \mu \ S \ dt + \sigma \ S \ dz.$$

 Choose the latter so that a relative change in S not only has a constant expected value, μ dt, but also a constant variance, σ<sup>2</sup>dt,

$$\frac{dS}{S} = \mu \ dt + \sigma \ dz.$$

- This stock price process process is basis for the most widespread option pricing theories, like the one in ch. 15 of Hull (9th ed.), Black-Scholes-Merton (8th ed., ch. 14, 7th ed., ch. 13).
- The process is called geometric Brownian motion with drift.

Stochastic process for a stock price, contd.

- Since S appears on right-hand side in dS formula: Not a generalized Wiener process, but a bit more complicated.
- dS is an Itô process, with  $a(S,t) = \mu S$  and  $b(S,t) = \sigma S$ .
- Different stocks will differ in  $\mu$  and/or  $\sigma.$
- Stock *i* has constants  $\mu_i, \sigma_i$ , stock *j* has constants  $\mu_j, \sigma_j$
- Hull discusses these variables in section 14.4 (9th ed.).<sup>2</sup>
- Remember: Hull's book does not rely on the CAPM.
- Imprecise discussion of how  $\mu$  depends on  $r_f$  and risk.
- Footnote<sup>3</sup> 5, p. 311, 9th ed., means  $\mu$  depends on covariance, not on  $\sigma.$

<sup>3</sup>8th ed., fn. 4, p. 289, 7th ed., fn. 4, p. 268

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<sup>&</sup>lt;sup>2</sup>8th ed., sect. 13.4, 7th ed., sect. 12.4

## Functions of Itô processes

- When x is an Itô process, dx = a(x, t)dt + b(x, t)dz:
  - Is a function G of x also an Itô process?
  - If yes, what happens to the functions a(x, t) and b(x, t)?
  - ▶ Put differently: *G* will also have functions like these.
  - What do the two functions look like for G?
- Motivation: Call option value as function of S.
- Find this via a general rule, Itô's lemma.
- A bit more complicated than suggested above.
- Call option not only function of S; also of t.
- Option's value depends on time until expiration.
- For some given S, different t's give different c's.
- Thus, the more general questions are:
  - If x is an Itô process, is G(x, t) an Itô process?
  - ▶ If yes, what do the "a and b functions" look like for G?
- The answers are given by *Itô's lemma*.
- Will not prove this mathematically.
- But will show how and why it differs from usual differentiation.

#### ltô's lemma

- Assume x is an Itô process:
- dx = a(x, t)dt + b(x, t)dz, where z is a Wiener process.
- Then G(x, t) is also an Itô process:

$$dG = \left(\frac{\partial G}{\partial x}a + \frac{\partial G}{\partial t} + \frac{1}{2}\frac{\partial^2 G}{\partial x^2}b^2\right)dt + \frac{\partial G}{\partial x}b dz.$$

- We recognize the general form of an Itô process.
- The expression above is Hull's equation<sup>4</sup> (14.12) (9th ed.).
- In fact, this is short-hand, dropping arguments.

<sup>&</sup>lt;sup>4</sup>8th ed., eq. (13.12), 7th ed., eq. (12.12)

### ltô's lemma, contd.

- Contains six different functions of (x, t).
- Both *a*, *b*, *G*, and the partial derivatives of *G*.
- Right-hand side should really be written like this:

$$\left( \frac{\partial G(x,t)}{\partial x} a(x,t) + \frac{\partial G(x,t)}{\partial t} + \frac{1}{2} \frac{\partial^2 G(x,t)}{\partial x^2} [b(x,t)]^2 \right) dt$$
$$+ \frac{\partial G(x,t)}{\partial x} b(x,t) dz.$$

• Perhaps this looks complicated, but:

• In our applications, G, a, and b are fairly simple.

Why not ordinary differentiation? Hull, p. 319f (9th ed.) (8th ed., p. 297f, 7th ed., p. 275 f)

Approximation of a function by its tangent:

$$\Delta G \approx \frac{dG}{dx} \Delta x$$

when G is a function of one variable, x.

- Holds precisely in limit as  $\Delta x \rightarrow 0$ .
- As long as  $\Delta x \neq 0$ , can use Taylor series expansion:

$$\Delta G = \frac{dG}{dx}\Delta x + \frac{1}{2}\frac{d^2G}{dx^2}\Delta x^2 + \frac{1}{6}\frac{d^3G}{dx^3}\Delta x^3 + \dots$$

• As  $\Delta x \rightarrow 0$ , higher-order terms vanish.

• G(x, y), two dimensions, a tangent plane:

$$\Delta G \approx \frac{\partial G}{\partial x} \Delta x + \frac{\partial G}{\partial y} \Delta y.$$

Why not use ordinary differentiation, contd.

• When both  $\Delta x$  and  $\Delta y \neq 0$ , can use Taylor series:

$$\Delta G = \frac{\partial G}{\partial x} \Delta x + \frac{\partial G}{\partial y} \Delta y + \frac{1}{2} \frac{\partial^2 G}{\partial x^2} \Delta x^2 + \frac{\partial^2 G}{\partial x \partial y} \Delta x \Delta y + \frac{1}{2} \frac{\partial^2 G}{\partial y^2} \Delta y^2 + \dots$$

• Again, precisely in limit as  $\Delta x \rightarrow 0$  and  $\Delta y \rightarrow 0$ :

$$dG = \frac{\partial G}{\partial x}dx + \frac{\partial G}{\partial y}dy.$$

- Want to find a similar expression for Itô processes.
- But all higher-order terms do not vanish.

## Itô's lemma vs. ordinary differentiation

- Assume x is an Itô process:
- dx = a(x, t)dt + b(x, t)dz, where z is a Wiener process.
- Let G be a function G(x, t), and use Taylor expansion:

$$\Delta G = \frac{\partial G}{\partial x} \Delta x + \frac{\partial G}{\partial t} \Delta t + \frac{1}{2} \frac{\partial^2 G}{\partial x^2} \Delta x^2 + \frac{\partial^2 G}{\partial x \partial t} \Delta x \Delta t + \frac{1}{2} \frac{\partial^2 G}{\partial t^2} \Delta t^2 + \dots$$

- Only novelty here: Have called second variable t, not y.
- When  $\Delta x \rightarrow 0$ , need to observe the following.
- $\Delta x = a \Delta t + b\epsilon \sqrt{\Delta t}$  implies:
- $(\Delta x)^2 = b^2 \epsilon^2 \Delta t + \text{terms of higher order.}$
- Since  $\Delta x$  contains a  $\sqrt{\Delta t}$  term, normal rules don't work.
- Must include extra term with second-order partial derivative.
- The extra term contains  $\epsilon^2$ , and  $\epsilon$  is stochastic.

Itô's lemma vs. ordinary differentiation, contd.

- Hull explains why  $E(\epsilon^2 \Delta t) = \Delta t$ .
- Hull also explains that  $var(\epsilon^2 \Delta t)$  is of order  $(\Delta t)^2$ .
- Variance approaches zero fast as  $\Delta t 
  ightarrow 0$ .
- Thus: In limit  $\epsilon^2 \Delta t$  is nonstochastic,  $= \Delta t$ .
- This gives us the following formula in the limit:

$$dG = \frac{\partial G}{\partial x}dx + \frac{\partial G}{\partial t}dt + \frac{1}{2}\frac{\partial^2 G}{\partial x^2}b^2dt$$

• Insert for *dx* from above to find the form we used above:

$$dG = \left(\frac{\partial G}{\partial x}a + \frac{\partial G}{\partial t} + \frac{1}{2}\frac{\partial^2 G}{\partial x^2}b^2\right)dt + \frac{\partial G}{\partial x}b\,dz.$$

# Example of application of Itô's lemma

- Consider the stock price process from slide 16:
- Assume  $dS = \mu S dt + \sigma S dz$ ; z is a Wiener process.
- What kind of process is In S?
- Natural question; deterministic part of S is exponential in t.
- Might believe that deterministic part of  $\ln S$  is linear in t.
- Observe this application of Itô's lemma is fairly simple:
  - "a(S, t) function" of S process is  $\mu S$ . Simple, and no t.
  - "b(S, t) function" of S process is  $\sigma S$ . Simple, and no t.
  - The G(S, t) function is  $\ln S$ . Fairly simple, and no t.
- Know from Itô's lemma that In S is an Itô process.
- But what are the "a and b functions" of the G process?
- Will turn out that they are very simple. Constants, no S, no t.
- But slightly less simple than one might have thought.
- The constant which multiplies dt is not  $\mu$ .
- Would be natural suggestion based on deterministic  $S_T = S_0 e^{\mu T}$ .

### Example; lognormal property, Hull, sect. 14.7 (9th ed.)

(8th ed., sect. 13.7, 7th ed., sect. 12.6)

• With  $G(S, t) \equiv \ln S$ , need three partial derivatives:

$$\frac{\partial G}{\partial S} = \frac{1}{S}, \ \frac{\partial^2 G}{\partial S^2} = -\frac{1}{S^2}, \ \frac{\partial G}{\partial t} = 0.$$

• Then Itô's lemma says that:

$$dG = \left(\frac{1}{S}\mu S + 0 + \frac{1}{2}\left(-\frac{1}{S^2}\right)(\sigma S)^2\right)dt + \frac{1}{S}\sigma S dz$$
$$= \left(\mu - \frac{\sigma^2}{2}\right)dt + \sigma dz.$$

- So this is an Itô process with constant *a* and *b* functions.
- Implies that In S is a generalized Wiener process.
- Can use formulae from slide 12.

#### Example, contd.

• The change  $\ln S_T - \ln S_0$  is normally distributed:

$$\ln S_{T} - \ln S_{0} \sim \phi \left[ \left( \mu - \frac{\sigma^{2}}{2} \right) T, \sigma^{2} T \right],$$

which implies (by adding the known  $\ln S_0$ )

$$\ln S_{T} \sim \phi \left[ \ln S_{0} + \left( \mu - \frac{\sigma^{2}}{2} \right) T, \sigma^{2} T \right]$$

- In S is normally distributed.
- By definition then, S is lognormally distributed.
- Not obvious earlier, but by using Itô's lemma.

#### The lognormal distribution of stock prices

- On slide 15, required an exponential expected path,  $S_T = S_0 e^{\mu T}$ .
- Could thus not use the generalized Wiener process for S.
- (Would have implied S having a normal distribution.)
- Found instead something similar for relative changes in S,

$$\frac{dS}{S} = \mu \ dt + \sigma \ dz.$$

- This implies S is lognormal, ln(S) is normal.
- Relation between these two distributions may be confusing.
- Remember that  $\ln(S)$  is not linear, thus  $E[\ln(S)] \neq \ln[E(S)]$ :

• 
$$E[\ln(S_T)|S_0] = \ln(S_0) + (\mu - \sigma^2/2)T$$
,

• 
$$E(S_T|S_0) = S_0 e^{\mu T}$$
 so that  $\ln[E(S_T|S_0)] = \ln(S_0) + \mu T$ .

#### The lognormal distribution of stock prices

• The variance expression is simpler for  $ln(S_T)$  than for  $S_T$ :

• var[ln(
$$S_T$$
)| $S_0$ ] =  $\sigma^2 T$ ,

• 
$$\operatorname{var}(S_T|S_0) = S_0^2 e^{2\mu T} (e^{\sigma^2 T} - 1).$$

• Footnote 2 on p. 323 in Hull (9th ed.)<sup>5</sup> refers to a note on this:

 $http://www-2.rotman.utoronto.ca/{\sim}hull/technicalnotes/TechnicalNote2.pdf$ 

- $S_T = S_0 e^{xT}$  defines continuously-compounded rate of return x.
- Its distribution is  $x \sim \phi\left(\mu \frac{\sigma^2}{2}, \frac{\sigma^2}{T}\right)$ .

<sup>5</sup>8th ed., fn. 2, p. 301, 7th ed., fn. 2, p. 279

## Monte Carlo simulation (Hull sections 14.3 and 21.6)

(8th ed., sect. 13.3 and 20.6, 7th ed., sect. 12.3 and 19.6)

- From lecture 10: Can find option values as expectations.
  - ▶ Not based on actual probabilities, but on "risk neutral" probabilities.
- Next lecture finds  $c(S, K, T, r, \sigma)$  from lognormal distribution.
- Numerically, e.g., c(10, 8, 2, 0.05, 0.2): Exists alternative method.
- For complicated nonlinear functions: Use Monte Carlo simulation:
  - Computer draws numbers,  $S_T$ , from a probability distribution.
  - Typically thousands of independent drawings from same distribution.
  - Gives *frequency distribution*, similar to probability distribution.
  - For each draw, compute some function of it, e.g.,  $max(0, S_T K)$ .
  - Average for, e.g., 10 000 draws gives estimate of  $E[\max(0, S_T K)]$ .
  - Could also calculate, e.g.,  $var[max(0, S_T K)]$ , but less interesting.
  - Expectation gives option value if use risk neutral probabilities for  $S_T$ .
    - \* Just need to take present value,  $E[\max(0, \hat{S}_T K)]e^{-rT}$ .
  - Can also be done for many periods, and for functions of many variables.

### Monte Carlo simulation in Excel spreadsheet

- Consider c(10, 8, 2, 0.05, 0.2) when stock price is lognormal.
- First determine parameters of probability distribution of  $\ln(\hat{S}_2)$ .
- For "risk neutral" process, should let  $\mu = r$ .
- Use  $S_0 = 10$ , and observe that  $\sigma = 0.2 \Rightarrow \sigma^2 = 0.04$ .
- Use these  $\mu, S_0, \sigma^2$  in formula from slide 27,

$$\ln \hat{S}_2 \sim \phi \left[ \ln(10) + \left( 0.05 - \frac{0.04}{2} \right) \cdot 2, 0.04 \cdot 2 \right].$$

- Create lognormal sample using Excel's RAND, NORMSINV, and EXP.
- For each  $S_T$  in sample, calculate function values using Excel's MAX.
- Across sample, estimate expectation using Excel's AVERAGE.
- Next time: Exact formula, may then compare results with M-C.

# Monte Carlo simulation in Excel, contd.

#### Column B contains sample of 100 numbers uniformly distributed on [0, 1].

	A	В	С	D	E	F	G
1		Uniform rand. no.s	Normally distributed	Lognormal price	Call option	Input data	
2	Average of below	=AVERAGE(B3:B102)	=AVERAGE(C3:C102)	=AVERAGE(D3:D102)	=AVERAGE(E3:E102)		
3		=RAND()	=NORMSINV(B3)*\$G\$	=EXP(C3)	=MAX(0;D3-\$G\$4)	S0 =	10
4		=RAND()	=NORMSINV(B4)*\$G\$	=EXP(C4)	=MAX(0;D4-\$G\$4)	К =	8
5		=RAND()	=NORMSINV(B5)*\$G\$	=EXP(C5)	=MAX(0;D5-\$G\$4)	T =	2
6		=RAND()	=NORMSINV(B6)*\$G\$	=EXP(C6)	=MAX(0;D6-\$G\$4)	r =	0,05
7		=RAND()	=NORMSINV(B7)*\$G\$	=EXP(C7)	=MAX(0;D7-\$G\$4)	sig =	0,2
8		=RAND()	=NORMSINV(B8)*\$G\$	=EXP(C8)	=MAX(0;D8-\$G\$4)		
9		=RAND()	=NORMSINV(B9)*\$G\$	=EXP(C9)	=MAX(0;D9-\$G\$4)	Output call	
10		=RAND()	=NORMSINV(B10)*\$G	=EXP(C10)	=MAX(0;D10-\$G\$4)	option val. =	
11		=RAND()	=NORMSINV(B11)*\$G	=EXP(C11)	=MAX(0;D11-\$G\$4)	=\$E\$2*EXP(-	
10		-DAND/\	-NIODMCINI\//D10\*CC		_MANV(0.010 CCCA)		

NORMSINV applied to uniform distribution gives normal distribution. The full contents of cell C3, which gives the normally distributed  $ln(S_2)$ : =NORMSINV(B3)\*\$G\$7\*SQRT(\$G\$5)+LN(\$G\$3)+\$G\$5\*(\$G\$6-0,5\*\$G\$7^2)

The full contents of cell F11, which gives the  $c_0$ , the call option value: = $\frac{1}{2} = \frac{1}{2} + \frac{1}{2$ 

(This is Norwegian; comma as decimal sign; semicolon as separator.)

## Monte Carlo: How obtain the desired distribution?

• Statement from previous page needs explanation:

"NORMSINV applied to uniform distribution gives normal distribution."

- Excel's RAND() gives uniform random numbers; but we need normal.
- Function to use is the inverse of the cumulative distribution function.
- (Works also for other distributions than normal, if know inverse cdf.)
- For standard normal, this inverse is the Excel function NORMSINV.
- Cumulative distribution function for standard normal is N in Hull.
- Defined by  $N(x) = \Pr( ilde{X} \leq x)$  when  $ilde{X} \sim \phi(0,1)$ , standard normal.
- N is monotonically increasing, continuous, thus has inverse  $N^{-1}(u)$ .
- If  $\tilde{U}$  is uniform on [0,1], then  $\tilde{X}\equiv N^{-1}(\tilde{U})$  is standard normal.
- Proof:  $\Pr[N^{-1}(\tilde{U}) \le x] = \Pr[\tilde{U} \le N(x)] = N(x).$
- First equality follows since the monotonic N is applied to both sides.
- Second equality is a property of  $\tilde{U}$ ; its cdf is F(u) = u when  $u \in [0, 1]$ .